Speeding up characteristic 2:

- I. Linear maps
- II. The M(n) game
- III. Batching
- IV. Normal bases
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#### Part I. Linear maps

Consider computing  $h_0 = q_0;$   $h_1 = q_1;$   $h_2 = q_2 \oplus (p_0 \oplus q_0 \oplus r_0);$   $h_3 = (p_1 \oplus q_1 \oplus r_1);$   $h_4 = (p_2 \oplus q_2 \oplus r_2) \oplus r_0;$   $h_5 = r_1;$  $h_6 = r_2.$ 

Easy: 8 additions. Can find these 8 additions in several papers. But 8 is not optimal! "Wasting brain power is bad for the environment." Use existing algorithms to find addition chains.

Apply, e.g., greedy additive CSE algorithm from 1997 Paar:

- find input pair  $i_0, i_1$ with most popular  $i_0 \oplus i_1$ ;
- compute  $i_0 \oplus i_1$ ;
- simplify using  $i_0 \oplus i_1$ ;
- repeat.

This algorithm finds repeated  $q_2 \oplus r_0$ ; uses 7 additions.

A new algorithm: "xor largest." Start with the matrix mod 2 for the desired linear map.

If two largest rows have same first bit, replace largest row by its xor with second-largest row.

Otherwise change largest row by clearing first bit.

In both cases, compute result recursively, and finish with one xor. A small example:

 $1011 = x_0 + x_2 + x_3$   $1111 = x_0 + x_1 + x_2 + x_3$   $0110 = x_1 + x_2$  $0101 = x_1 + x_3$ 

Replace largest row by its xor with second-largest row.

 $egin{aligned} 1011 &= x_0 + x_2 + x_3 \ 0100 &= x_1 \leftarrow \ 0110 &= x_1 + x_2 \ 0101 &= x_1 + x_3 \end{aligned}$ 

plus 1 xor of first output into second output.

 $\begin{array}{l} 0011 \leftarrow \\ 0100 \\ 0110 \\ 0101 \end{array}$ 

plus 1 input load, 2 xors.

- $\begin{array}{c} 0011 \\ 0100 \\ 0011 \leftarrow \\ 0101 \end{array}$
- plus 1 input load, 3 xors.

0011 0100 0011

 $0001 \leftarrow$ 

plus 1 input load, 4 xors.

- 0011 0000 ←
- 0011
- 0001

plus 2 input loads, 4 xors. Note: this was just a copy.

0001

plus 2 input loads, 4 xors.

- $\begin{array}{l} 0000\\ 0000\\ 0001 \leftarrow\\ 0001 \end{array}$
- plus 3 input loads, 5 xors.

plus 3 input loads, 5 xors.

 $\begin{array}{c} 0000\\ 0000\\ 0000\\ 0000\\ \leftarrow\end{array}$ 

plus 4 input loads, 5 xors.

Memory friendliness: Algorithm writes only to the output registers. No temporary storage.

*n* inputs, *n* outputs: total 2*n* registers with 0 loads, 0 stores.

Or n + 1 registers with n loads, 0 stores: each input is read only once.

Or *n* registers with *n* loads, 0 stores, if platform has load-xor insn. Two-operand friendliness: Platform with  $a \leftarrow a \oplus b$ but without  $a \leftarrow b \oplus c$ uses only *n* extra copies.

Naive column sweep also uses n + 1 registers, n loads, but usually many more xors.

Input partitioning (e.g., 1956 Lupanov) uses somewhat more xors, copies; somewhat more registers.

Greedy additive CSE uses somewhat fewer xors but many more copies, registers. For m inputs and n outputs, average  $n \times m$  matrix:

The xor-largest algorithm uses  $\approx mn/\lg n$  two-operand xors; *n* copies; *m* loads; n+1 regs. For m inputs and n outputs, average  $n \times m$  matrix:

The xor-largest algorithm uses  $\approx mn/\lg n$  two-operand xors; *n* copies; *m* loads; n + 1 regs.

Pippenger's algorithm uses  $\approx mn/\lg mn$  three-operand xors but seems to need many regs.

Pippenger proved that his algebraic complexity was near optimal for most matrices (at least without mod 2), but didn't consider regs, two-operand complexity, etc.

Each row has coefficients of  $p_0, p_1, p_2, q_0, q_1, q_2, r_0, r_1, r_2$ .

plus 1 xor, 1 input load.

plus 2 xors, 2 input loads.

 $000001101 \leftarrow$ 

plus 3 xors, 3 input loads.

plus 4 xors, 3 input loads.

plus 4 xors, 4 input loads.

plus 5 xors, 4 input loads.

Our original example:  $\rightarrow$  000000000  $\leftarrow$ 

plus 5 xors, 5 input loads.

 $00000001 \leftarrow$ 

plus 6 xors, 5 input loads.

plus 7 xors, 6 input loads.

Our original example:  $\rightarrow$  00000000  $\leftarrow$ 

plus 7 xors, 7 input loads.

plus 7 xors, 7 input loads.

plus 7 xors, 8 input loads.

plus 7 xors, 8 input loads.

plus 7 xors, 9 input loads.

Algorithm found the speedup.

## Part II. The M(n) game

Define M(n)as the minimum number of bit operations (ands, xors) needed to multiply n-bit polys  $f, g \in \mathbf{F}_2[x]$ (in standard representation).

e.g. 
$$M(2) \leq 5$$
:  
to compute  
 $h_0 + h_1 x + h_2 x^2 =$   
 $(f_0 + f_1 x)(g_0 + g_1 x)$   
can compute  $h_0 = f_0 g_0$ ,  
 $h_1 = f_0 g_1 + f_1 g_0$ ,  $h_2 = f_1 g_1$   
with 4 ands, 1 xor.

Schoolbook multiplication:  $M(n) \leq \Theta(n^2).$ 

1963 Karatsuba: $M(n) \leq \Theta(n^{\lg 3}).$ 

1963 Toom: $M(n) \leq n 2^{\Theta(\sqrt{\lg n})}.$ 

1971 Schönhage–Strassen: $M(n) \leq \Theta(n \lg n \lg \lg n).$ 

2007 Fürer improves lg lg *n* for integers but doesn't help mod 2. What does this tell us about M(131) or M(251)? Absolutely nothing! Reanalyze algorithms to see exact complexity. Rethink algorithm design to find constant-factor (and sub-constant-factor) speedups that are not visible in the asymptotics.

Schoolbook recursion:  $M(n+1) \leq M(n) + 4n.$ Hence  $M(n) \le 2n^2 - 2n + 1$ . Karatsuba recursion as commonly stated: M(2n) < 3M(n) + 8n - 4.e.g. Karatsuba for n = 1:  $f = f_0 + f_1 x$ ,  $g=g_0+g_1x,$  $h_0 = f_0 q_0$ ,  $h_2 = f_1 q_1$ ,  $h_1 = (f_0 + f_1)(g_0 + g_1) - h_0 - h_2$  $\Rightarrow fq = h_0 + h_1x + h_2x^2$ .

Karatsuba for n = 2:

$$f=f_0+f_1x+f_2x^2+f_3x^3$$
, $g=g_0+g_1x+g_2x^2+g_3x^3$ ,

 $egin{aligned} &\mathcal{H}_0 = (f_0 + f_1 x)(g_0 + g_1 x), \ &\mathcal{H}_2 = (f_2 + f_3 x)(g_2 + g_3 x), \ &\mathcal{H}_1 = (f_0 + f_2 + (f_1 + f_3) x) \cdot \ &(g_0 + g_2 + (g_1 + g_3) x) \ &- \mathcal{H}_0 - \mathcal{H}_2 \end{aligned}$ 

 $\Rightarrow fg = H_0 + H_1 x^2 + H_2 x^4.$ 

Initial linear computation:  $f_0 + f_2$ ,  $f_1 + f_3$ ,  $g_0 + g_2$ ,  $g_1 + g_3$ ; cost 4.

Three size-2 mults producing  $H_0 = q_0 + q_1 x + q_2 x^2;$   $H_2 = r_0 + r_1 x + r_2 x^2;$  $H_0 + H_1 + H_2 = p_0 + p_1 x + p_2 x^2.$ 

Final linear reconstruction:

$$egin{aligned} \mathcal{H}_1 &= (p_0 - q_0 - r_0) + \ && (p_1 - q_1 - r_1)x + \ && (p_2 - q_2 - r_2)x^2, \end{aligned}$$

cost 6;

$$fg = H_0 + H_1 x^2 + H_2 x^4$$
,  
cost 2.

Let's look more closely at the reconstruction:  $fg = h_0 + h_1 x + \cdots + h_6 x^6$  with  $h_0 = q_0;$  $h_1 = q_1;$  $h_2 = q_2 + (p_0 - q_0 - r_0);$  $h_3 = (p_1 - q_1 - r_1);$  $h_4 = (p_2 - q_2 - r_2) + r_0;$  $h_5 = r_1;$  $h_6 = r_2$ .

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We've seen this before! Reduce 6 + 2 = 8 ops to 7 ops by reusing  $q_2 - r_0$ . 2000 Bernstein:  $M(2n) \le 3M(n) + 7n - 3.$ 2009 Bernstein: new bounds on M(n)from further improvements to Karatsuba, Toom, etc. binary.cr.yp.to/m.html

Typically 20% smaller than 2003 Rodríguez-Henríquez–Koç, 2005 Chang–Kim–Park–Lim, 2006 Weimerskirch–Paar, 2006 von zur Gathen–Shokrollahi, 2007 Peter–Langendörfer. So far have focused on M(n) for small n, but different techniques are better for large n.

I'm now exploring impact of 2008 Gao–Mateer.

For  $\mathbf{F}_2 \subseteq \mathbf{F}_q \subseteq k$ : 1988 Wang–Zhu, 1989 Cantor diagonalize  $k[t]/(t^q + t)$  using  $\approx 0.5q \lg q$  mults in k,  $\approx 0.5q(\lg q)^{\lg 3}$  adds in k. 2008 Gao–Mateer use  $\approx 0.5q \lg q$  mults,  $\approx 0.25q \lg q \lg \lg q$  adds. "Who cares?"

Conventional wisdom:

Detailed M(n) analysis has very little relevance to software speed.

We multiply *f* by *g* by looking up 4 bits of *f* in a size-16 table of precomputed multiples of *g*; looking up next 4 bits; etc. One table lookup replaces many bit operations!

Might use Karatsuba etc., but only for large *n*.

## Part III. Batching

Classic  $\mathbf{F}_{p}^{*}$  index calculus needs to check smoothness of many positive integers < p.

Smooth integer: integer with no prime divisors > y. Typical:  $(\log y)^2 \in$  $(1/2 + o(1)) \log p \log \log p$ . Many: typically  $y^{2+o(1)}$ ,

of which  $y^{1+o(1)}$  are smooth.

(Modern index calculus, NFS: smaller integers; smaller y.)

How to check smoothness?

Old answers: Trial division, time  $y^{1+o(1)}$ ; rho, time  $y^{1/2+o(1)}$ , assuming standard conjectures. Better answer: ECM etc. Time  $y^{o(1)}$ ; specifically  $\exp \sqrt{(2+o(1)) \log y \log \log y}$ , assuming standard conjectures.

Much better answer (in standard RAM model): Known *batch* algorithms test smoothness of *many* integers simultaneously. Time per input:  $(\log y)^{O(1)}$  $= \exp O(\log \log y)$ . General pattern:

Algorithm designer optimizes algorithm for *one* input.

But algorithm is then applied to *many* inputs! Oops.

Often much better speed from *batch* algorithms optimized for many inputs.

e.g. Batch ECDL:  $\sqrt{\#}$  speedup. Batch NFS: smaller exponent. Can find many more examples. Surprising recent example: Batching can save time in *multiplication*!

Largest speedups:  $F_2[x]$ .

Consequence: New speed record for public-key cryptography. 37895 scalar mults/second on a 3.2GHz Phenom II X4 for a secure elliptic curve/**F**<sub>2</sub>251.

http://binary.cr.yp.to

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Note: No subfields were exploited in the creation of this record.

Simplest batching technique: "bitslicing."

Transpose 128 polynomials  $f_0, f_1, \ldots, f_{127} \in \mathbf{F}_2[x]$ , each having d coefficients, into d vectors  $F_0, F_1, \ldots, F_{d-1} \in \mathbf{F}_2^{128}$ , where  $F_i[j] = f_j[i]$ .

Vector operation  $F_1 \oplus F_{33}$ adds bit 1 of  $f_j$ to bit 33 of  $f_j$ for each *i* in parallel. Bitslicing disadvantages:

Table lookups are expensive. e.g. tab[ $f_j$  mod 16].

Conditional branches are expensive.

128× volume of data; harder to avoid load/store bottlenecks.

Transposition costs roughly 1 cycle per byte; frequent transposition is bad. Bitslicing advantages:

Free bit extraction, bit shuffling, etc.

No word-size penalty. e.g. 128 additions of d-bit polynomials cost d vector xors instead of 128  $\lceil d/128 \rceil$ . Huge speedup for small d.

 $\Rightarrow$  Productive synergy with M(n) techniques. Elliptic-curve addition P + Q traditionally uses conditional branches: Q = P? Q = -P? etc.

2006 Bernstein: cheaply avoid conditional branches in  $P \mapsto nP$  if  $2 \neq 0$ .

2007 Bernstein–Lange, using Edwards curves: arbitrary group ops if  $2 \neq 0$ .

2008 Bernstein–Lange– Rezaeian Farashahi,

"binary Edwards curves": arbitrary group ops if 2 = 0.

## Part IV. Normal bases

Current ECRYPT project, spearheaded by Tanja Lange: break Certicom's ECC2K-130.

i.e., compute discrete log of a challenge point on  $y^2 + xy = x^3 + 1$  over  ${\sf F}_{2^{131}}$ .

Carefully selected iteration function for Pollard rho involves 5 mults,

- 21 squarings, 7 adds,
- occasional inversions,

and one computation of weight in normal basis.

 $\mathbf{F}_{2131}$  has type-2 normal basis  $\zeta + \zeta^{-1}$ ,  $\zeta^2 + \zeta^{-2}, \ \zeta^4 + \zeta^{-4},$  $\zeta^{2^{130}} + \zeta^{-2^{130}}$  where  $\zeta$  is primitive 263rd root of 1. Weight is sum of coefficients. Squaring is rotation. Multi-squaring is rotation. Inversion by Fermat uses many multi-squarings.

But fast ECDL software uses polynomial basis: e.g., basis 1, x,  $x^2$ , ...,  $x^{130}$  of  $F_2[x]/(x^{131} + x^{13} + x^2 + x + 1)$ .

Many obvious disadvantages: more expensive squaring, multi-squaring, inversion; must convert to normal basis (e.g., with xor-largest) before computing weight.

But huge speedup in the 5 mults: polynomial multiplication uses Karatsuba etc.; reduction is very fast. How slow is normal-basis mult?

Type-1 normal basis of  $F_{2^n}$ , where 2 has order  $n \mod n + 1$ , is a permutation of

$$\zeta,\zeta^2,\ldots,\zeta^n$$
  
in  ${f F}_2[\zeta]/(\zeta^{n+1}-1).$ 

M(n) operations to multiply, obtaining coefficients of  $\zeta^2, \zeta^3, \ldots, \zeta^{2n}$ .

2n - 1 operations to reduce  $\zeta^2, \zeta^3, \ldots, \zeta^{2n}$ to  $\zeta, \zeta^2, \ldots, \zeta^n$ .

Alternative: M(n+1) + nfor redundant  $1, \zeta, \ldots, \zeta^n$ .

Type-2 normal basis of  $\mathbf{F}_{2^n}$ , where 2 has order  $n \mod 2n + 1$ , is a permutation of  $\zeta + \zeta^{-1}, \ \zeta^2 + \zeta^{-2},$  $\zeta^3+\zeta^{-3},\ldots,\,\zeta^n+\zeta^{-n}$ in  $\mathbf{F}_2[\zeta]/(\zeta^{2n+1}-1)$ . 2000 Gao-von zur Gathen-Panario–Shoup: 2M(n) + O(n) operations to multiply on this basis.

Polynomial basis of  $\mathbf{F}_{2^n}$ is about twice as fast. 2007 von zur Gathen– Shokrollahi–Shokrollahi:  $M(n) + O(n \lg n)$  operations to multiply on this basis.

2009 Bernstein:

improved variant of algorithm sets Core 2 speed records for the ECC2K-130 attack.

2009 Schwabe: also Cell speed records.

2009 Bernstein–Lange: mix normal bases with polynomial bases and speed up reduction. vzG–S–S in a nutshell:

Write 
$$N_j = \zeta^j + \zeta^{-j}$$
  
and  $P_j = (\zeta + \zeta^{-1})^j$ .

lf

 $f_0 + f_1 P_1 + f_2 P_2 + f_3 P_3 =$   $g_0 + g_1 N_1 + g_2 N_2 + g_3 N_3 \text{ and}$   $f_4 + f_5 P_1 + f_6 P_2 + f_7 P_3 =$   $g_4 + g_5 N_1 + g_6 N_2 + g_7 N_3$ then

 $\begin{aligned} f_0 + f_1 P_1 + f_2 P_2 + f_3 P_3 + \\ f_4 P_4 + f_5 P_5 + f_6 P_6 + f_7 P_7 = \\ g_0 + (g_1 + g_7) N_1 + \\ (g_2 + g_6) N_2 + (g_3 + g_5) N_3 + \\ g_4 N_4 + g_5 N_5 + g_6 N_6 + g_7 N_7. \end{aligned}$ 

Proof: e.g.,  $(\zeta + \zeta^{-1})^4 (\zeta^3 + \zeta^{-3})$   $= \zeta^7 + \zeta^{-7} + \zeta^1 + \zeta^{-1}$ so  $P_4 N_3 = N_7 + N_1$ . Q.E.D.

So size-8 conversion from 1,  $P_1$ ,  $P_2$ , ...,  $P_7$ to 1,  $N_1$ ,  $N_2$ , ...,  $N_7$ can be done with two size-4 conversions and three additions.

Apply same idea recursively: size-n conversion uses  $\leq 1 + 0.5n(\lg n - 2)$  additions.

Inverse has same cost.

To multiply f, g on basis  $N_1, N_2, \ldots, N_n$ : Convert to 1,  $P_1$ , ...,  $P_n$ ; cost  $\approx 0.5 n \lg n$ , twice. Polynomial product; M(n+1). Convert 1,  $P_1, ..., P_{2n}$ to 1,  $N_1$ , ...,  $N_{2n}$ ;  $\cot x \approx n \lg n$ . Eliminate  $N_{n+1}, \ldots, N_{2n}$ 

using  $N_{2n+1-j} = N_j$ ; cost n. Eliminate 1 using  $1 + N_1 + \cdots + N_n = 0$ ; cost n. Some new improvements:

1. For 1,  $P_1$ , ...,  $P_n$ : coefficient of 1 is 0. Cost M(n) instead of M(n + 1).

2. For 1,  $P_1$ , ...,  $P_{2n}$ : coefficients of 1,  $P_1$  are 0. Reduces cost by n + 1.

3. If mults share input, reuse input conversion. Reduces cost by  $\approx 0.5n \lg n$ .

4. If output is an input, use different reduction strategy to skip a first-half conversion. Reduces cost by  $\approx 0.5n \lg n$ .

Can represent field element using basis  $P_1, \ldots, P_n$ for fast multiplication; or basis  $N_1, \ldots, N_n$ for fast multi-squarings; or both. Can vary this choice across field-element variables. Can also vary over time.

Approximate costs:

$$P \rightarrow N$$
: 0.5 $n \lg n$ .

 $N \rightarrow P$ : 0.5 $n \lg n$ .

 $P \times P \rightarrow N$ :  $M(n) + n \lg n$ .

 $P \times P \rightarrow P$ :  $M(n) + n \lg n$ .  $N^{2^j} \rightarrow N$ : 0.