

Two grumpy giants  
and a baby

D. J. Bernstein

University of Illinois at Chicago

Tanja Lange

Technische Universiteit Eindhoven

# Discrete-logarithm problems

Fix a prime  $\ell$ .

Input: generator  $g$   
of group of order  $\ell$ ;  
element  $h$  of same group.

Output: integer  $k \in \mathbf{Z}/\ell$   
such that  $h = g^k$ , where  
group is written multiplicatively.

“ $k = \log_g h$ ”.

How difficult is computation of  $k$ ?

## Real-world importance

Apple, “iOS Security”, 2012.05:

“Some files may need to be written while the device is locked. A good example of this is a mail attachment downloading in the background. This behavior is achieved by using asymmetric elliptic curve cryptography (ECDH over Curve25519).”

Also used for “iCloud Backup”.

More examples: DNSCrypt;  
elliptic-curve signatures  
in German electronic passports.

## Generic algorithms

Will focus on algorithms that work for every group of order  $\ell$ .

Allowed operations:  
neutral element 1;  
multiplication  $a, b \mapsto ab$ .

Will measure algorithm cost by counting  $\#$  multiplications.

Success probability:  
average over groups  
and over algorithm randomness.

Each group element  
computed by the algorithm  
is trivially expressed as

$$h^x g^y \text{ for known } (x, y) \in (\mathbf{Z}/\ell)^2.$$

$$1 = h^x g^y \text{ for } (x, y) = (0, 0).$$

$$g = h^x g^y \text{ for } (x, y) = (0, 1).$$

$$h = h^x g^y \text{ for } (x, y) = (1, 0).$$

If algorithm multiplies

$$h^{x_1} g^{y_1} \text{ by } h^{x_2} g^{y_2}$$

then it obtains  $h^x g^y$  where

$$(x, y) = (x_1, y_1) + (x_2, y_2).$$

## Slopes

If  $h^{x_1} g^{y_1} = h^{x_2} g^{y_2}$

and  $(x_1, y_1) \neq (x_2, y_2)$

then  $\log_g h$  is the negative

of the slope  $(y_2 - y_1)/(x_2 - x_1)$ .

(Impossible to have  $x_1 = x_2$ :

if  $x_1 = x_2$  then  $g^{y_1} = g^{y_2}$

so  $y_1 = y_2$ , contradiction.)

Algorithm immediately recognizes

collisions of group elements

by putting each  $(h^x g^y, x, y)$

into, e.g., a red-black tree.

(Low memory? Parallel?

Distributed? Not in this talk.)

# Baby-step-giant-step

(1971 Shanks)

Choose  $n \geq 1$ ,  
typically  $n \approx \sqrt{\ell}$ .

Points  $(x, y)$ :

$n + 1$  “baby steps”

$(0, 0), (0, 1), (0, 2), \dots, (0, n)$ ;

$n + 1$  “giant steps”

$(1, 0), (1, n), (1, 2n), \dots, (1, n^2)$ .

Can use more giant steps.

Stop when  $\log_g h$  is found.

## Performance of BSGS

Slope  $jn - i$  from  $(0, i)$  to  $(1, jn)$ .

Covers slopes

$\{-n, \dots, -1, 0, 1, 2, 3, \dots, n^2\}$ ,

using  $2n - 1$  multiplications.

Finds all discrete logarithms

if  $\ell \leq n^2 + n + 1$ .

Worst case with  $n \approx \sqrt{\ell}$ :

$(2 + o(1))\sqrt{\ell}$  multiplications.

(In fact always  $< 2\sqrt{\ell}$ .)

Average case with  $n \approx \sqrt{\ell}$ :

$(1.5 + o(1))\sqrt{\ell}$  multiplications.



## Interleaving (2000 Pollard)

Improve average case to

$(4/3 + o(1))\sqrt{\ell}$  multiplications:

$(0, 0), (1, 0),$

$(0, 1), (1, n),$

$(0, 2), (1, 2n),$

$(0, 3), (1, 3n),$

$\vdots$

$(0, n), (1, n^2).$

$4/3$  arises as  $\int_0^1 (2x)^2 dx$ .

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$4/3$  arises as  $\int_0^1 (2x)^2 dx$ .

Oops: Have to start with

$(0, n)$  as step towards  $(1, n)$ .

But this costs only  $O(\log \ell)$ .

## Is BSGS optimal?

After  $m$  multiplications

have  $m + 3$  points in  $(\mathbf{Z}/\ell)^2$ .

Can hope for  $(m + 3)(m + 2)/2$   
different slopes in  $\mathbf{Z}/\ell$ .

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1994 Nechaev, 1997 Shoup:

proof that generic algorithms

have success probability  $O(m^2/\ell)$ .

Proof actually gives

$\leq ((m + 3)(m + 2)/2 + 1)/\ell$ .

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BSGS: at best  $\approx m^2/4$  slopes,

taking  $n \approx m/2$ .

Factor of 2 away from the bound.

## The rho method

(1978 Pollard,  $r = 3$  “mixed”;  
many subsequent variants)

Initial computation:

$r$  uniform random “steps”

$(s_1, t_1), \dots, (s_r, t_r) \in (\mathbf{Z}/\ell)^2$ .

$O(r \log \ell)$  multiplications;

negligible if  $r$  is small.

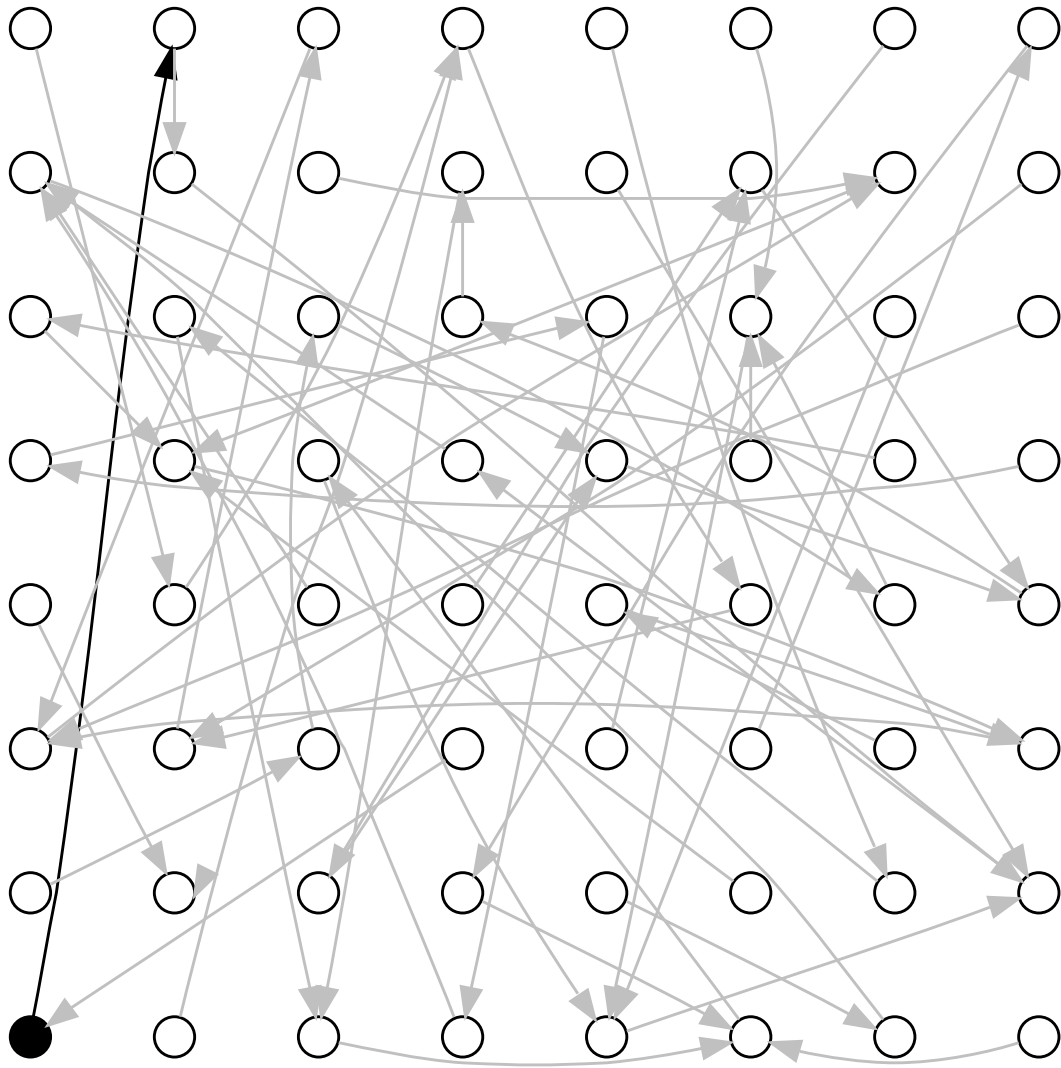
The “walk”: Starting from

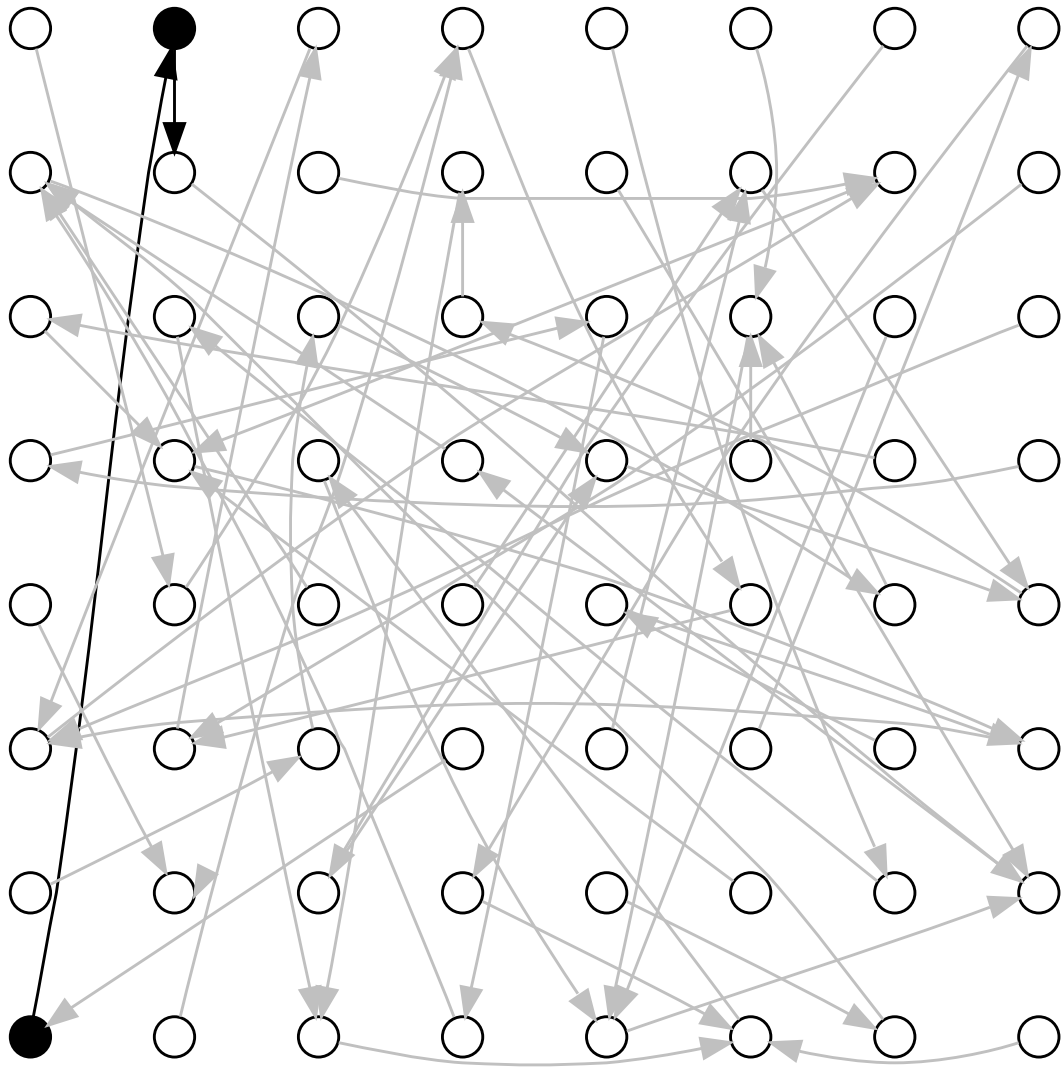
$(x_i, y_i) \in (\mathbf{Z}/\ell)^2$  compute

$(x_{i+1}, y_{i+1}) = (x_i, y_i) + (s_j, t_j)$

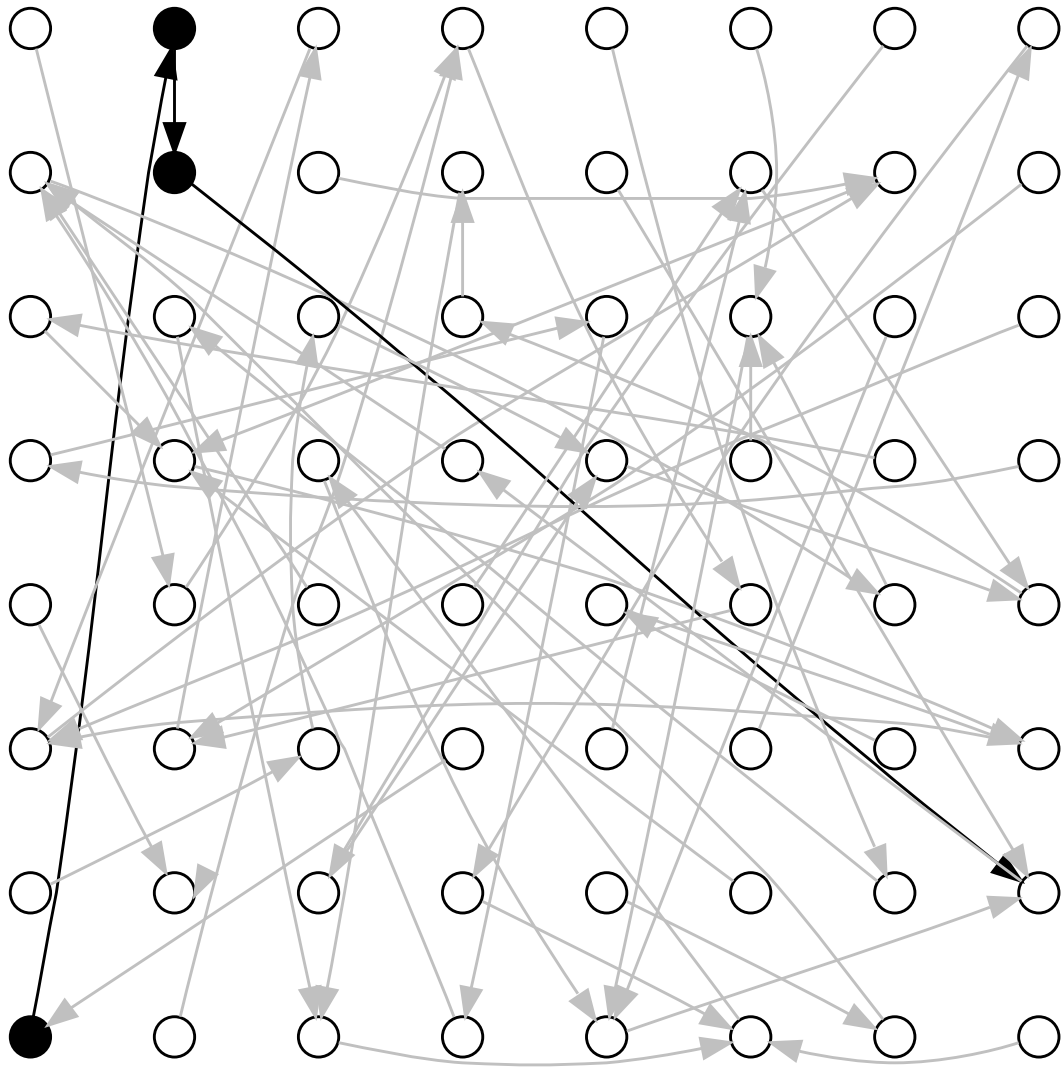
where  $j \in \{1, \dots, r\}$

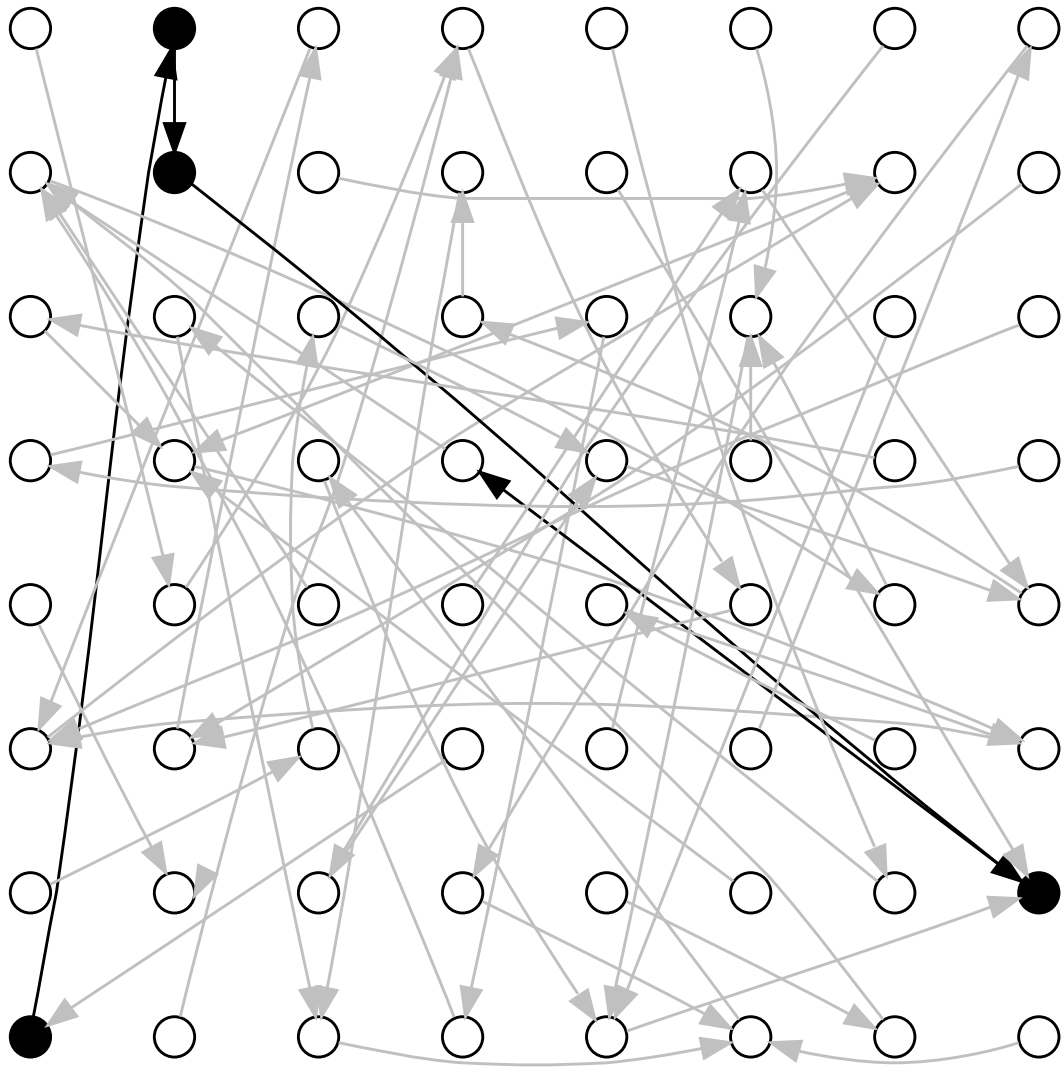
is a hash of  $h^{x_i} g^{y_i}$ .

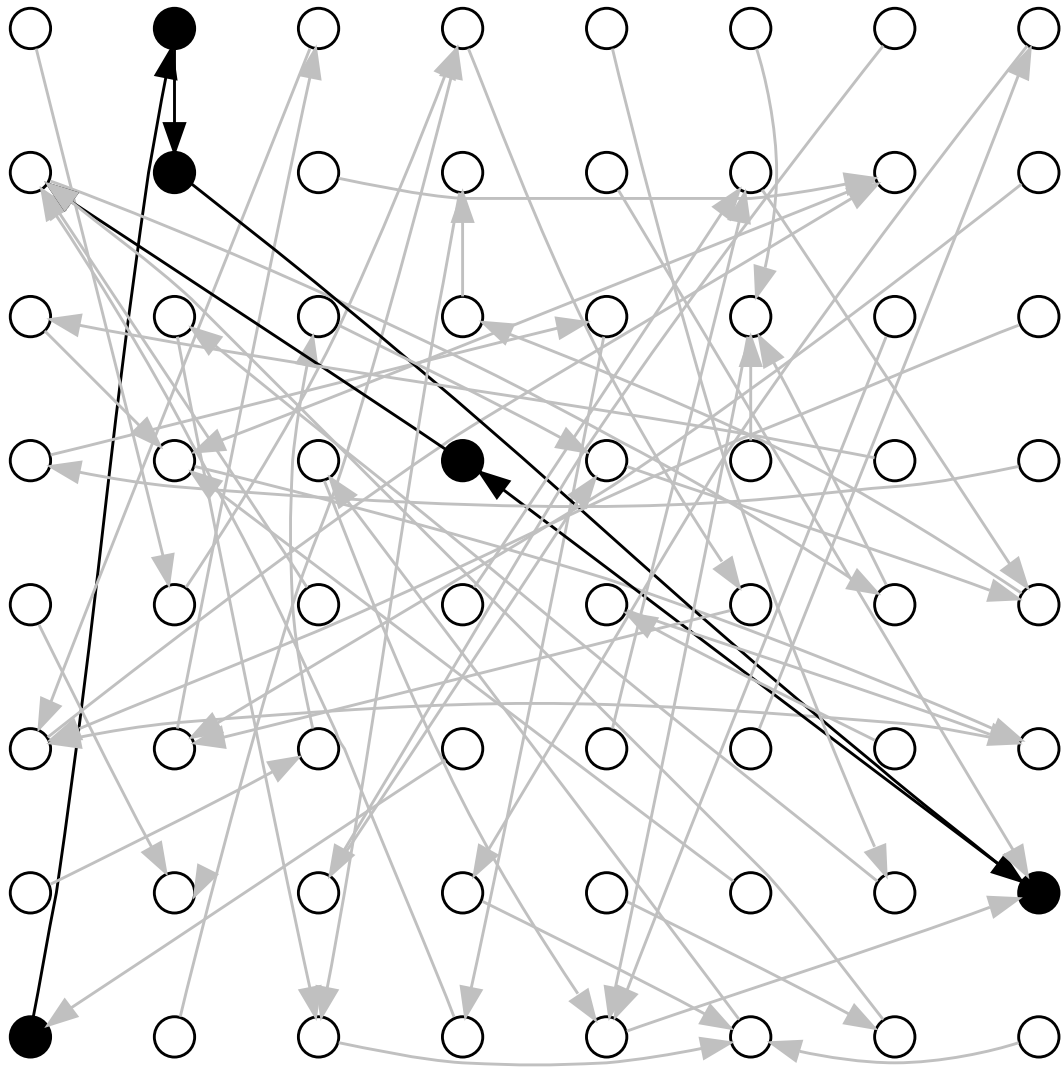


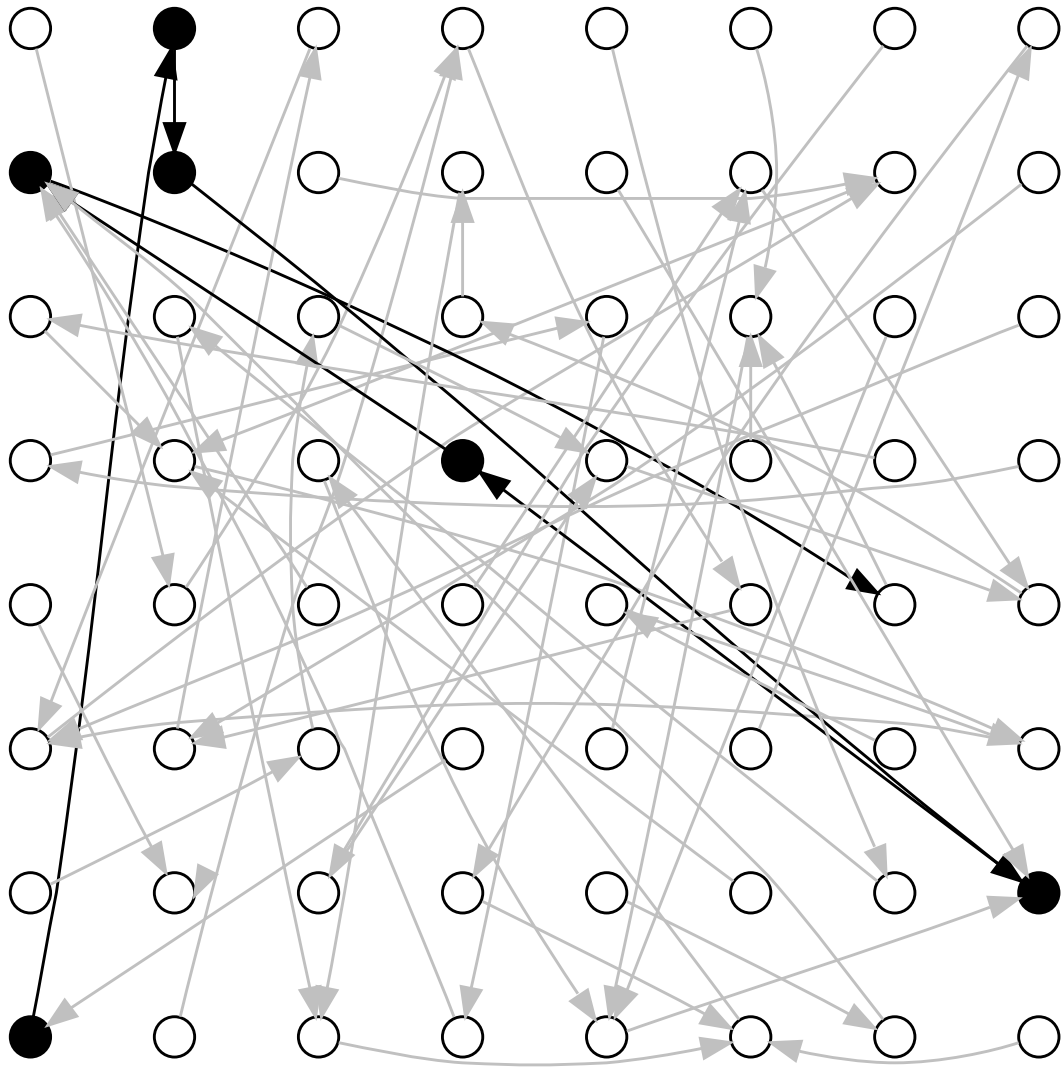


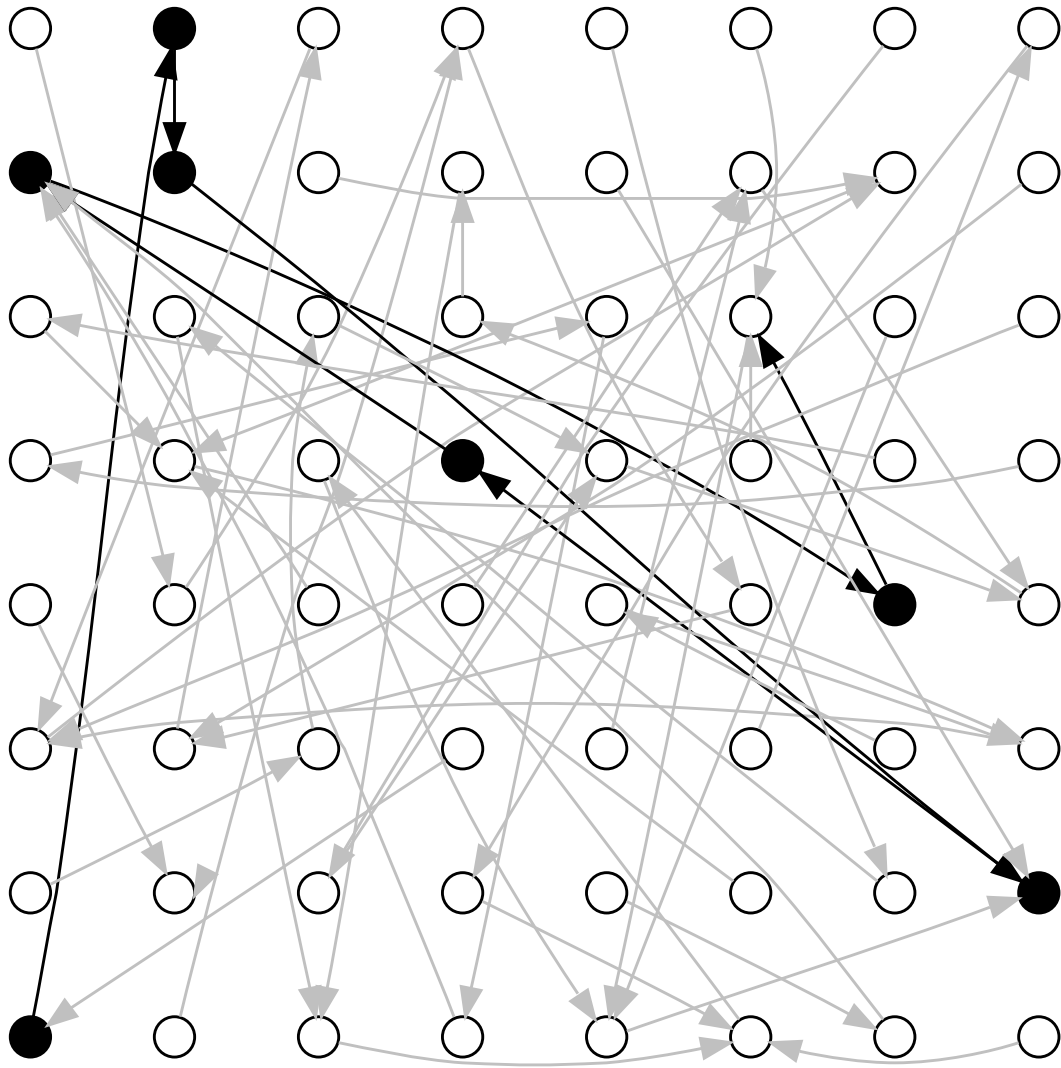


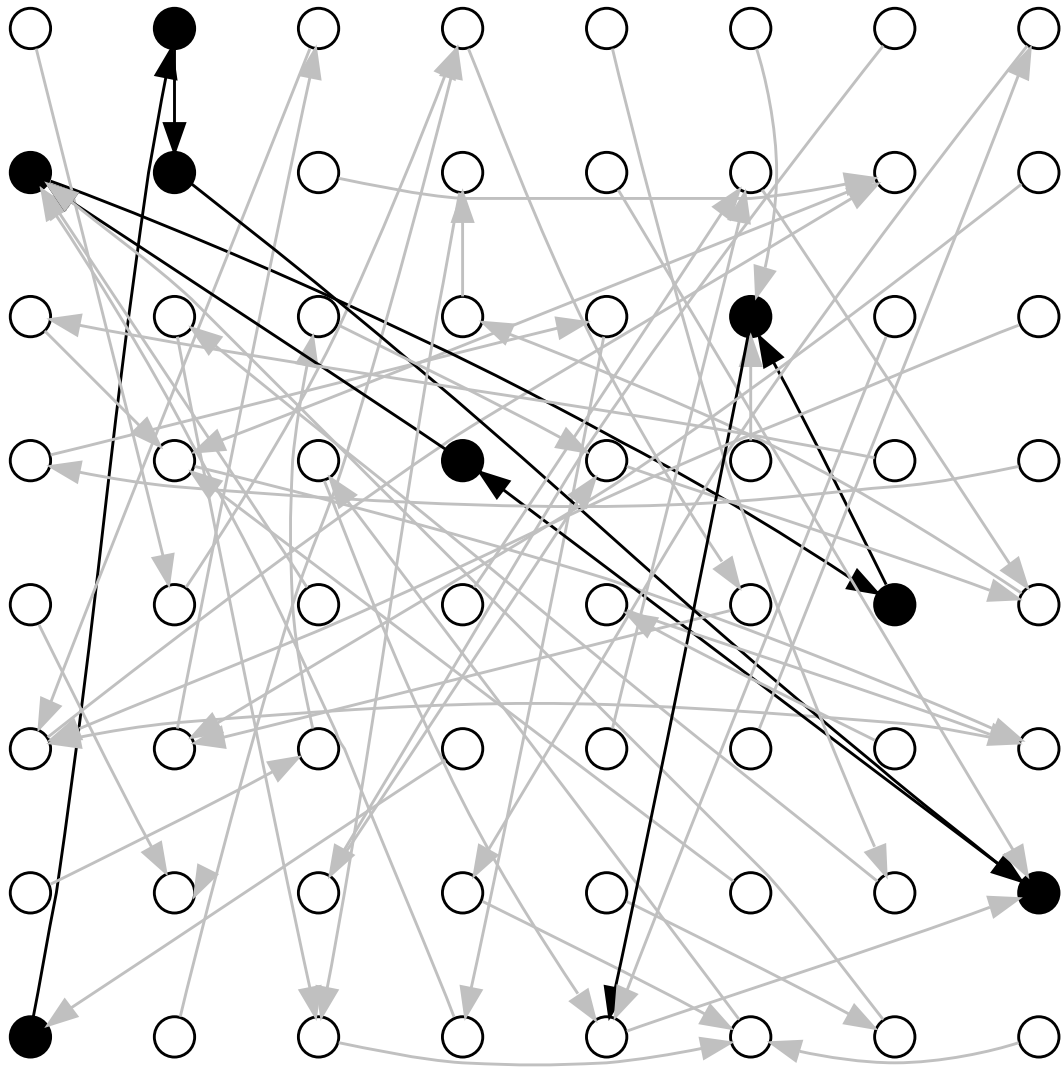


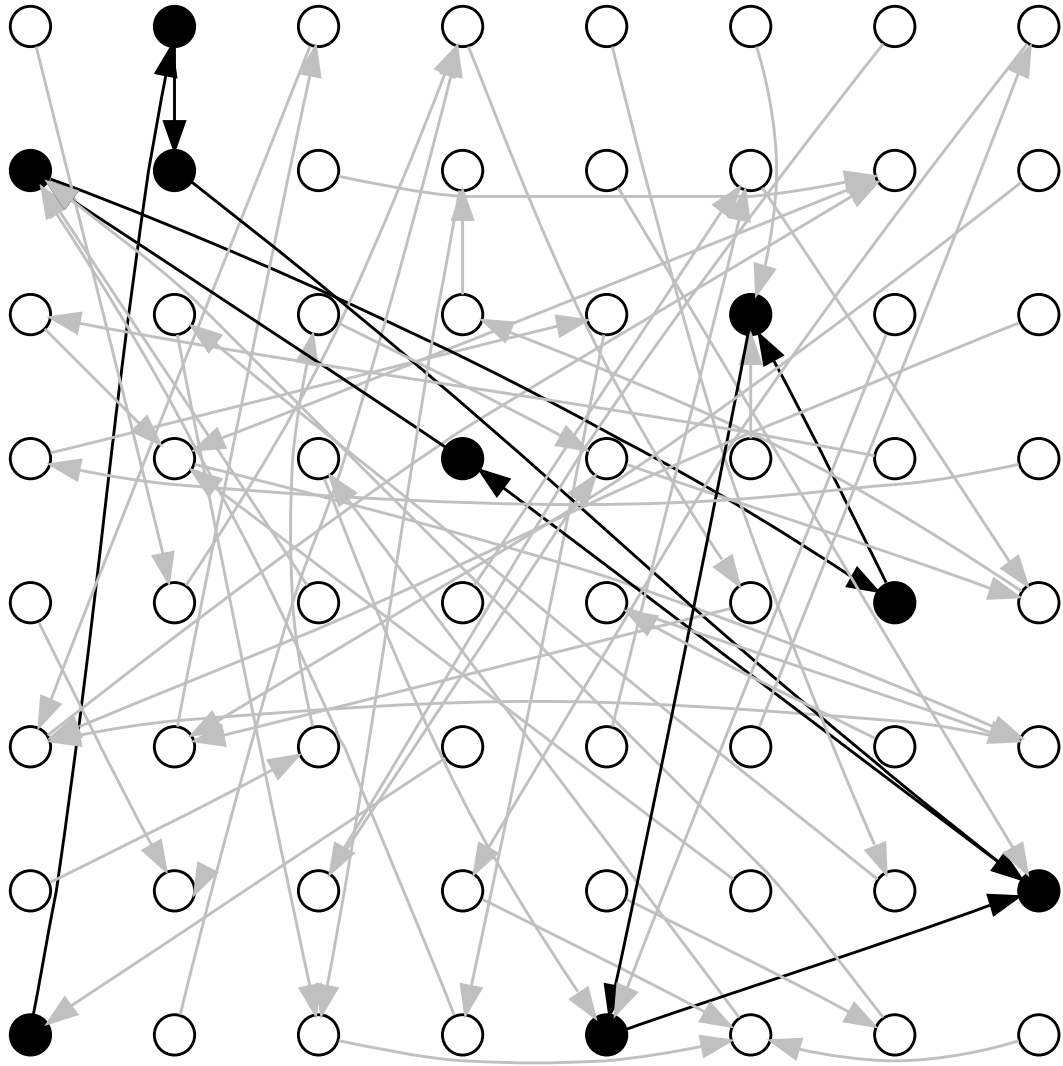


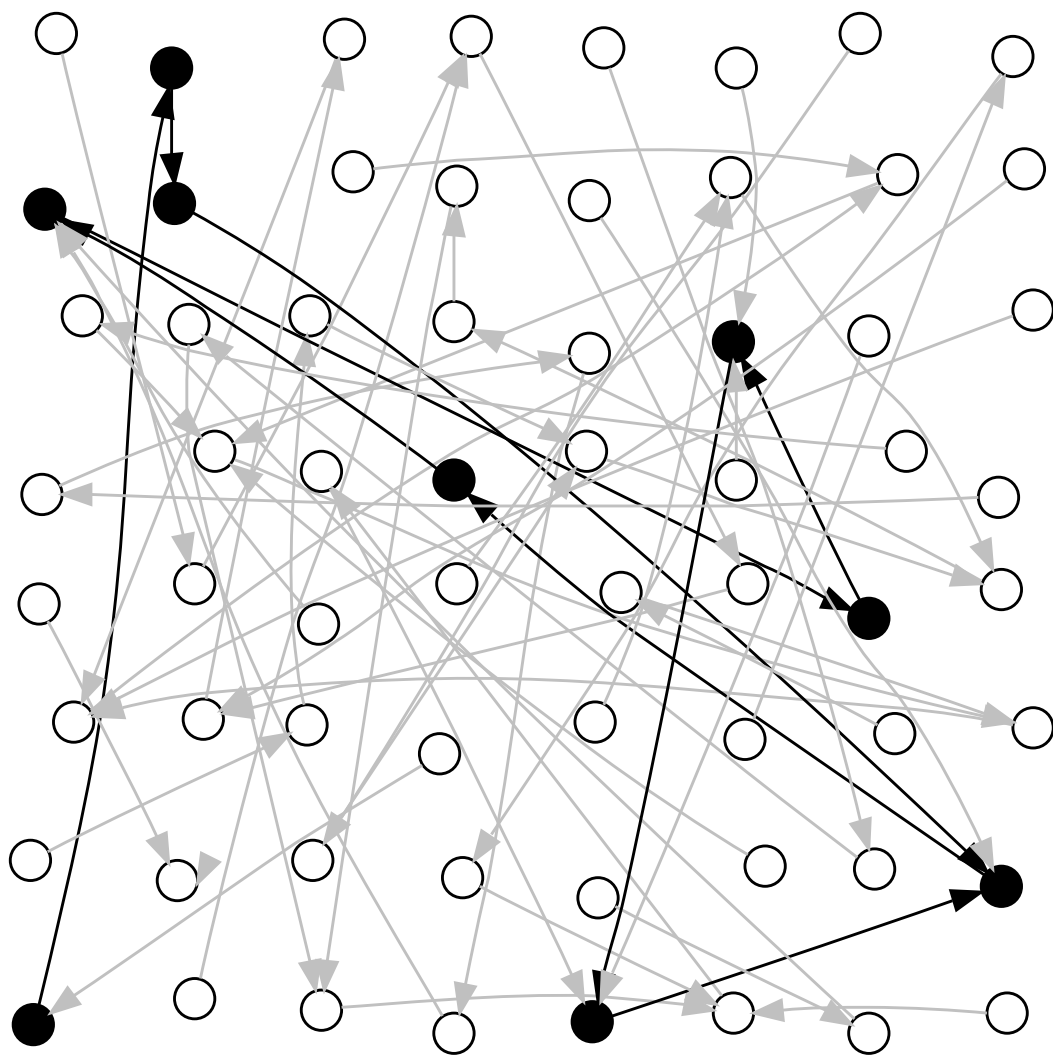




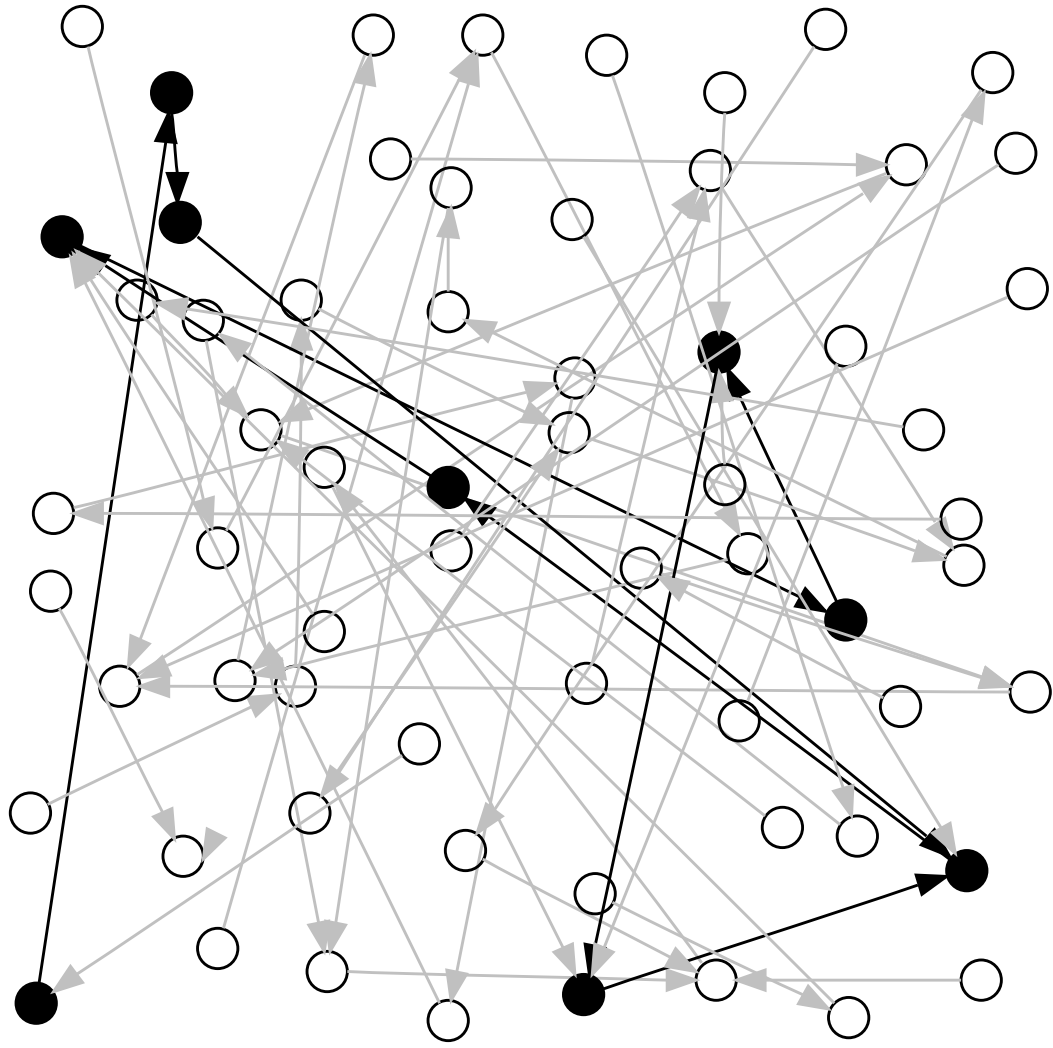


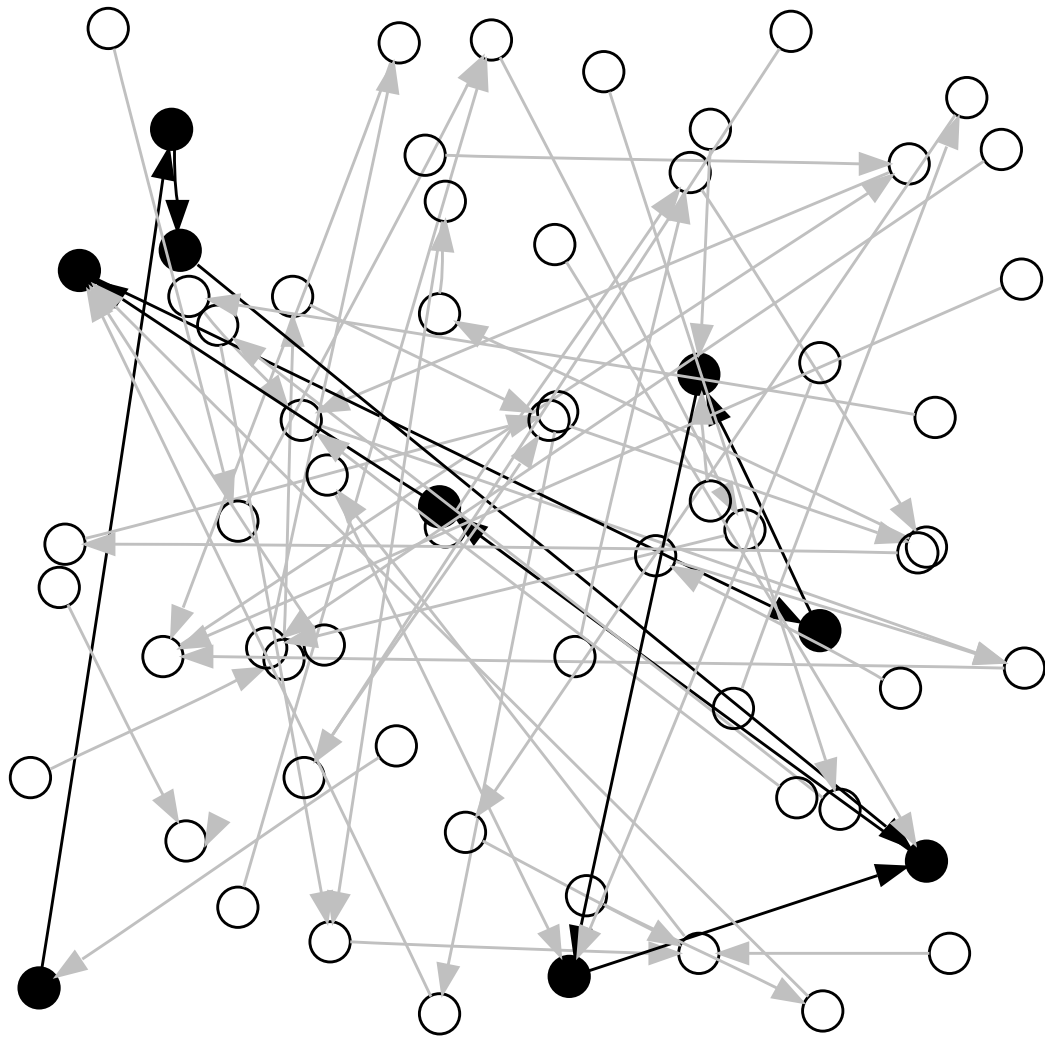


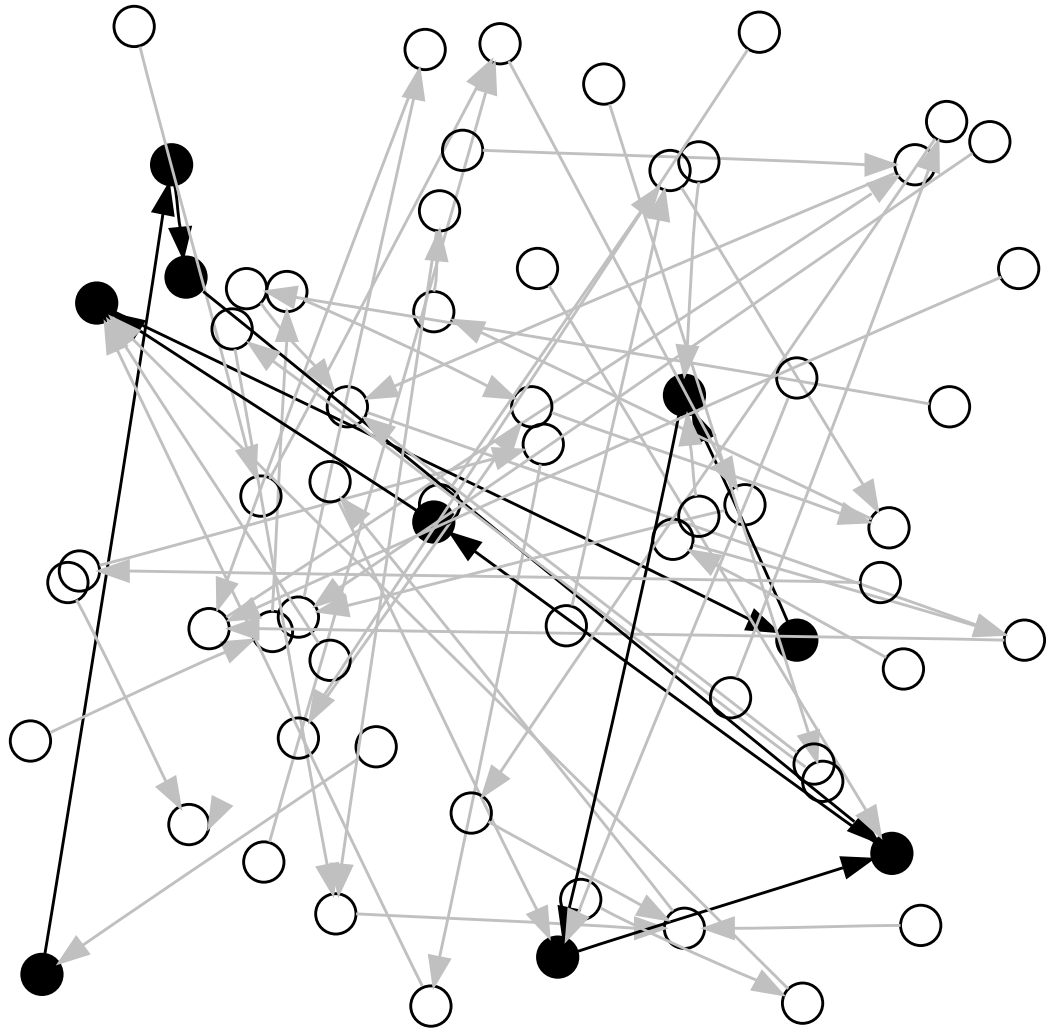


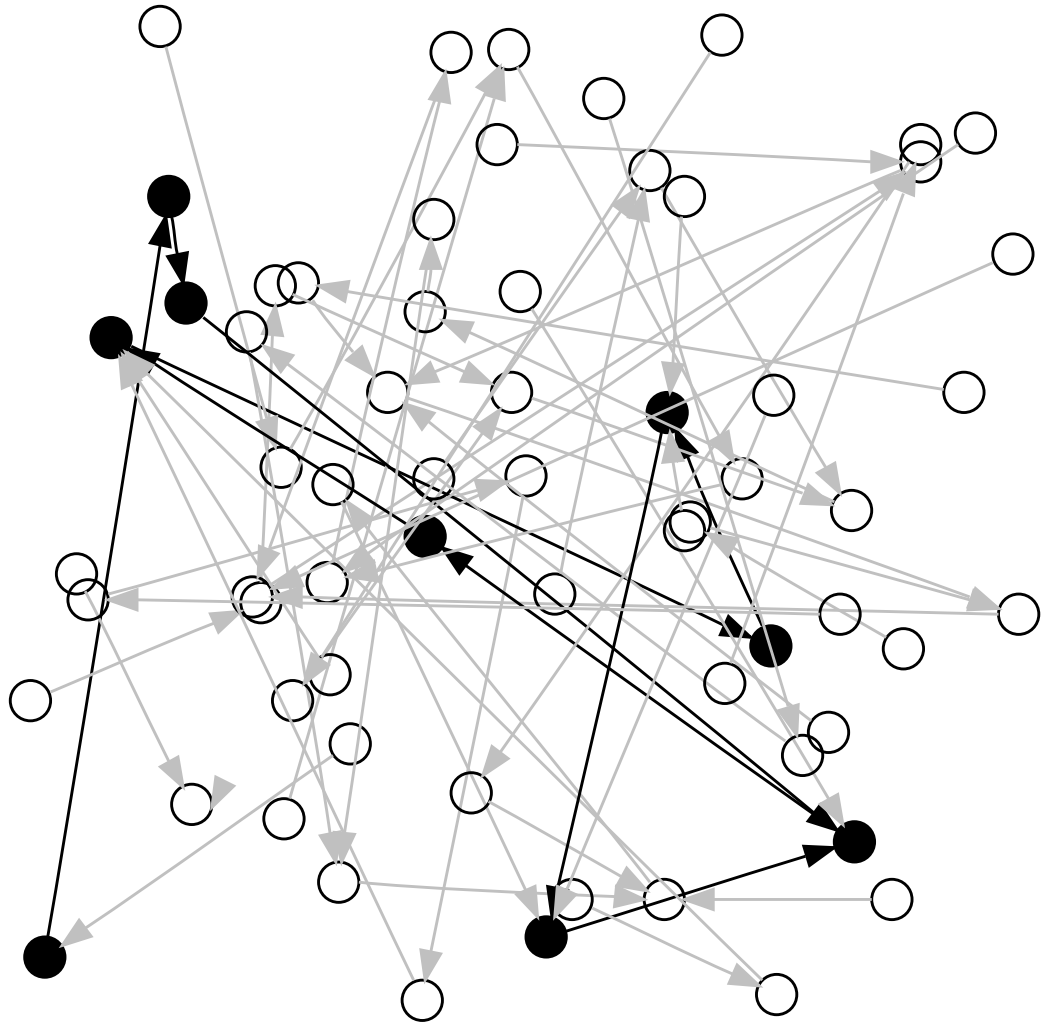


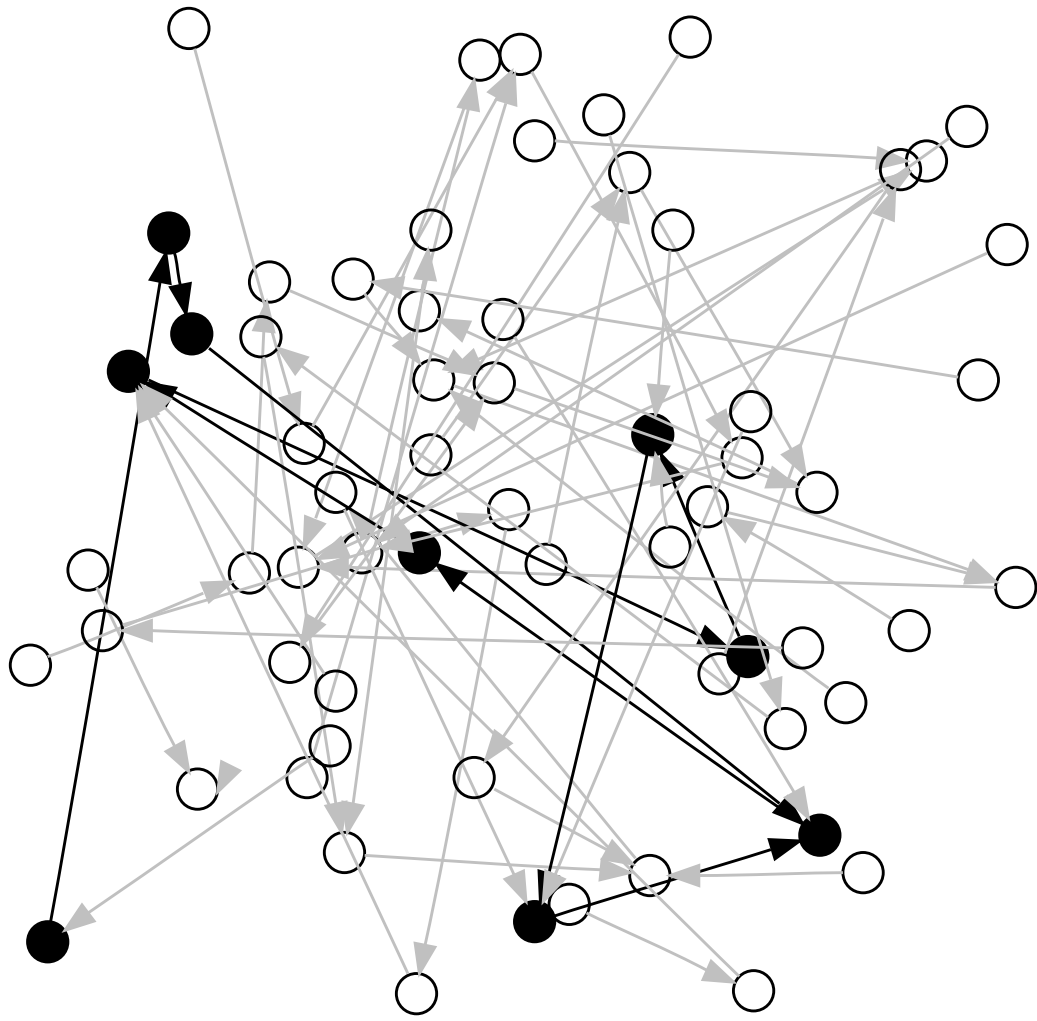


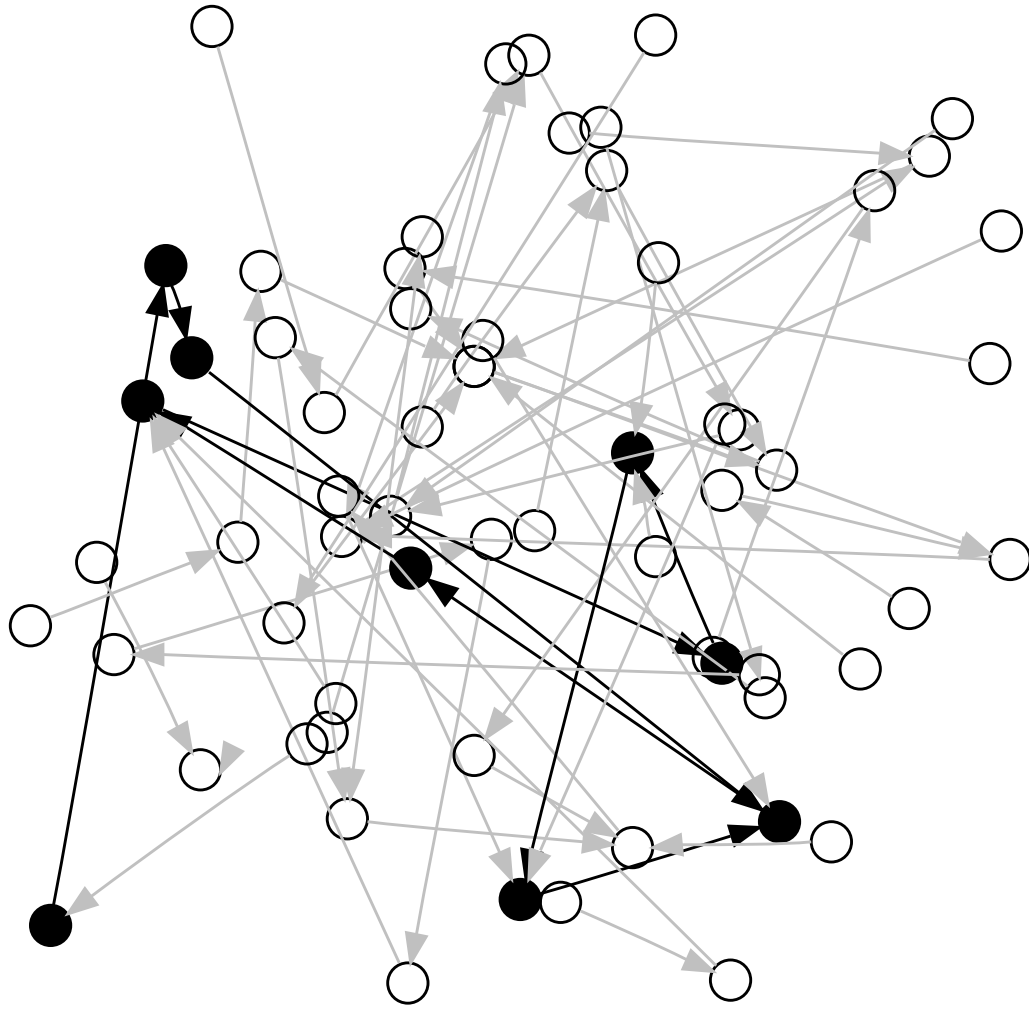


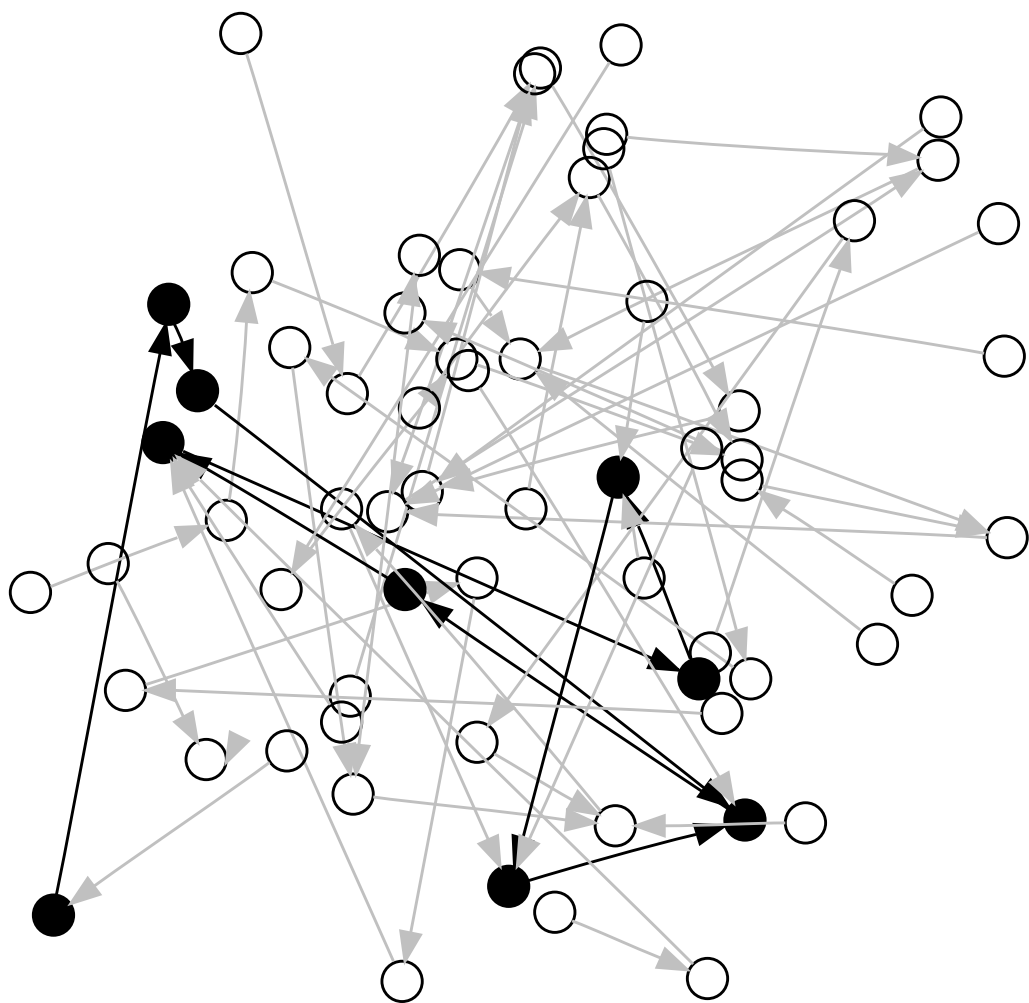


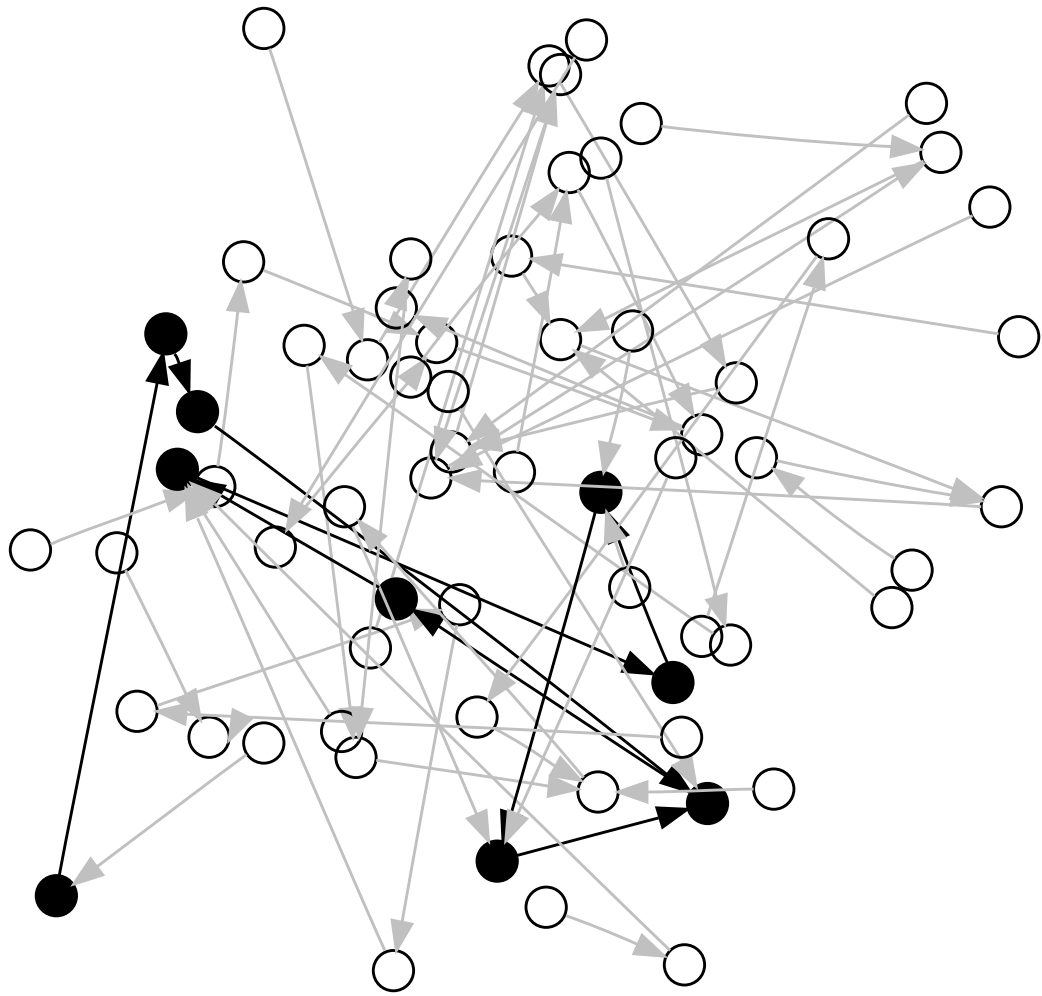




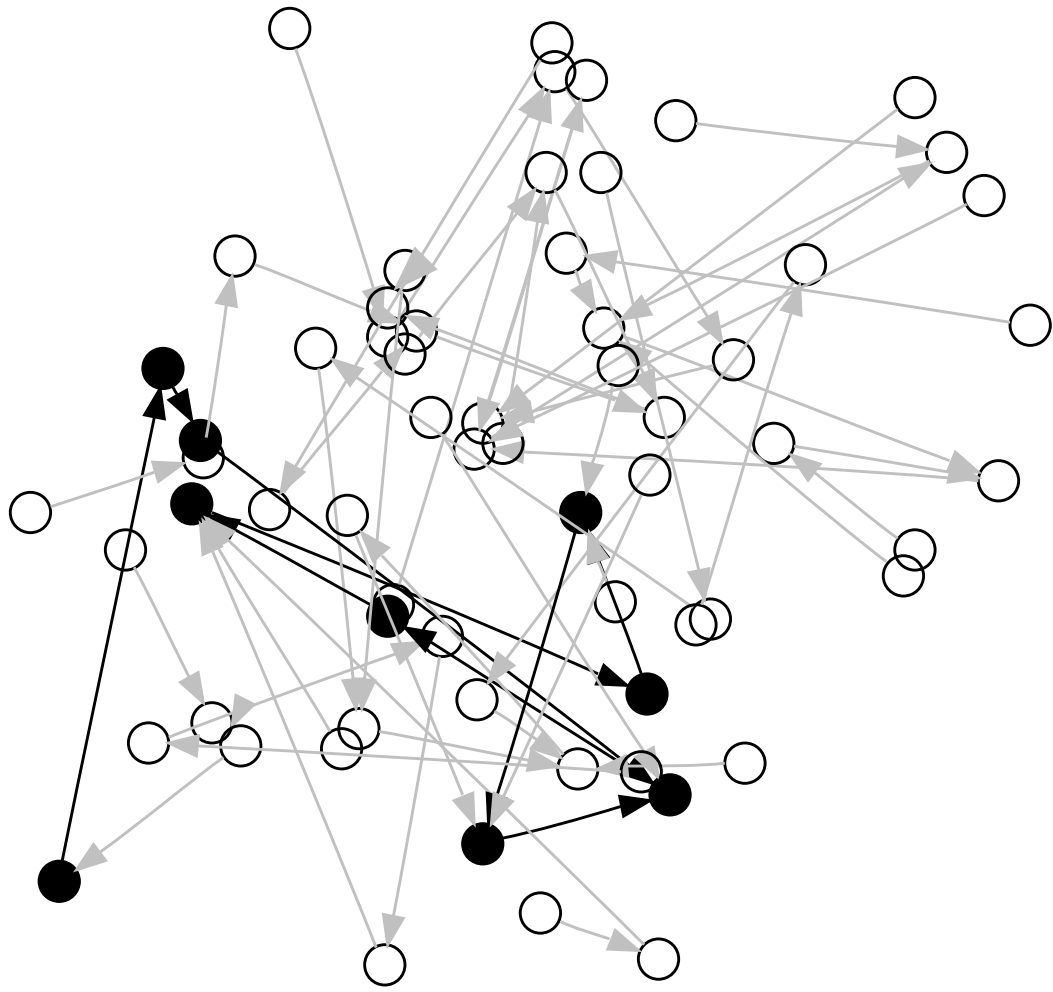


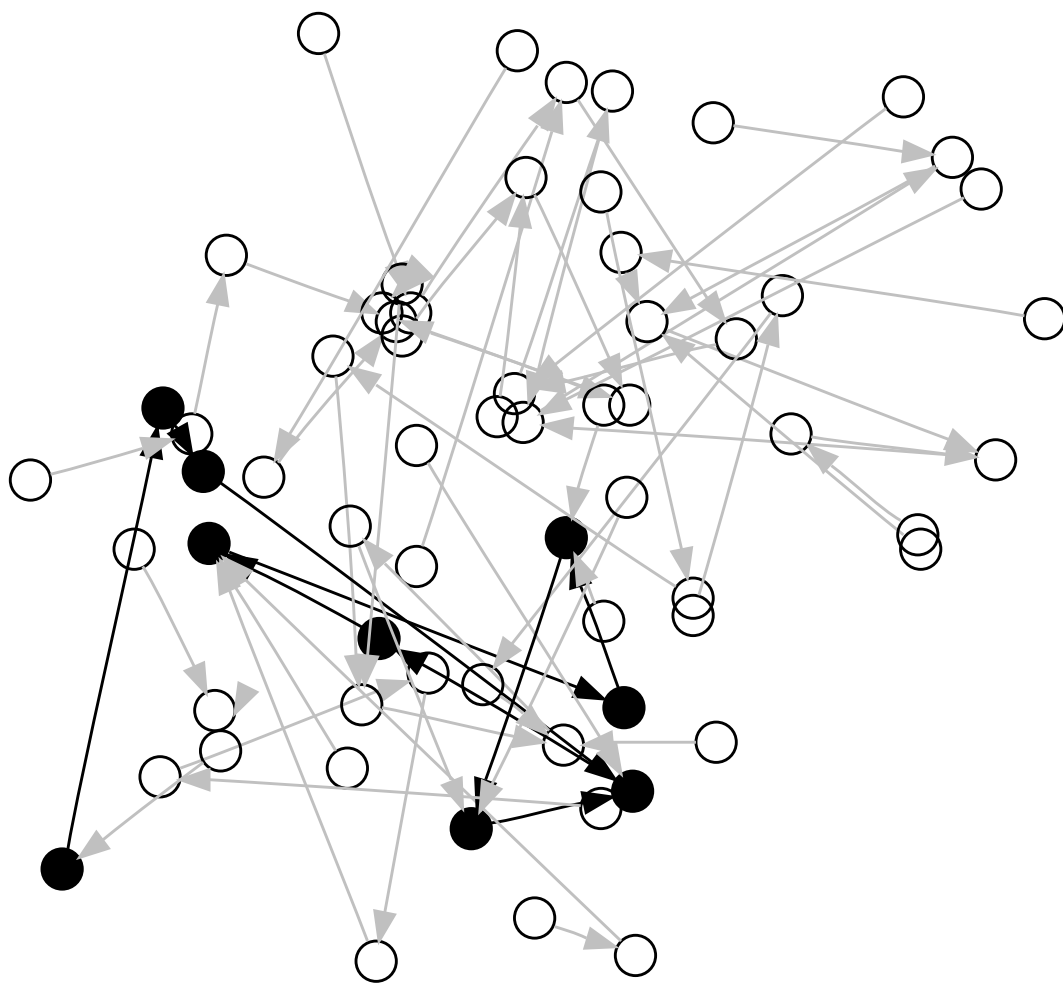


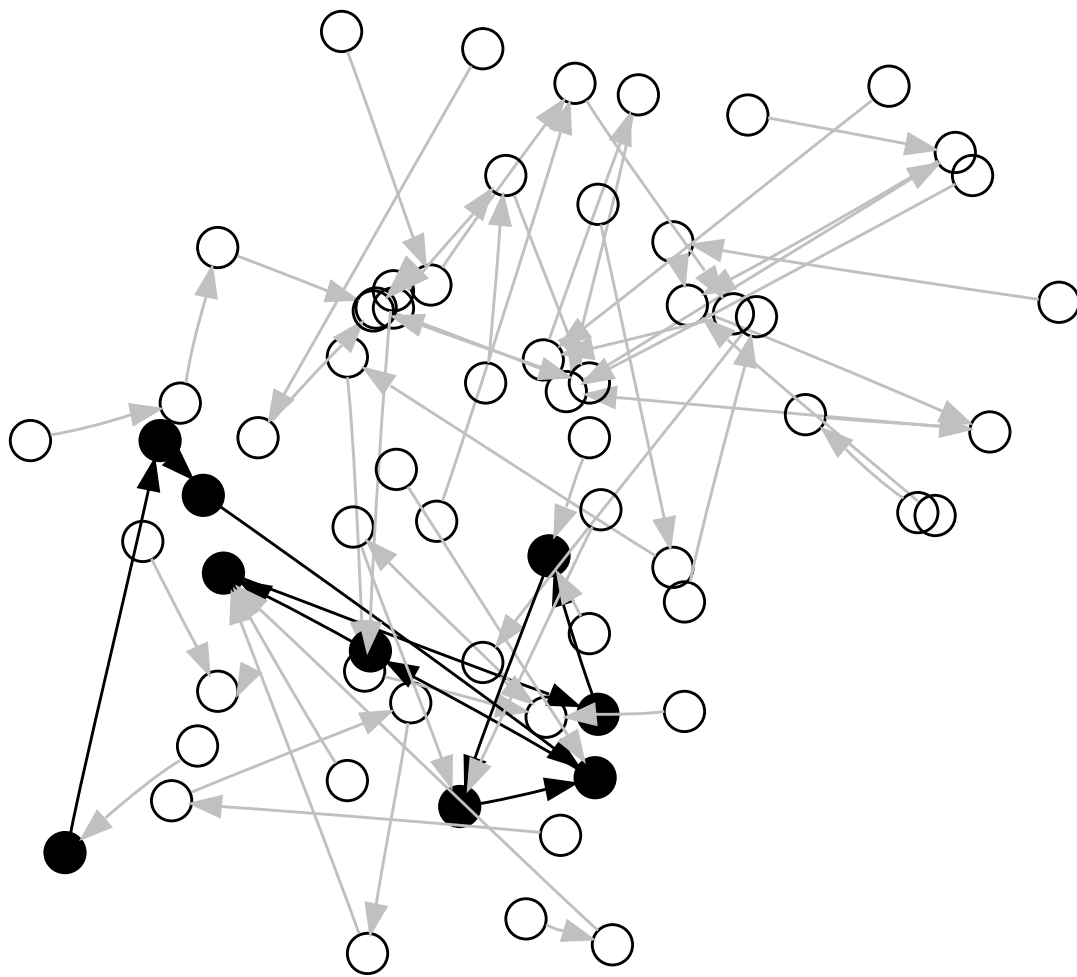


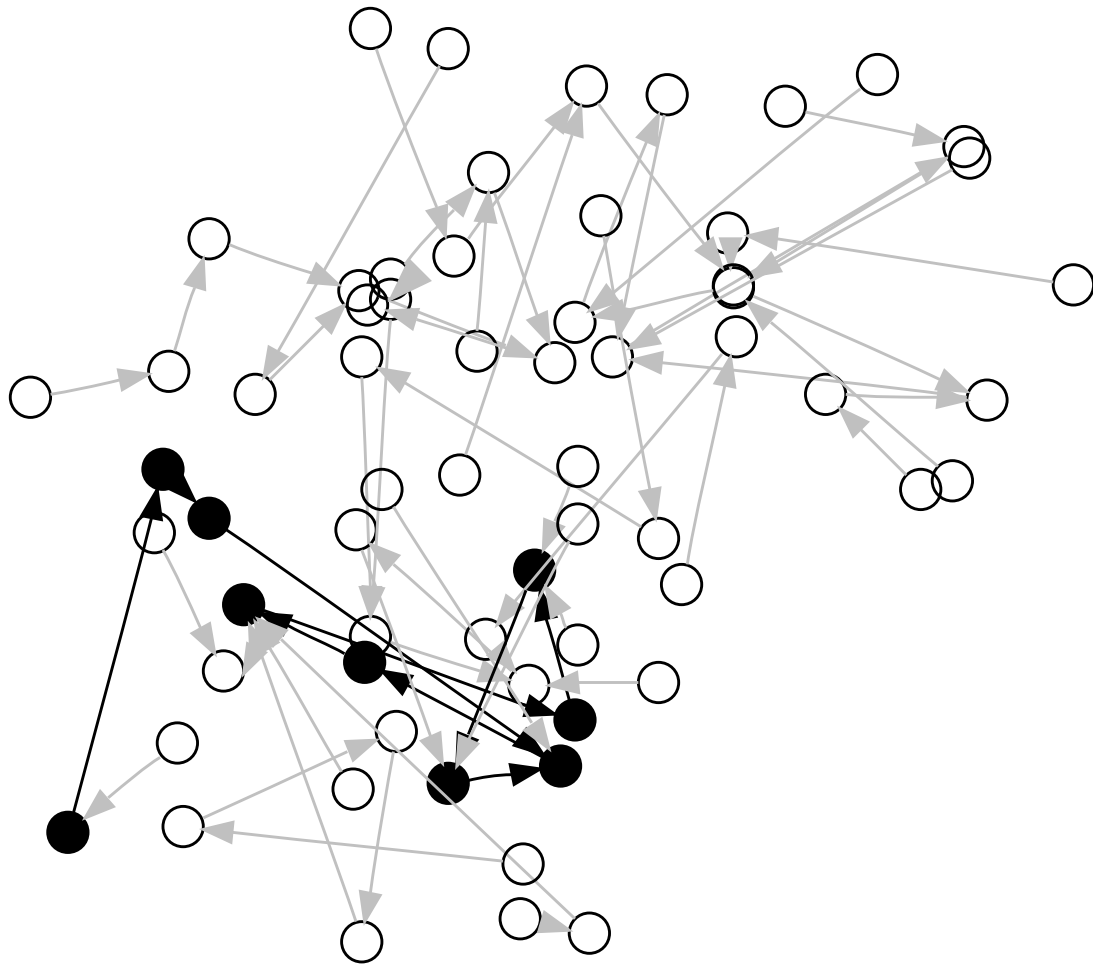


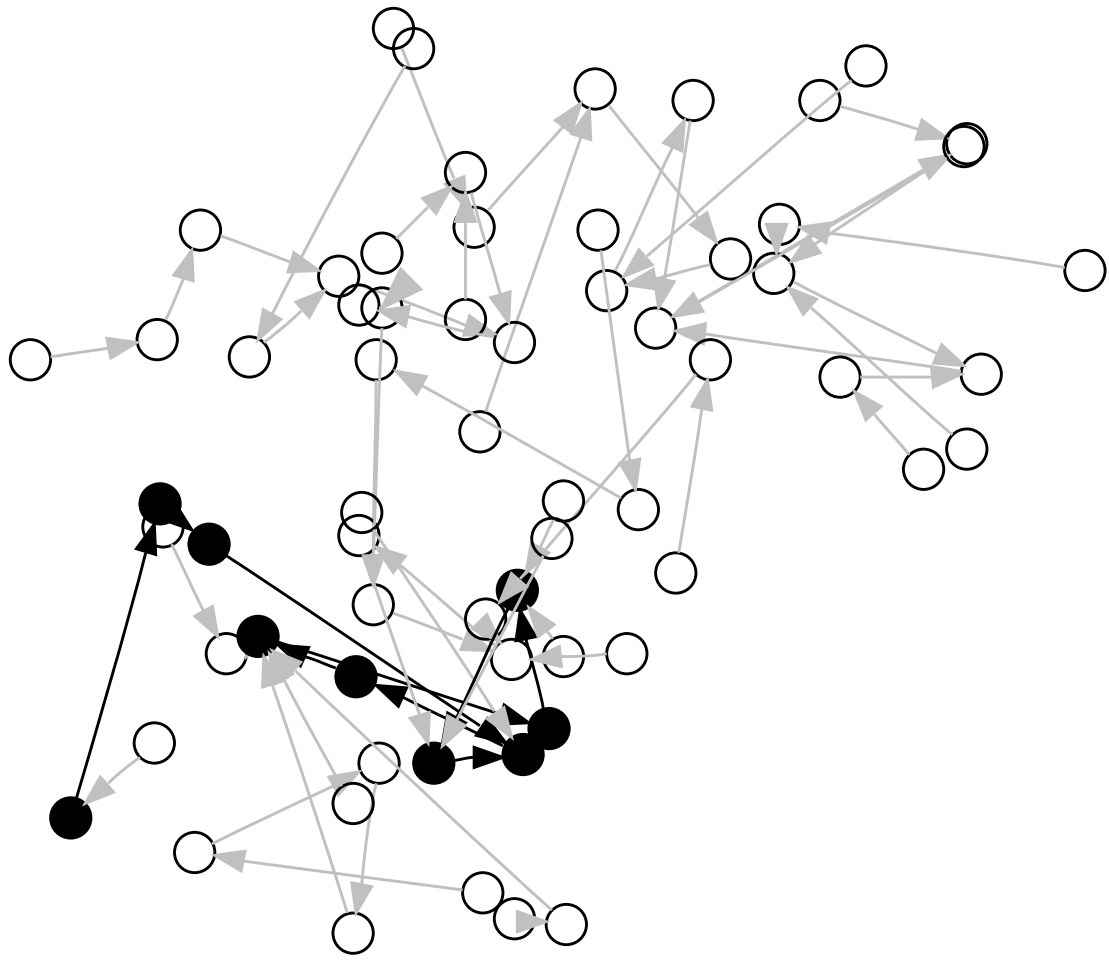


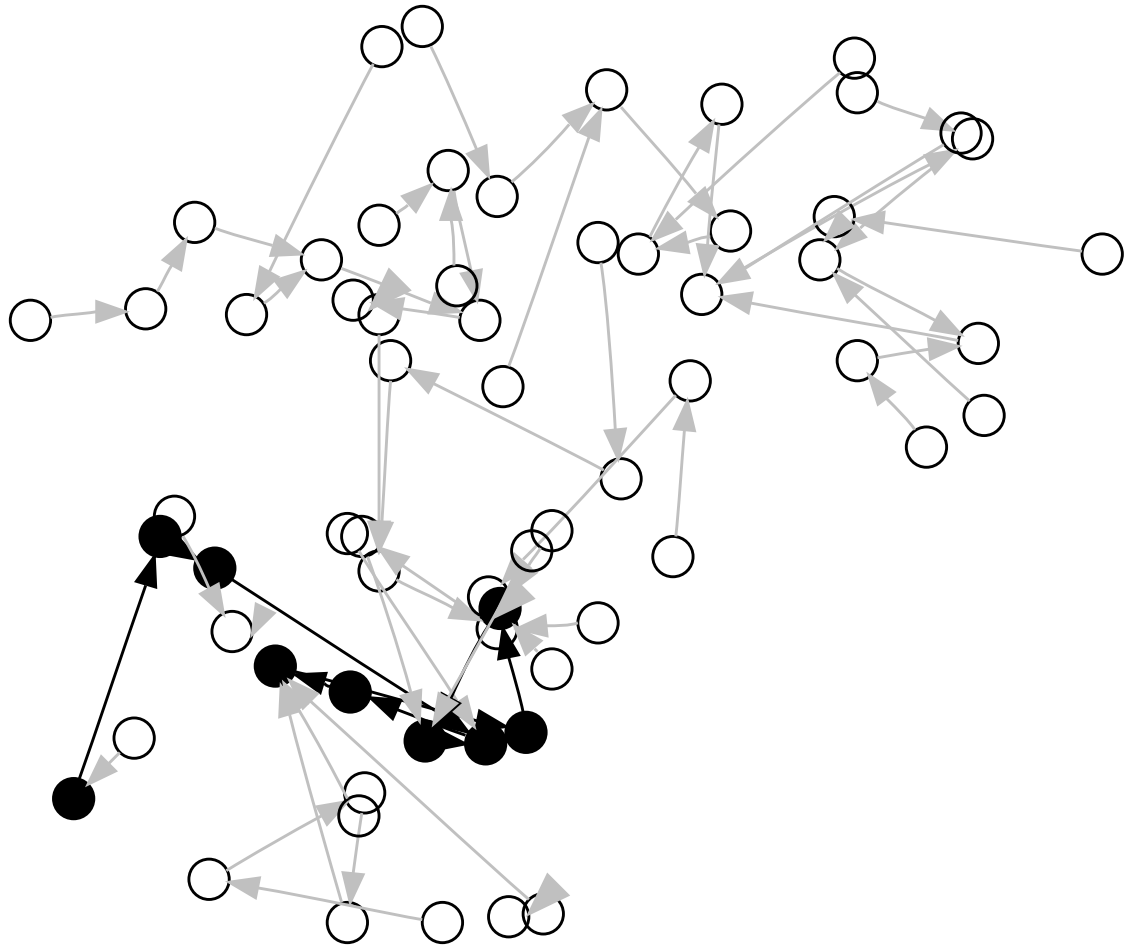


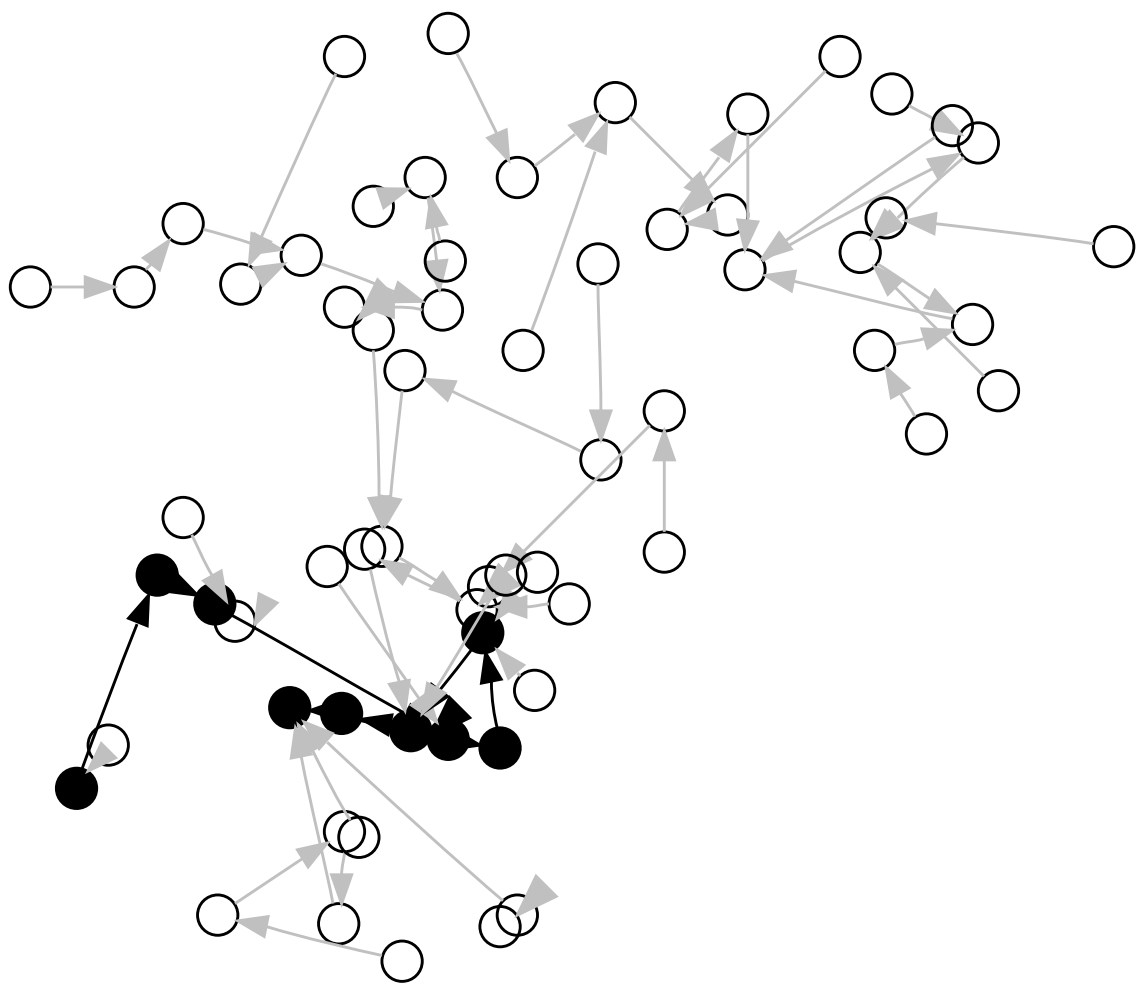


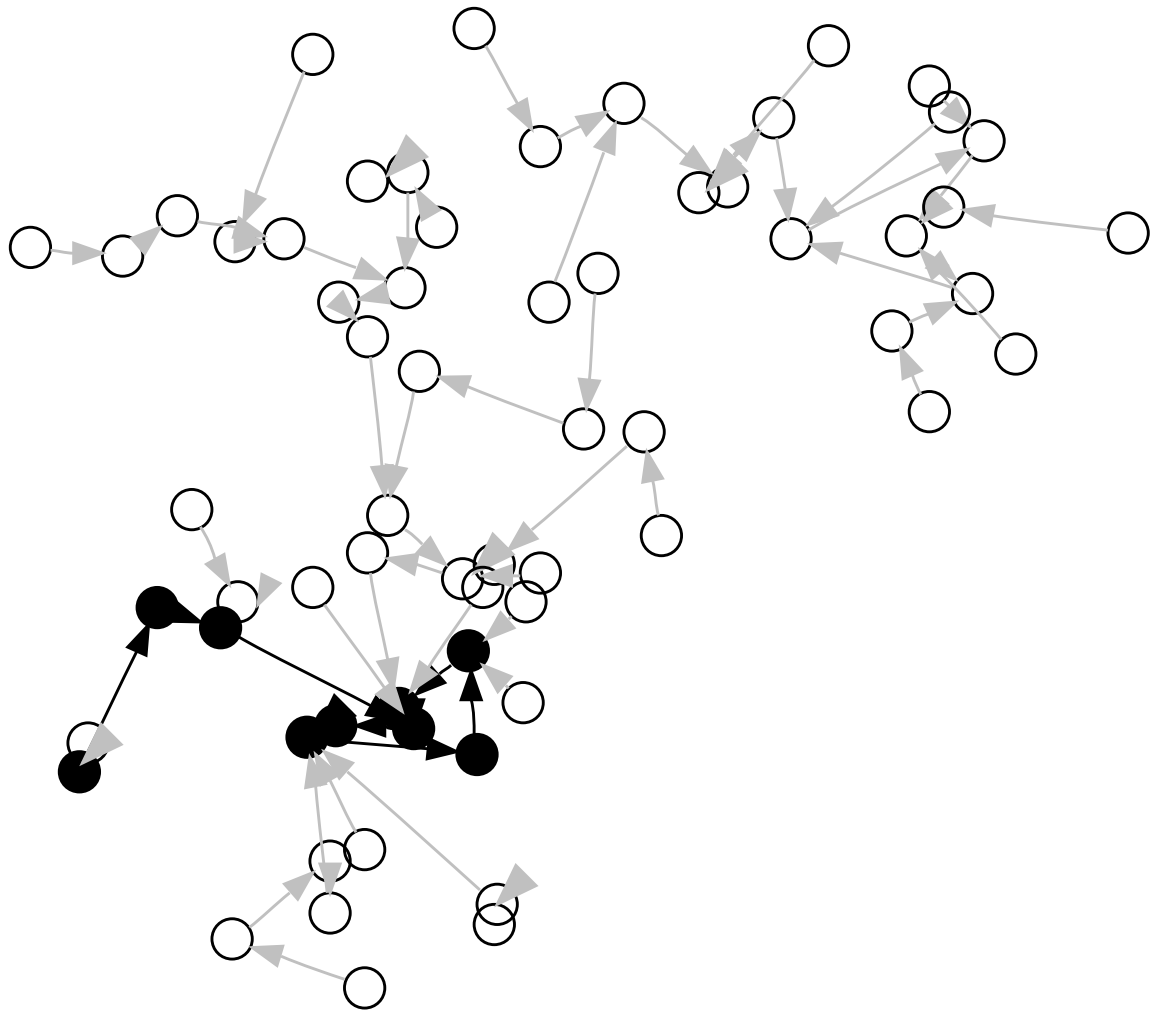




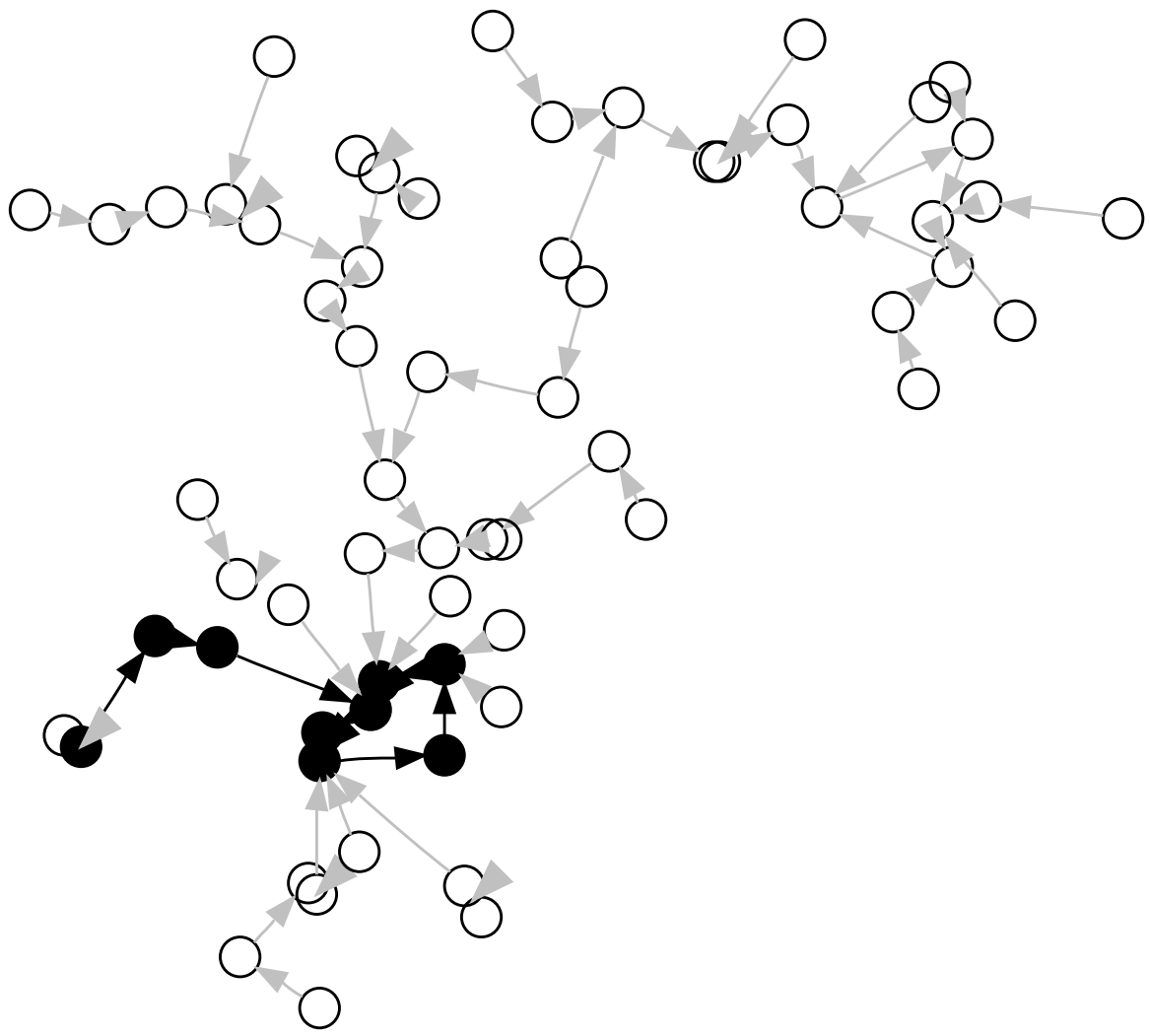


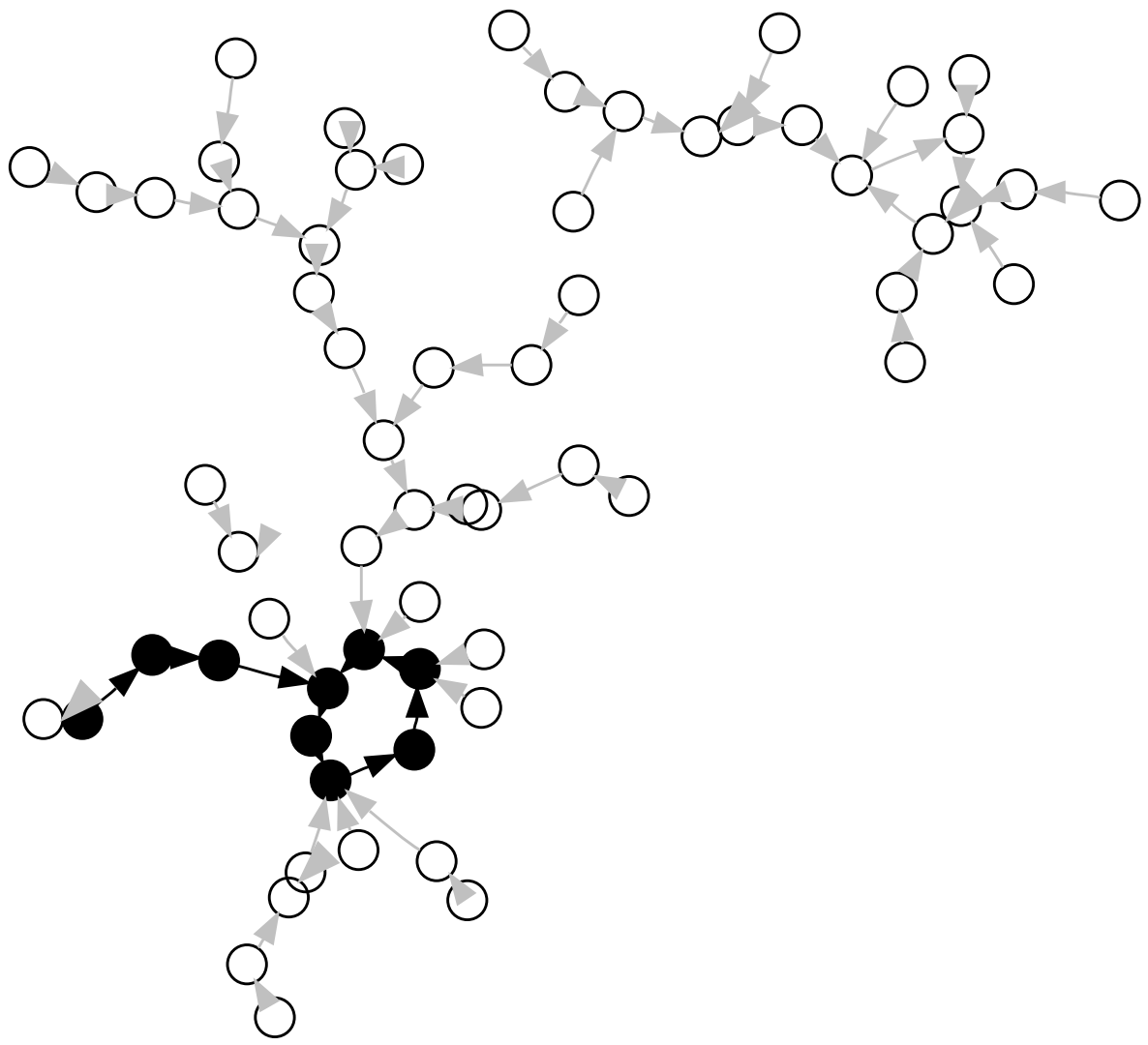


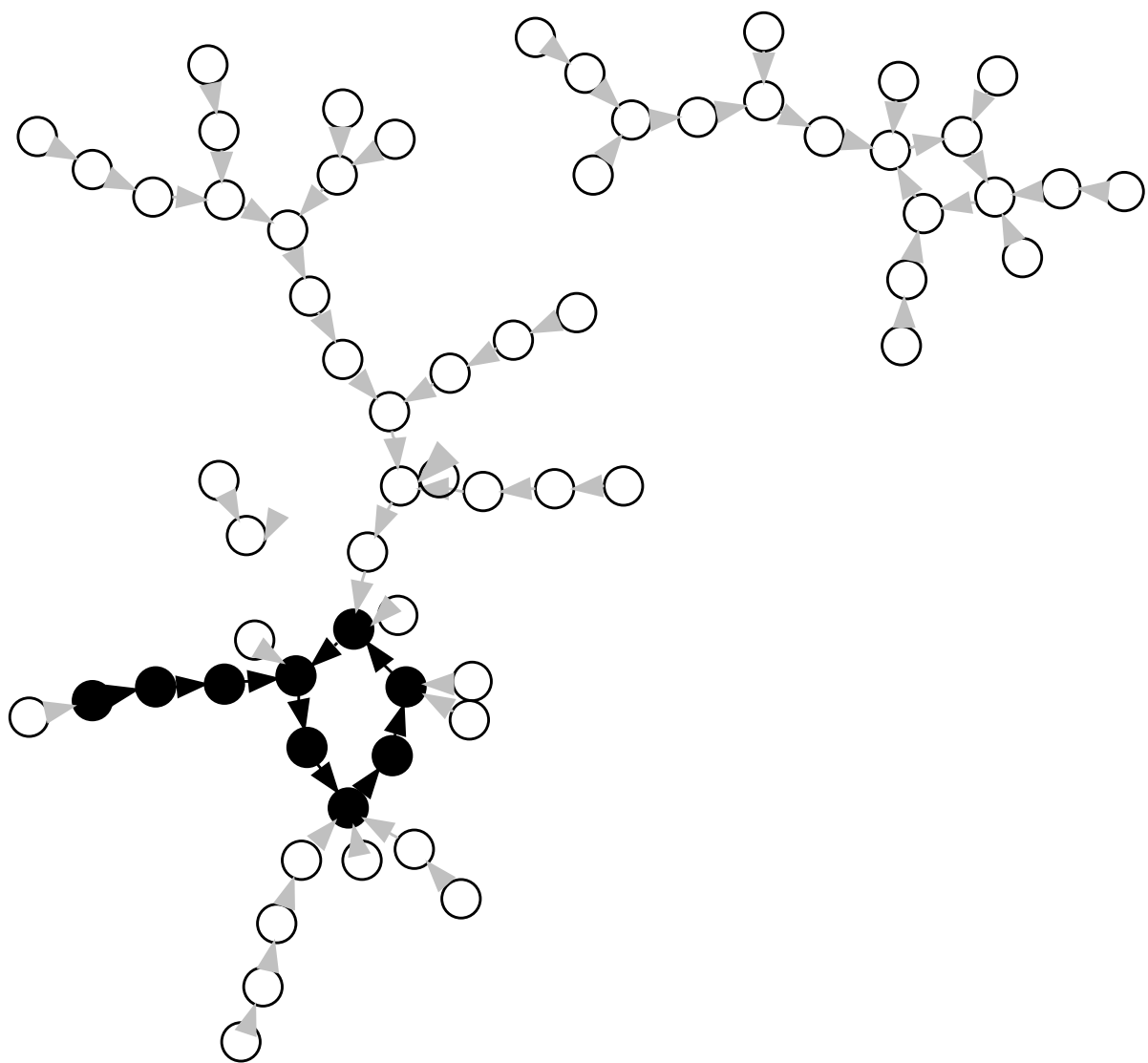












## Performance of rho

Model walk as truly random.

Using  $m$  multiplications:

$\approx m$  points  $(x_i, y_i)$ ;

$\approx m^2/2$  pairs of points;

slope  $\lambda$  is missed

with chance  $\approx (1 - 1/\ell)^{m^2/2}$

$\approx \exp(-m^2/(2\ell))$ .

Average # multiplications

$$\approx \sum_0^\infty \exp(-m^2/(2\ell))$$

$$\approx \int_0^\infty \exp(-m^2/(2\ell)) dm$$

$$= \sqrt{\pi/4} \sqrt{2\ell} = (1.25 \dots) \sqrt{\ell}.$$

Better than  $(4/3 + o(1)) \sqrt{\ell}$ .

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Better than  $(4/3 + o(1)) \sqrt{\ell}$ .

Don't ask about the worst case.

# Anti-collisions

Bad news:

The walk is worse than random.

Very often have

$$(\mathbf{x}_{i+1}, \mathbf{y}_{i+1}) = (\mathbf{x}_i, \mathbf{y}_i) + (\mathbf{s}_j, \mathbf{t}_j)$$

followed later by

$$(\mathbf{x}_{k+1}, \mathbf{y}_{k+1}) = (\mathbf{x}_k, \mathbf{y}_k) + (\mathbf{s}_j, \mathbf{t}_j).$$

Slope from

$$(\mathbf{x}_{k+1}, \mathbf{y}_{k+1}) \text{ to } (\mathbf{x}_{i+1}, \mathbf{y}_{i+1})$$

is not new: same as slope from

$$(\mathbf{x}_k, \mathbf{y}_k) \text{ to } (\mathbf{x}_i, \mathbf{y}_i).$$

Repeated slope: “anti-collision”.

$m^2/2$  was too optimistic.

About  $(1/r)m^2/2$  pairs  
use same step, so only  
 $(1 - 1/r)m^2/2$  chances.

This replacement model  $\Rightarrow$   
 $(\sqrt{\pi/2}/\sqrt{1 - 1/r} + o(1))\sqrt{\ell}$ .

Can derive  $\sqrt{1 - 1/r}$   
from more complicated 1981  
Brent–Pollard  $\sqrt{V}$  heuristic.

1998 Blackburn–Murphy:  
explicit  $\sqrt{1 - 1/r}$ .

2009 Bernstein–Lange:  
simplified heuristic;

generalized  $\sqrt{1 - \sum_j p_j^2}$ .

## Higher-degree anti-collisions

Actually, rho is even worse!

Often have

$$(x_{i+1}, y_{i+1}) = (x_i, y_i) + (s_j, t_j)$$

$$(x_{i+2}, y_{i+2}) = (x_{i+1}, y_{i+1}) + (s_h, t_h)$$

followed later by

$$(x_{k+1}, y_{k+1}) = (x_k, y_k) + (s_h, t_h)$$

$$(x_{k+2}, y_{k+2}) = (x_{k+1}, y_{k+1}) + (s_j, t_j)$$

so slope from

$$(x_{k+2}, y_{k+2}) \text{ to } (x_{i+2}, y_{i+2})$$

is not new.

“Degree-2 local anti-collisions”:

$$1/\sqrt{1 - 1/r - 1/r^2 + 1/r^3}.$$

See paper for more.



## Is rho optimal?

Allow  $r$  to grow slowly with  $\ell$ .  
(Not quickly: remember  
cost of initial computation.)

$$\sqrt{1 - 1/r} \rightarrow 1.$$

$$\sqrt{1 - 1/r - 1/r^2 + 1/r^3} \rightarrow 1.$$

Experimental evidence  $\Rightarrow$   
average  $(\sqrt{\pi/2} + o(1))\sqrt{\ell}$ .

But still have many  
global anti-collisions:  
slopes appearing repeatedly.

## Two grumpy giants and a baby

$$B: (0, 0) + \{0, \dots, n\}(0, 1).$$

$$G1: (1, 0) + \{0, \dots, n\}(0, n).$$

$$G2: (2, 0) - \{0, \dots, n\}(0, n+1).$$

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$$\text{Minor initial cost: } (0, -(n+1)).$$

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As before can interleave:

$$(0, 0), (1, 0), (2, 0),$$

$$(0, 1), (1, n), (2, -(n+1)),$$

$$(0, 2), (1, 2n), (2, -2(n+1)),$$

$$(0, 3), (1, 3n), (2, -3(n+1)),$$

⋮

$$(0, n), (1, n^2), (2, -n(n+1)).$$

## Grumpy performance

For  $(1.5 + o(1))\sqrt{\ell}$  mults:

BSGS, with  $n \approx 0.75\sqrt{\ell}$

or interleaved with  $n \approx \sqrt{\ell}$ ,

finds  $(0.5625 + o(1))\ell$  slopes.

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Truly random walk

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Also better average case than rho.