

Usable assembly language
for GPUs:
a success story

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OpenSSL crypto library
(version 1.0.1, 2012.03)
includes 15 different
asm implementations of AES.

SHA-3-512 implementations
benchmarked in eBASH:

17 for blake512,
25 for keccakc1024,
15 for groestl512,
7 for round3jh512,
12 for skein512512.

Widespread use of asm
in the fastest implementations.

Why not just one
portable implementation?

What do compilers do wrong?

- Instruction selection:
e.g., compiler doesn't see
how to use vector instructions.
- Instruction scheduling.
- Register allocation.

Can blame programming language
for hiding critical information.

Increasing gap between
common languages and hardware.

NVIDIA GTX 295 graphics card:

Massively parallel—2 GPUs,
60 cores, 480 32-bit ALUs.

(NVIDIA marketing terminology:
60 “MPs”; 480 “cores” .)

Massively vectorized—
1 slow instruction decoder/core.

Relatively little fast RAM—
16384 bytes “shared mem” /core.
(Newer “Fermi” GPUs: better.)

Can C compilers use GPUs?

No! Intolerable slowdown.

NVIDIA solution: Change the programming language. Tweaked “CUDA” version of C. (“OpenCL” variant of CUDA is also supported by AMD.)

CUDA programs explicitly state parallelization, vectorization. Eliminates biggest problem in instruction selection.

But the NVIDIA compilers still have big trouble with register allocation.

Case study: ECC2K-130—
“infeasible” ECDLP challenge
posed in 1997 by Certicom.

Optimized attack

(see paper for references):

$\approx 2^{60.9}$ iterations of

$(x, y) \mapsto (x', y')$; many in parallel.

x, y are in $\mathbf{F}_{2^{131}}$;

x has even Hamming weight w ;

$j = 3 + ((w/2) \bmod 8)$;

$\lambda = (y + y^{2^j}) / (x + x^{2^j})$;

$x' = \lambda^2 + \lambda + x + x^{2^j}$;

$y' = \lambda(x + x') + x' + y$.

≈ 70000 bit ops/iteration
with best techniques known;
 $\approx 2^{77}$ bit ops overall.

Main cost (85% of bit ops):
5 poly mults/iteration,
 $131 \times 131 \rightarrow 261$ bits.

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Compare to theoretical capacity
of one GTX 295: 60 cores,
each 256 bit ops/cycle,
 $1.242 \cdot 10^9$ cycles/second
 $\Rightarrow 2^{70}$ bit ops in 2 years.

64 dual-GTX-295 PCs:
 2^{77} bit ops in 2 years.

This comparison assumes that 100% of GPU time is spent on useful bit operations.

We try writing CUDA code, feed it to NVIDIA's `nvcc`.

Experiment extensively with “optimizations” to CUDA code.

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What's going wrong?

`nvcc` is constantly

running out of registers,

spilling to “local memory”;

huge cost. (Less huge on Fermi.)

NVIDIA has `ptxas` assembler,
documents “PTX” instruction set.
(Recent NVIDIA `nvcc` releases
support inline PTX in CUDA.)

Great! Rewrite code in PTX,
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PTX isn’t the machine language.
`ptxas` is the actual compiler:
converts to SSA, re-assigns regs,
spills to expensive local memory.

2007 van der Laan
reverse-engineered binaries,
wrote decuda tool
to print machine language
in a readable format.
(NVIDIA now supports this.)

Also cudasm to convert readable
format back to machine language.

2010 L.-S. Chien “Hand-tuned
SGEMM on GT200 GPU”:

Successfully gained speed
using decuda, cudasm
and manually rewriting
a small section of ptxas output.

But this was “tedious” and hampered by `cuDasm` bugs:

“we must extract minimum region of binary code needed to be modified and keep remaining binary code unchanged . . .

implementation of `cuDasm` is not entirely complete, it is not a good idea to write whole assembly manually and rely on `cuDasm`.”

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Not a serious obstacle!

We fixed various bugs

and now use `cuDasm`

to generate our GTX 295 code.

Everybody knows that
writing in asm is painful.

Maybe the most painful part:
have to manually assign
live values to registers.

Our fix: `qhasm-cudasm`.
Usable asm for GPUs.

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`qhasm` toolkit for parsing
and smart register allocation.

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The old parts: `cudasm`;
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and smart register allocation.

New: usable syntax
for the GPU instructions.

C/C++/CUDA:

```
z2 = x2 ^ y2;
```

PTX:

```
xor.b32 %r24, %r22, %r23;
```

cuasm:

```
xor.b32 $r2, $r3, $r2
```

qhasm-cuasm:

```
z2 = x2 ^ y2
```

See paper for many
detailed examples.

low32 threadinfo

input threadinfo

enter Z9kerneladdPjPKjS_

low32 tid

low32 x

low32 y

low32 t

low32 tstart

low32 tend

low32 ttid

low32 tselected

low32 now

tselected = 0

low32 j

low32 twenty

cond testloop

tid = 65535 & threadinfo

cond tid12

tid12 tid - c[0]

low32 tid4

tid4 = tid << 2

offset tid4off

tid4off = tid << 2

low32 batchshift

batchshift = blockindex

batchshift int24*= 33536

```
x = parameters[0]
```

```
y = parameters[1]
```

```
t = parameters[2]
```

```
x += batchshift
```

```
y += batchshift
```

```
low32 0x0
```

```
low32 0x1
```

```
low32 0x2
```

```
low32 0x3
```

```
low32 0x4
```

```
low32 0pos
```

```
syncthreads
```

new 0x4

0pos = tid4 + x

0x0 = g[0pos]

0pos += 512

0x1 = g[0pos]

0pos += 512

0x2 = g[0pos]

0pos += 512

0x3 = g[0pos]

0pos += 512

0x4 = g[0pos] if tid12 signed<

s[tid4off + 512] = 0x0

s[tid4off + 1024] = 0x1

`s[tid4off + 1536] = 0x2`

`s[tid4off + 2048] = 0x3`

`s[tid4off + 2560] = 0x4 if tid12 s`

`low32 1x0`

`low32 1x1`

`low32 1x2`

`low32 1x3`

`low32 1x4`

`low32 1pos`

`syncthread`

`new 1x4`

1pos = tid4 + y

1x0 = g[1pos]

1pos += 512

1x1 = g[1pos]

1pos += 512

1x2 = g[1pos]

1pos += 512

1x3 = g[1pos]

1pos += 512

1x4 = g[1pos] if tid12 signed<

s[tid4off + 2608] = 1x0

s[tid4off + 3120] = 1x1

s[tid4off + 3632] = 1x2

s[tid4off + 4144] = 1x3

```
s[tid4off + 4656] = 1x4 if tid12 s
```

```
syncthread
```

```
j = 0
```

```
twenty = 20
```

```
syncthread
```

```
tstart = halfclock
```

```
low32 2x0
```

```
low32 2x1
```

```
low32 2x2
```

```
low32 2x3
```

```
low32 2x4
```

```
low32 0y0
```

```
low32 0y1
```

low32 0y2

low32 0y3

low32 0y4

new 2x4

new 0y4

2x0 = s[tid4off + 512]

2x1 = s[tid4off + 1024]

2x2 = s[tid4off + 1536]

2x3 = s[tid4off + 2048]

2x4 = s[tid4off + 2560] if tid12 s

0y0 = s[tid4off + 2608]

0y1 = s[tid4off + 3120]

0y2 = s[tid4off + 3632]

0y3 = s[tid4off + 4144]

$0y4 = s[tid4off + 4656]$ if tid12 s

$2x0 \hat{=} 0y0$

$2x1 \hat{=} 0y1$

$2x2 \hat{=} 0y2$

$2x3 \hat{=} 0y3$

$2x4 \hat{=} 0y4$

$s[tid4off + 512] = 2x0$

$s[tid4off + 1024] = 2x1$

$s[tid4off + 1536] = 2x2$

$s[tid4off + 2048] = 2x3$

$s[tid4off + 2560] = 2x4$ if tid12 s

syncthread

tend = halfclock

```
tend -= tstart
```

```
tend <<= 1
```

```
low32 3x0
```

```
low32 3x1
```

```
low32 3x2
```

```
low32 3x3
```

```
low32 3x4
```

```
low32 2pos
```

```
syncthread
```

```
new 3x4
```

```
3x0 = s[tid4off + 512]
```

```
3x1 = s[tid4off + 1024]
```

3x2 = s[tid4off + 1536]

3x3 = s[tid4off + 2048]

3x4 = s[tid4off + 2560] if tid12 s

2pos = tid4 + x

g[2pos] = 3x0

2pos += 512

g[2pos] = 3x1

2pos += 512

g[2pos] = 3x2

2pos += 512

g[2pos] = 3x3

2pos += 512

g[2pos] = 3x4 if tid12 signed<

```
ttid = tid << 2
```

```
ttid += t
```

```
g[ttid] = tend
```

```
leave
```