

Fast arithmetic on elliptic curves

D. J. Bernstein

University of Illinois at Chicago

EC point counting

1983 (published 1985) Schoof:
Algorithm to count points on
elliptic curves over finite fields.

Input: prime power q ; $a, b \in \mathbf{F}_q$
such that $6(4a^3 + 27b^2) \neq 0$.

Output: $\#\{(x, y) \in \mathbf{F}_q \times \mathbf{F}_q : y^2 = x^3 + ax + b\} + 1$;
i.e., $\#E(\mathbf{F}_q)$ where E is the
elliptic curve $y^2 = x^3 + ax + b$.

Time: $(\log q)^{O(1)}$.

How? See this afternoon's talk.

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Let q be a prime power; $a, b \in \mathbf{F}_q$
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$$N_q = \#\{(x, y) \in \mathbf{F}_q \times \mathbf{F}_q : y^2 = x^3 + ax + b\} + 1;$$

$N_q \approx \#E(\mathbf{F}_q)$ where E is the
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$$N_q = \#E(\mathbf{F}_q) + O(\log q).$$

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Representations

Cryptographic applications of
elliptic curves.

Given a point P on an elliptic curve, division points are hard to compute.

“in 26 lines”

but can be done.

“It appears that the representation of integers in the form of sums of squares is a special case of the representation of integers in the form of sums of squares of linear forms in the variables x_1, \dots, x_n .”

Each prime p is represented by a unique triple (a, b, c) (up to the order of the variables).

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Representing curve points

Crypto 1985, Miller, “Use
elliptic curves in cryptography”

Given $n \in \mathbf{Z}$, $P \in E(\mathbf{F}_q)$,
division-polynomial recurrence
computes $nP \in E(\mathbf{F}_q)$

“in $26 \log_2 n$ multiplications
but can do better!

“It appears to be best to
represent the points on the curve
in the following form:

Each point is represented by a
triple (x, y, z) which corresponds
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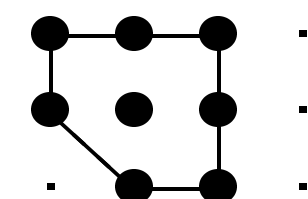
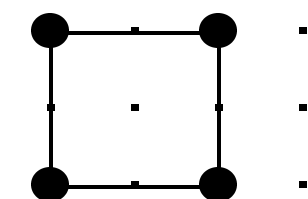
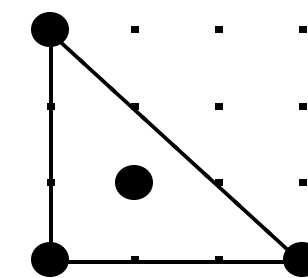
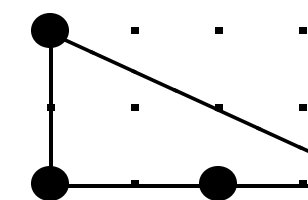
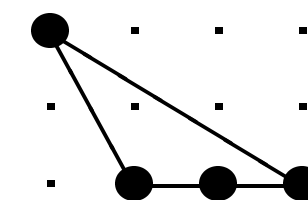
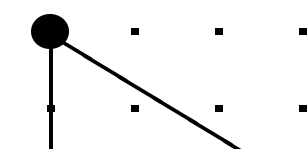
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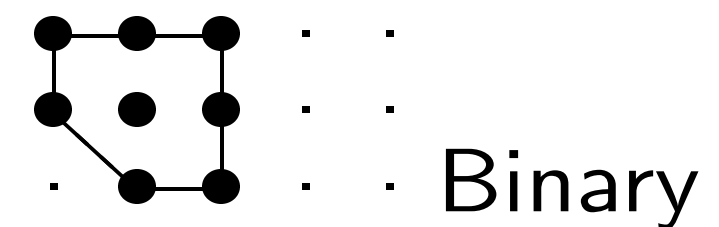
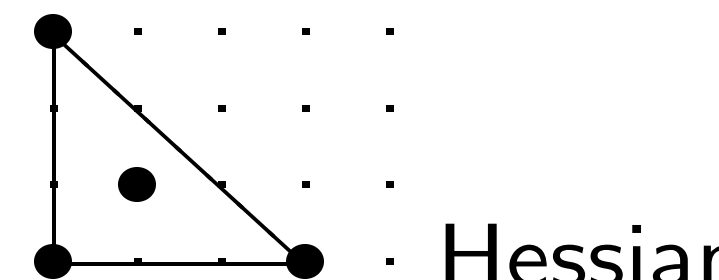
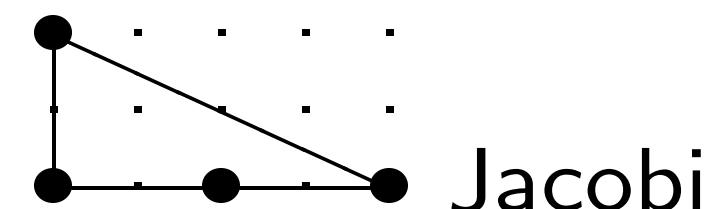
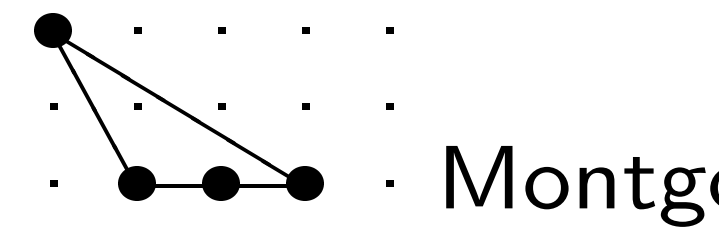
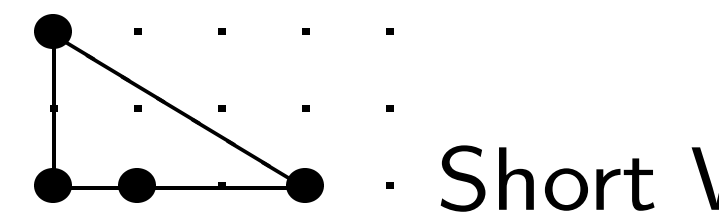
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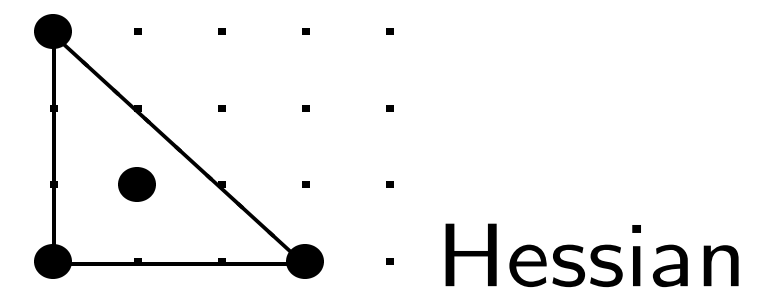
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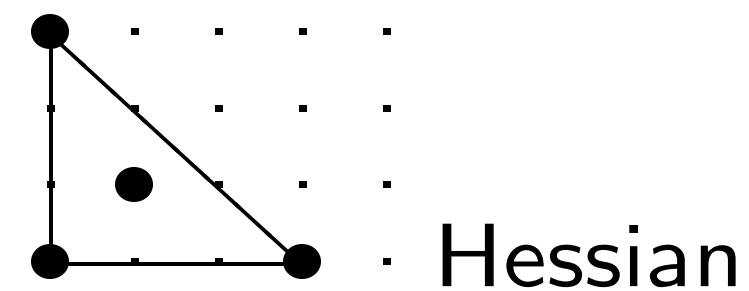
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Jacobi quartic: $y^2 = x^4 + 2ax^2 + 1.$

Hessian: $x^3 + y^3 + 1 = 3dxy.$

Some Newton polygons



preferable to use
of elliptic curves
in low-dimensional spaces,
otherwise the number of
operations and operations is
increasing. This limits us ... to
models of elliptic curves.”

Weierstrass:

$$y^2 = x^3 + ax + b.$$

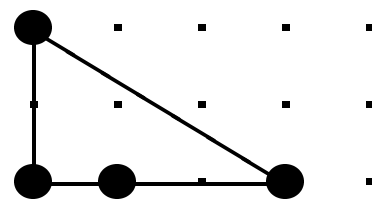
intersection:

$$x^2 = 1, as^2 + d^2 = 1.$$

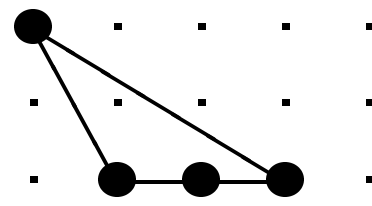
quartic: $y^2 = x^4 + 2ax^2 + 1.$

ternary: $x^3 + y^3 + 1 = 3dxy.$

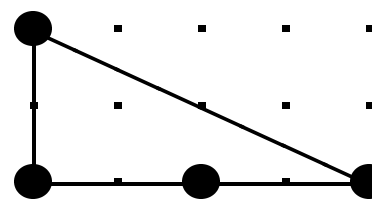
Some Newton polygons



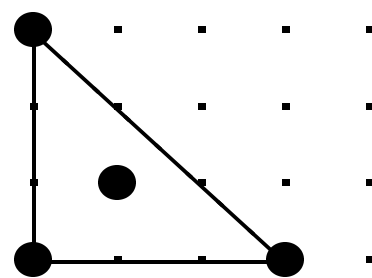
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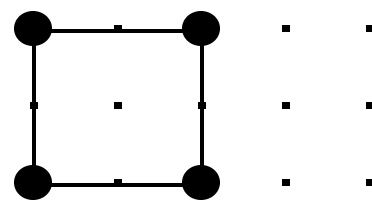
Montgomery



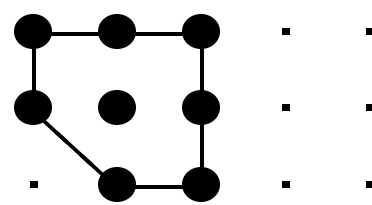
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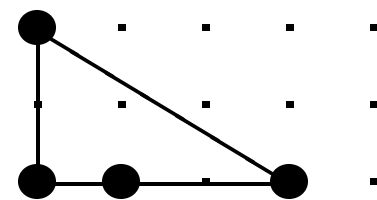
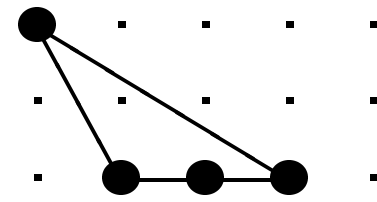
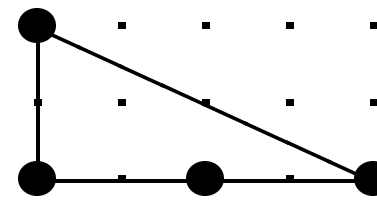
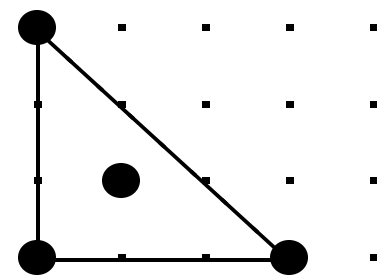
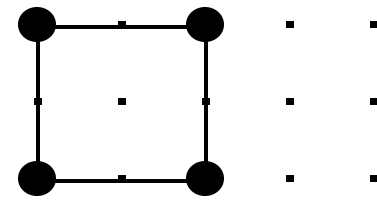
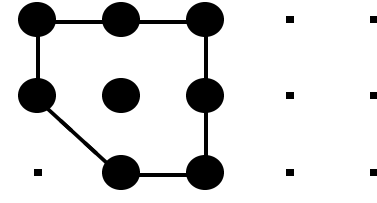
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Some Newton polygons

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Short Weierstrass
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Montgomery
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Jacobi quartic
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Hessian
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Edwards
- 
Binary Edwards

Optimizing Jacob

For “traditional”
 on $y^2 = x^3 + ax$
 1986 Chudnovsky
 state explicit form
 10M for DBL; 16

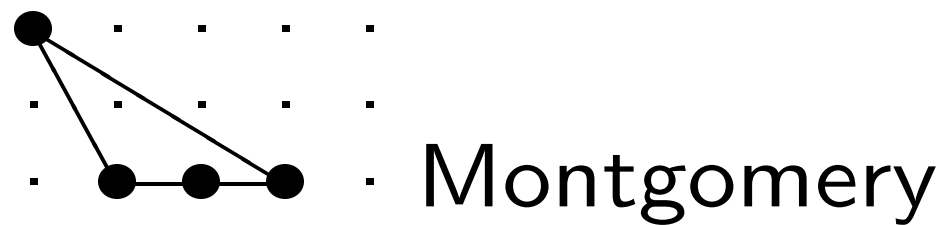
Consequence:
 $\approx \left(10 \lg n + 16 \right)$
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Notation: $\lg = \log$

Some Newton polygons



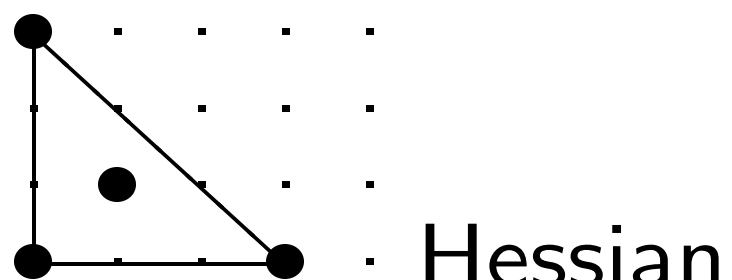
Short Weierstrass



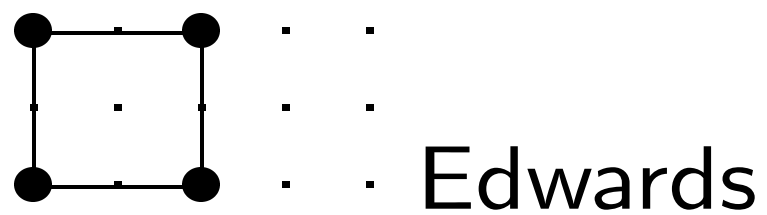
Montgomery



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Edwards



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Optimizing Jacobian coord

For “traditional” $(X/Z^2, Y/Z^3)$ on $y^2 = x^3 + ax + b$:

1986 Chudnovsky–Chudnovsky state explicit formulas using 10M for DBL; 16M for AD

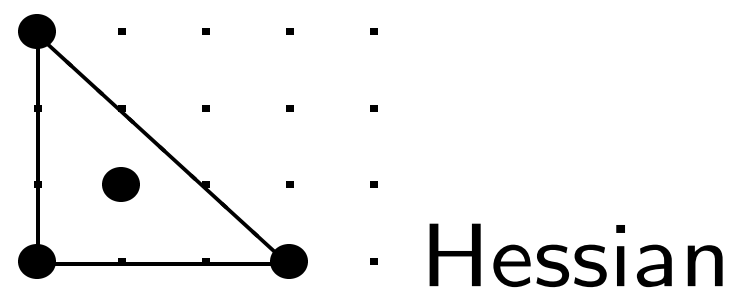
Consequence:

$$\approx \left(10 \lg n + 16 \frac{\lg n}{\lg \lg n} \right) \mathbf{M}$$

to compute $n, P \mapsto nP$ using sliding-windows method of scalar multiplication.

Notation: $\lg = \log_2$.

Some Newton polygons



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Squaring

Here are

$$S =$$

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$$T = M^2 - 2S;$$

$$X_3 = T;$$

$$Y_3 = M \cdot (S -$$

$$Z_3 = 2Y_1 \cdot Z_1.$$

Total cost $3\mathbf{M} +$

\mathbf{S} is the cost of s

\mathbf{D} is the cost of r

The squarings pr

$$X_1^2, Y_1^2, Y_1^4, Z_1^2, Z_1^3$$

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Notation: $\lg = \log_2$.

Squaring is faster than \mathbf{M} .

Here are the DBL formulas

$$S = 4X_1 \cdot Y_1^2;$$

$$M = 3X_1^2 + aZ_1^4;$$

$$T = M^2 - 2S;$$

$$X_3 = T;$$

$$Y_3 = M \cdot (S - T) - 8Y_1^4$$

$$Z_3 = 2Y_1 \cdot Z_1.$$

Total cost $3\mathbf{M} + 6\mathbf{S} + 1\mathbf{D}$

\mathbf{S} is the cost of squaring in

\mathbf{D} is the cost of multiplying

The squarings produce

$$X_1^2, Y_1^2, Y_1^4, Z_1^2, Z_1^4, M^2.$$

Optimizing Jacobian coordinates

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S is the cost of squaring in \mathbf{F}_q ,
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The squarings produce

$$X_1^2, Y_1^2, Y_1^4, Z_1^2, Z_1^4, M^2.$$

Using Jacobian coordinates

“traditional” $(X/Z^2, Y/Z^3)$

$$= x^3 + ax + b:$$

Chudnovsky–Chudnovsky

explicit formulas using

for DBL; $16\mathbf{M}$ for ADD.

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$$\left(\frac{\lg n}{\lg \lg n} \right) \mathbf{M}$$

$\mapsto nP$

Wahlström's method

of point addition.

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Most ECC standards use elliptic curves that make

Curve-choice advantage

1986 Chudnovsky

Can eliminate the

by choosing curve

But "it is even simpler

to choose curve with

If $a = -3$ then M

$$= 3(X_1 - Z_1^2) \cdot (X_1 + Z_1^2)$$

Replace $2\mathbf{S}$ with

Now DBL costs 4

Squaring is faster than **M**.

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Most ECC standards choose curves that make formulas

Curve-choice advice from 1986 Chudnovsky–Chudnov

Can eliminate the $1\mathbf{D}$ by choosing curve with $a =$

But “it is even smarter” to choose curve with $a =$

If $a = -3$ then $M = 3(X_1^2 - Z_1^2) = 3(X_1 - Z_1)(X_1 + Z_1)$

Replace $2\mathbf{S}$ with $1\mathbf{M}$.

Now DBL costs $4\mathbf{M} + 4\mathbf{S}$.

Squaring is faster than **M**.

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Replace **2S** with **1M**.

Now DBL costs **4M** + **4S**.

2001 Bernstein:

3M + **5S** for DBL

11M + **5S** for AD

How? Easy **S** –

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$(X_1 - Z_1^2) \cdot (X_1 + Z_1^2)$.

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 $U_1 = X_1 Z_2^2, U_2 =$
 $S_1 = Y_1 Z_2^3, S_2 =$
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1986 Chudnovsky
“We suggest to v
addition formulas
 (X, Y, Z, Z^2, Z^3)

Disadvantages:
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Advantages:
Save **2S + 2M** at
Save **1S** at start

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1986 Chudnovsky–Chudnov

“We suggest to write
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Disadvantages:

Allocate space for Z^2, Z^3 .

Pay $1\mathbf{S} + 1\mathbf{M}$ in ADD and

Advantages:

Save $2\mathbf{S} + 2\mathbf{M}$ at start of A

Save $1\mathbf{S}$ at start of DBL.

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Pay **1S** + **1M** in ADD and in DBL.

Advantages:

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Save **1S** at start of DBL.

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Formulas were already

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Idea for the ADD formulas,

we to scale X, Y, Z

eliminate divisions by 2.

ADD for $y^2 = x^3 + ax + b$:

$$U_1 = X_1 Z_2^2, U_2 = X_2 Z_1^2,$$

$$S_1 = Y_1 Z_2^3, S_2 = Y_2 Z_1^3,$$

many more computations.

1986 Chudnovsky–Chudnovsky:

“We suggest to write

addition formulas involving

(X, Y, Z, Z^2, Z^3) .”

Disadvantages:

Allocate space for Z^2, Z^3 .

Pay $1\mathbf{S} + 1\mathbf{M}$ in ADD and in DBL.

Advantages:

Save $2\mathbf{S} + 2\mathbf{M}$ at start of ADD.

Save $1\mathbf{S}$ at start of DBL.

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M tradeoff:

Computing $2Y_1 \cdot Z_1$,

$(Z_1)^2 - Y_1^2 - Z_1^2$.

are already

and Z_1^2 .

the ADD formulas,

the X, Y, Z

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Save $1S$ at start of DBL.

1998 Cohen–Miy

Store point as (X, Y, Z)

If point is input to

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No cost, aside from

If point is input to

reuse Z^2, Z^3 . Save

Best Jacobian space

including **S – M**

$3M + 5S$ for DBL

$11M + 5S$ for ADD

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1998 Cohen–Miyaji–Ono:

Store point as $(X : Y : Z)$.

If point is input to ADD, also cache Z^2 and Z^3 .

No cost, aside from space.

If point is input to another reuse Z^2, Z^3 . Save $1\mathbf{S} + 1\mathbf{M}$.

Best Jacobian speeds today

including $\mathbf{S} - \mathbf{M}$ tradeoffs:

$3\mathbf{M} + 5\mathbf{S}$ for DBL if $a = -3b$.

$11\mathbf{M} + 5\mathbf{S}$ for ADD.

$10\mathbf{M} + 4\mathbf{S}$ for reADD.

$7\mathbf{M} + 4\mathbf{S}$ for mADD (i.e. Z^2, Z^3 cached).

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$$U_1 Z_2^2, U_2 = X_2 Z_1^2,$$

$$V_1 Z_2^3, S_2 = Y_2 Z_1^3,$$

more computations.

Chudnovsky–Chudnovsky:

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(Z, Z^2, Z^3) ."

antages:

ce space for Z^2, Z^3 .

$5 + 1M$ in ADD and in DBL.

tages:

$5S + 2M$ at start of ADD.

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Store point as $(X : Y : Z)$.

If point is input to ADD,

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No cost, aside from space.

If point is input to another ADD,

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Best Jacobian speeds today,

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$7M + 4S$ for mADD (i.e. $Z_2 = 1$).

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$= Y_2 Z_1^3,$

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Compare to speed

curves $x^2 + y^2 =$

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(2007 Bernstein–

$3\mathbf{M} + 4\mathbf{S}$ for DB

$10\mathbf{M} + 1\mathbf{S} + 1\mathbf{D}$

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Inverted Edwards

(2007 Bernstein–

$3\mathbf{M} + 4\mathbf{S} + 1\mathbf{D}$ f

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Compare to speeds for Edv
curves $x^2 + y^2 = 1 + dx^2y$

in projective coordinates
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Inverted Edwards coordinates
(2007 Bernstein–Lange):

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Latest Edwards speed news

2008.12 Hisil–Wong–Carter

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Latest Edwards speed news:

2008.12 Hisil–Wong–Carter–Dawson.

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Latest Edwards speed news:

2008.12 Hisil–Wong–Carter–Dawson.

$$y^2 = x$$

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ive **1S + 1M!**

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Compare to speeds for Edwards

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3M + 4S for DBL.

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Inverted Edwards coordinates

(2007 Bernstein-Lange):

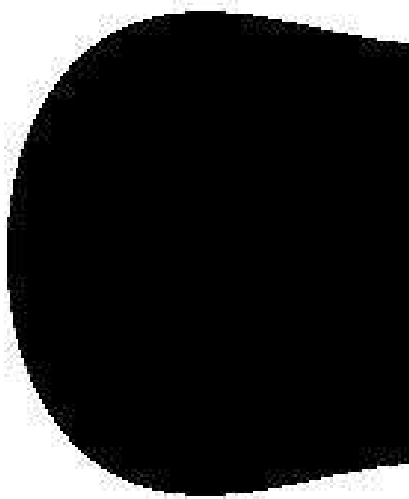
3M + 4S + 1D for DBL.

9M + 1S + 1D for ADD.

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Latest Edwards speed news:

2008.12 Hisil-Wong-Carter-Dawson.



$$y^2 = x^3 - 0.4x -$$

Compare to speeds for Edwards
curves $x^2 + y^2 = 1 + dx^2y^2$

in projective coordinates

(2007 Bernstein–Lange):

3M + 4S for DBL.

10M + 1S + 1D for ADD.

9M + 1S + 1D for mADD.

Inverted Edwards coordinates

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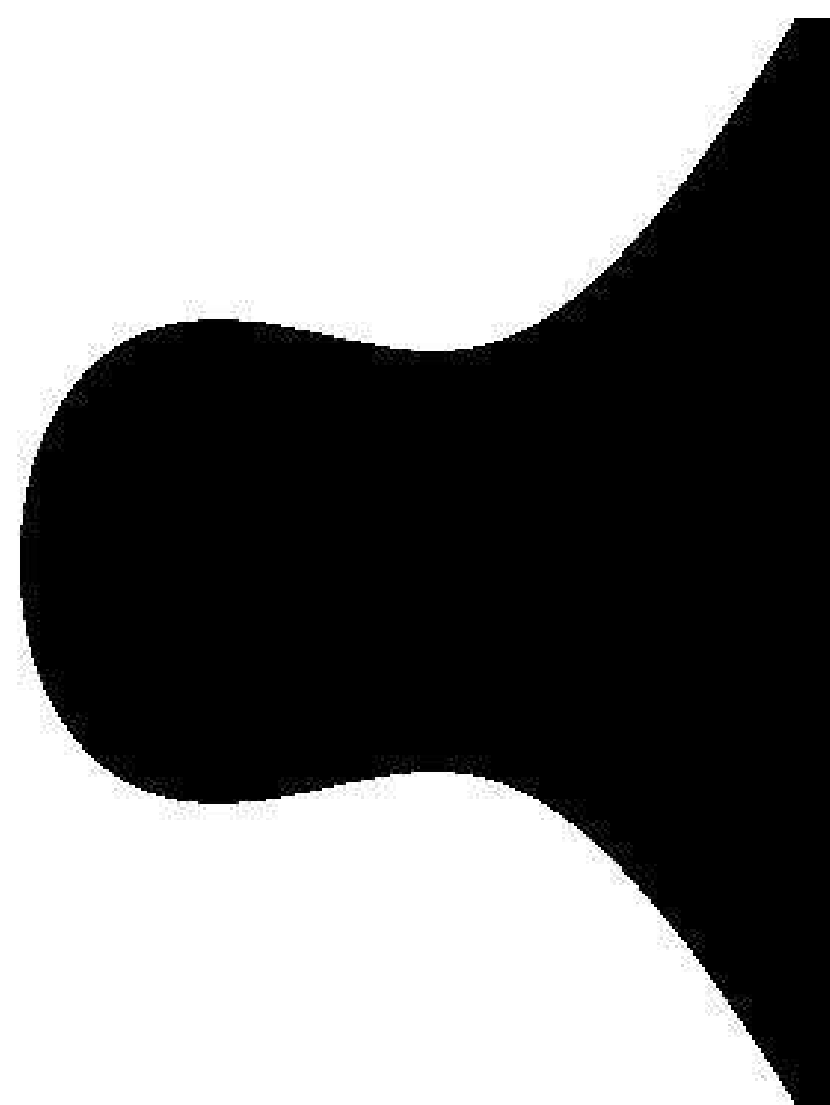
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9M + 1S + 1D for ADD.

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Latest Edwards speed news:

2008.12 Hisil–Wong–Carter–Dawson.



$$y^2 = x^3 - 0.4x + 0.7$$

Compare to speeds for Edwards
curves $x^2 + y^2 = 1 + dx^2y^2$

in projective coordinates

(2007 Bernstein–Lange):

3M + 4S for DBL.

10M + 1S + 1D for ADD.

9M + 1S + 1D for mADD.

Inverted Edwards coordinates

(2007 Bernstein–Lange):

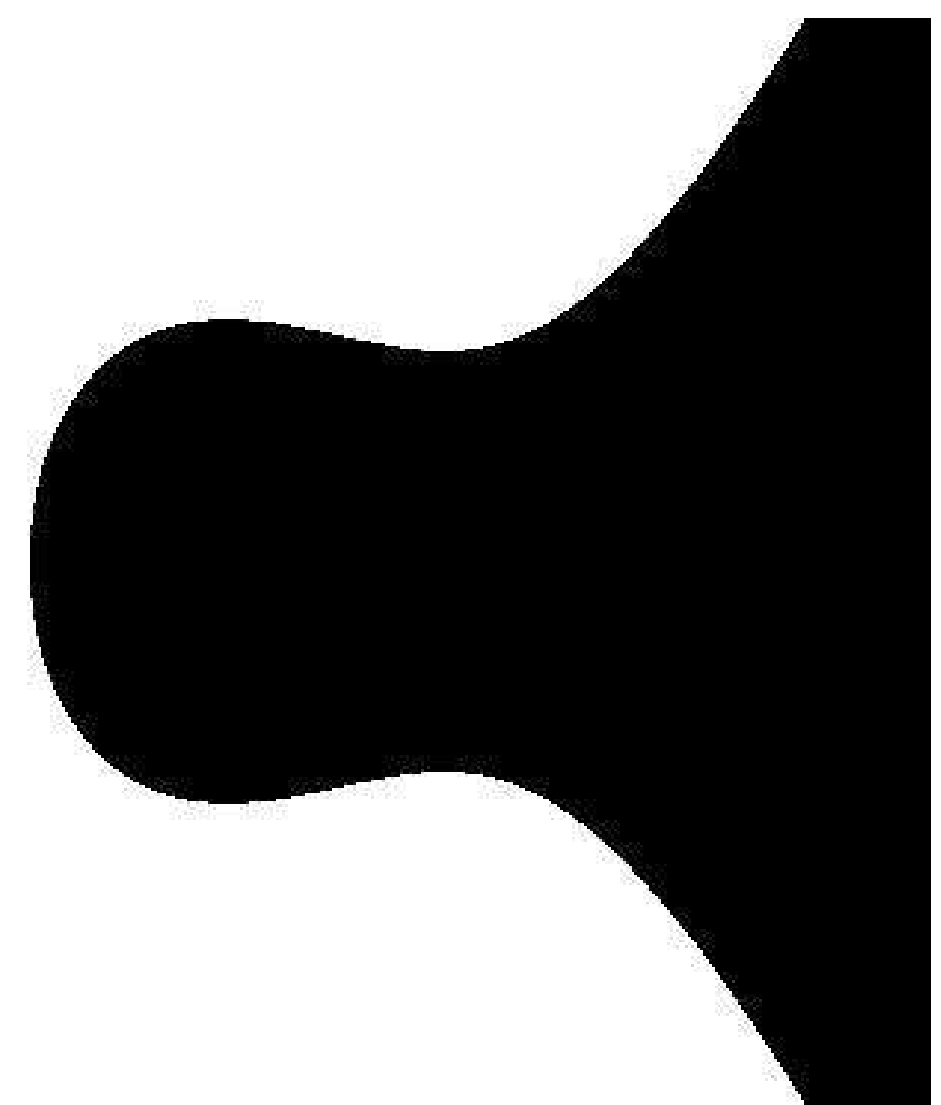
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Latest Edwards speed news:

2008.12 Hisil–Wong–Carter–Dawson.



$$y^2 = x^3 - 0.4x + 0.7$$

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$$x^2 + y^2 = 1 + dx^2y^2$$

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Bernstein–Lange):

4**S** for DBL.

1**S** + 1**D** for ADD.

1**S** + 1**D** for mADD.

d Edwards coordinates

Bernstein–Lange):

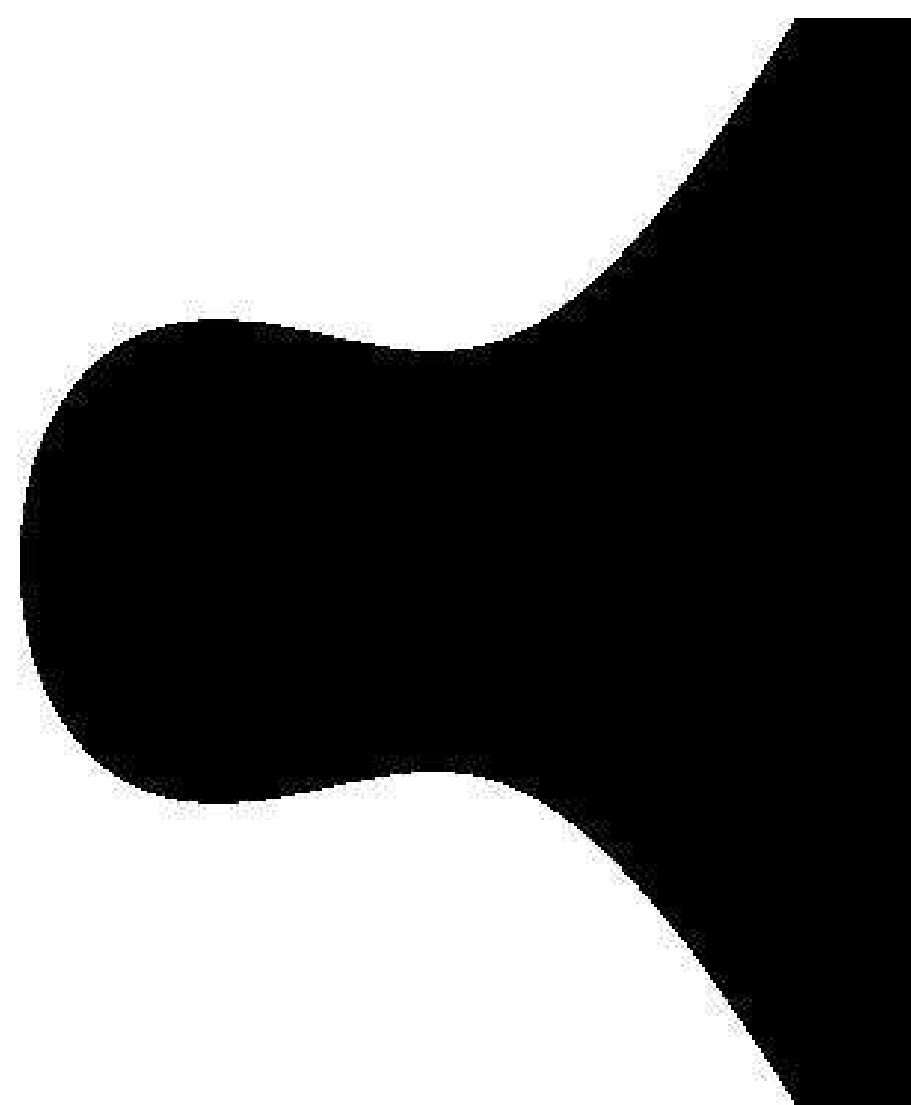
4**S** + 1**D** for DBL.

1**S** + 1**D** for ADD.

1**S** + 1**D** for mADD.

Edwards speed news:

2 Hisil–Wong–Carter–Dawson.



$$y^2 = x^3 - 0.4x + 0.7$$



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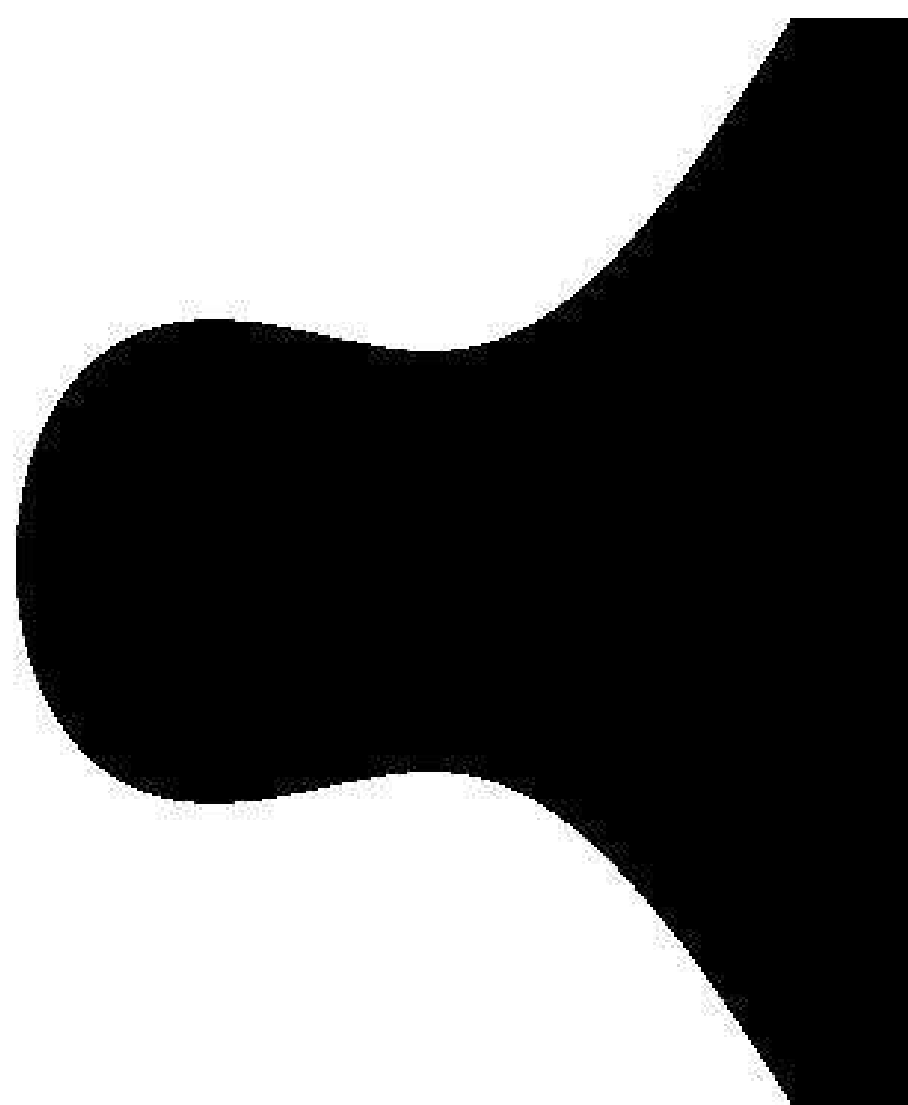
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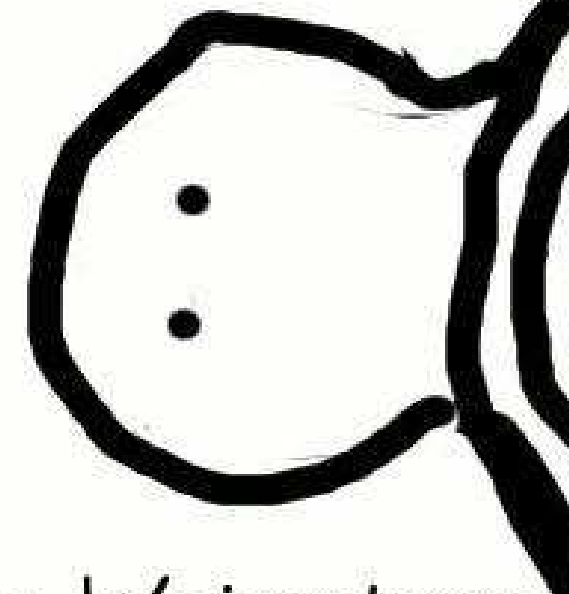
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$$y^2 = x^3 - 0.4x + 0.7$$



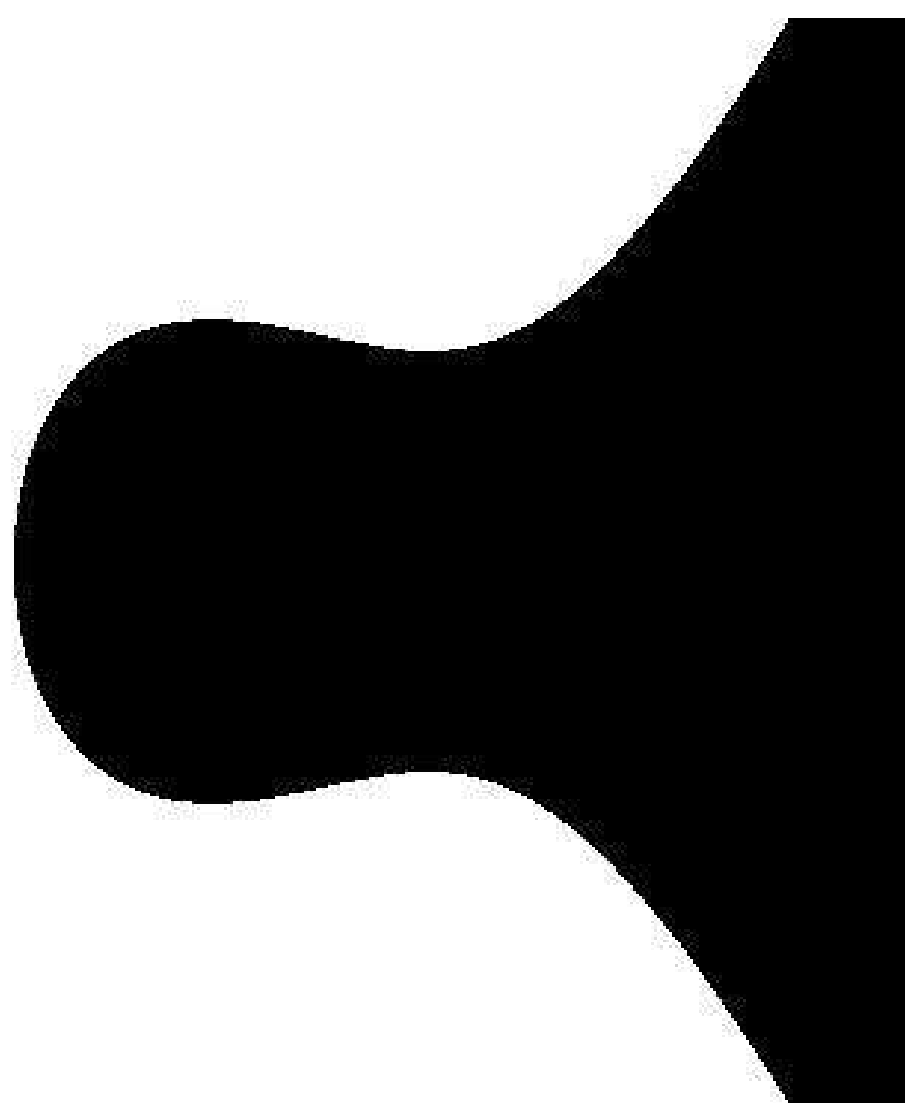
*The Weierstrass-
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(Thanks to Tanja
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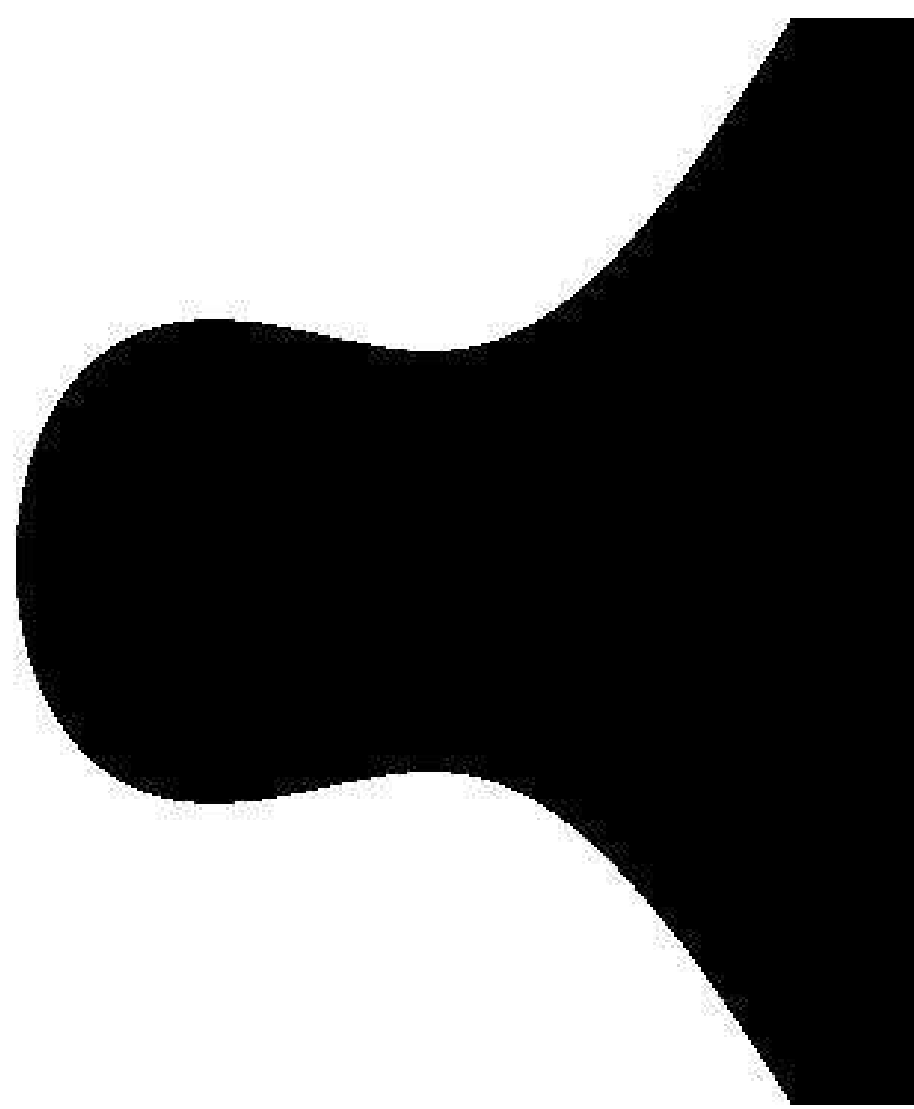


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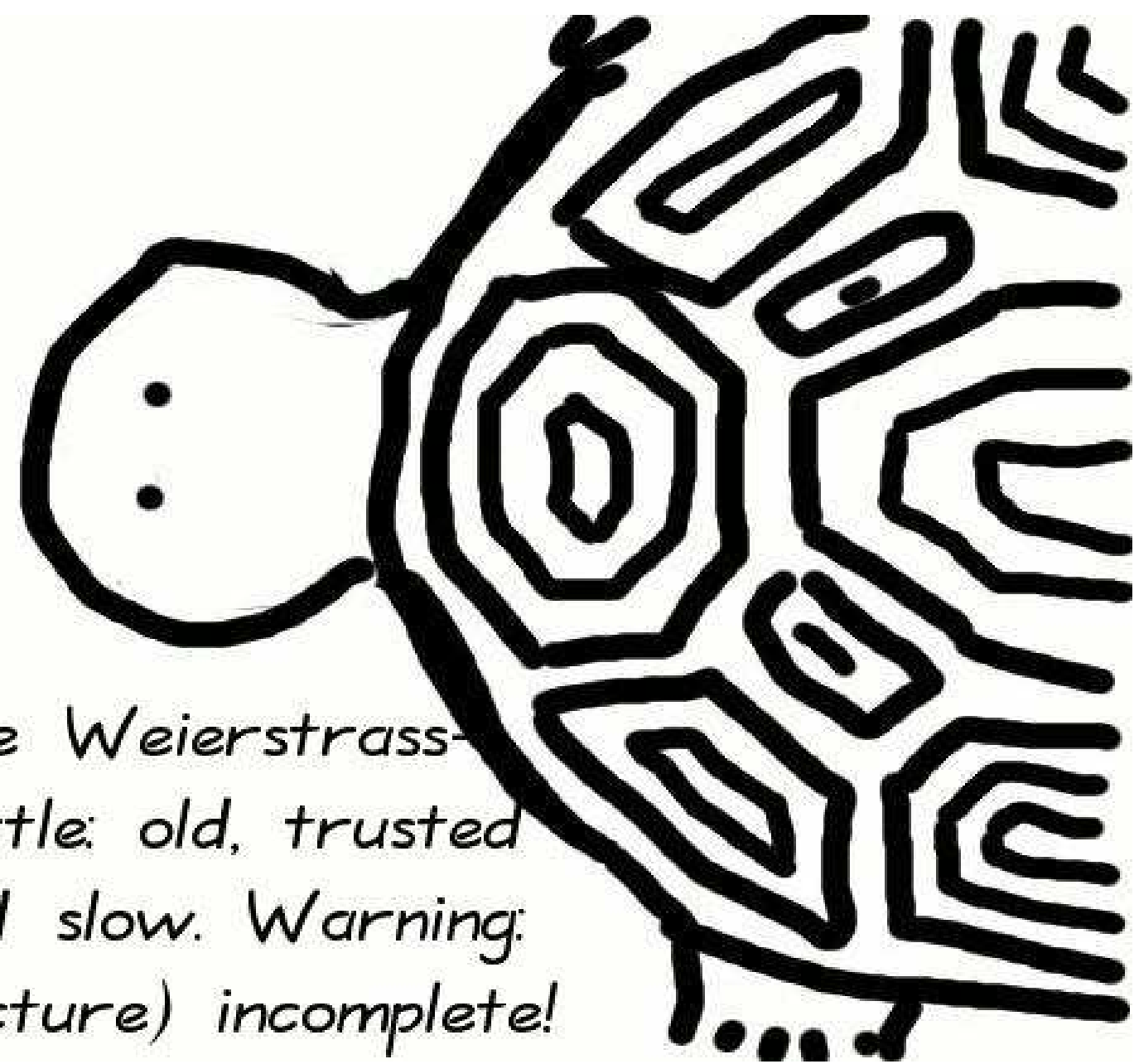


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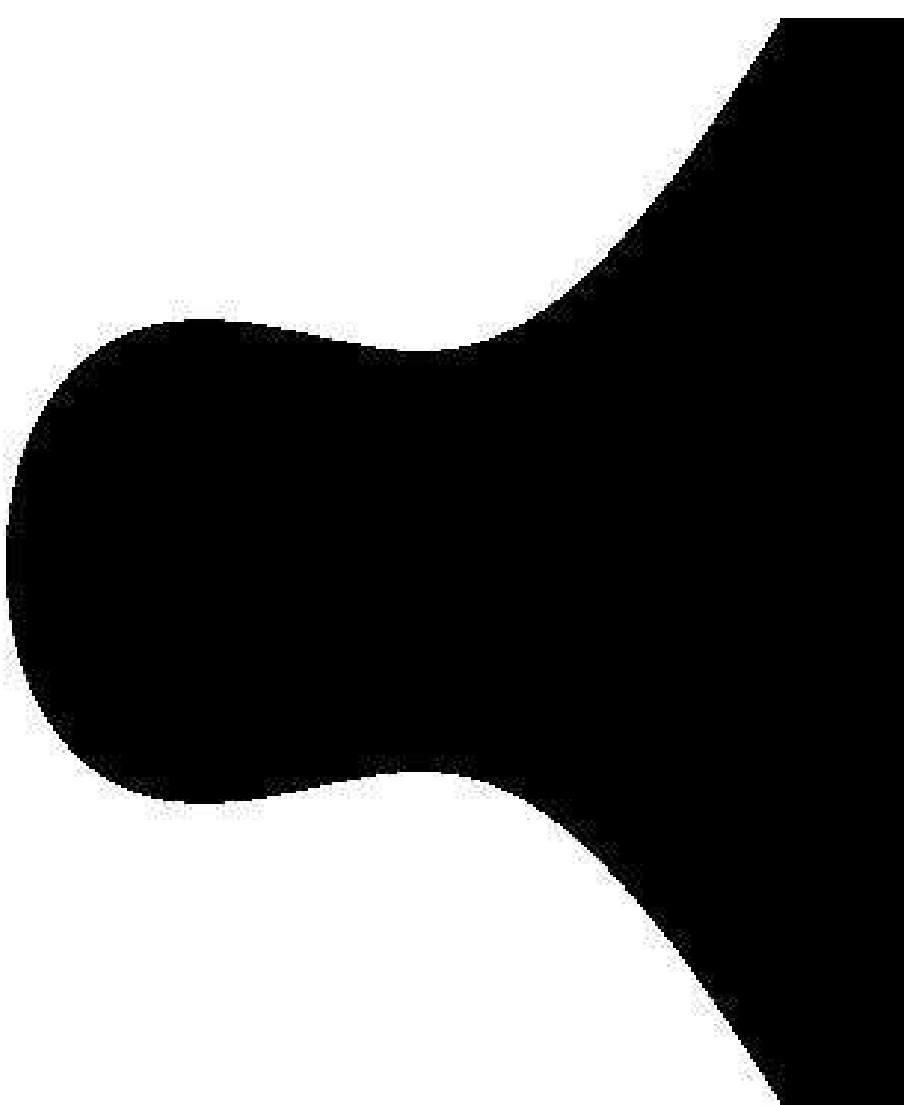


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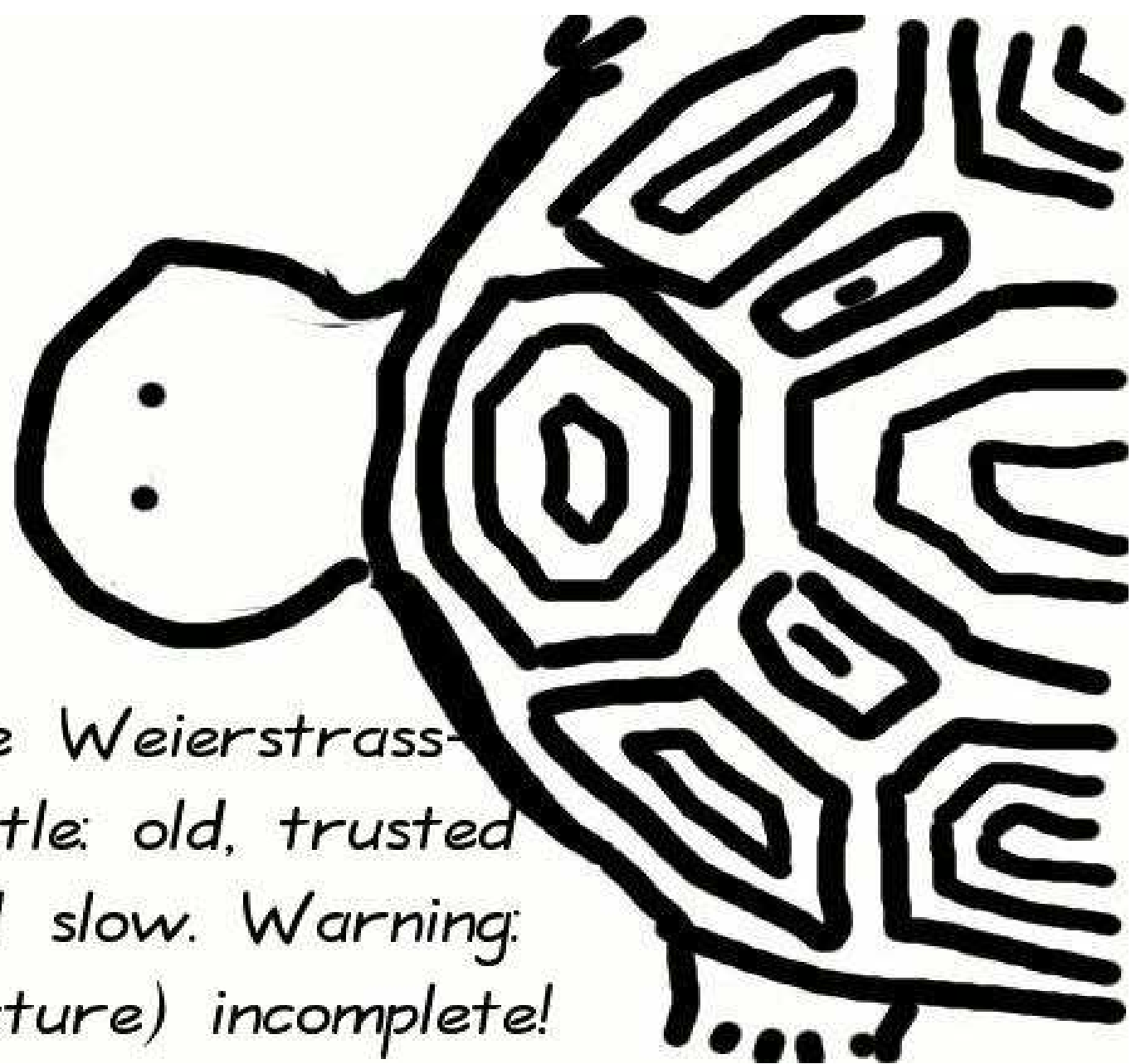


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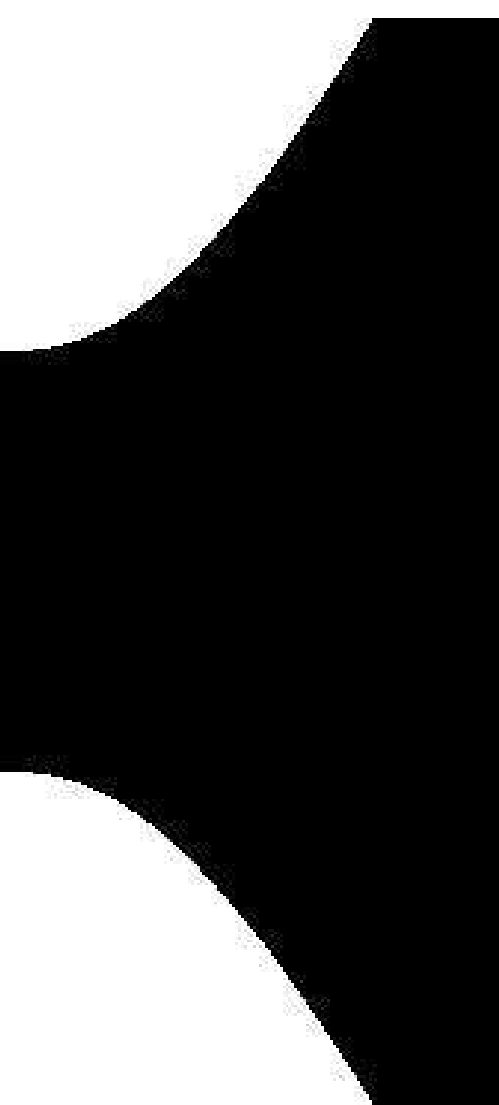
$$x^3 - 0.4x + 0.7$$



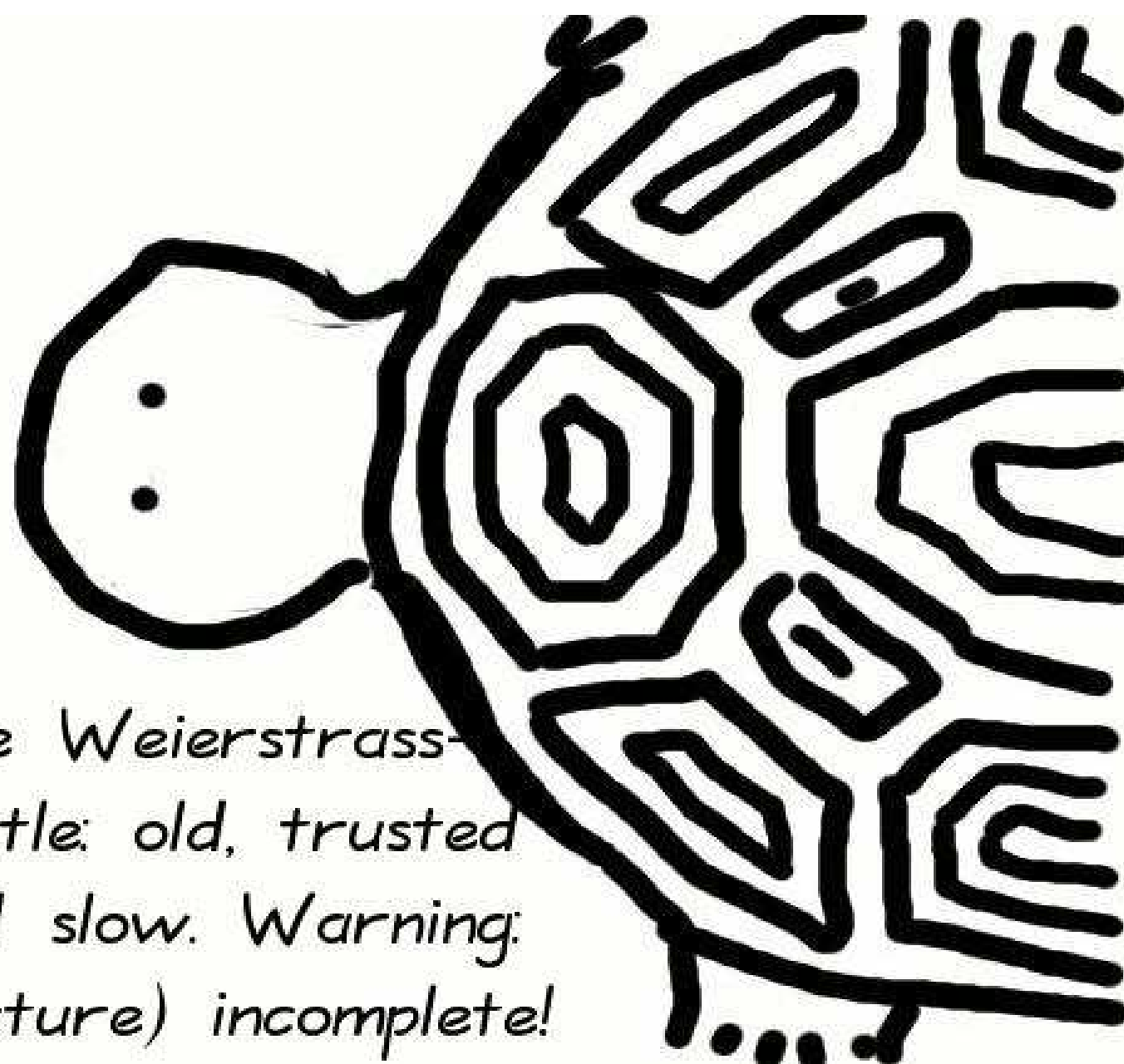
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$$x^2 + y^2$$

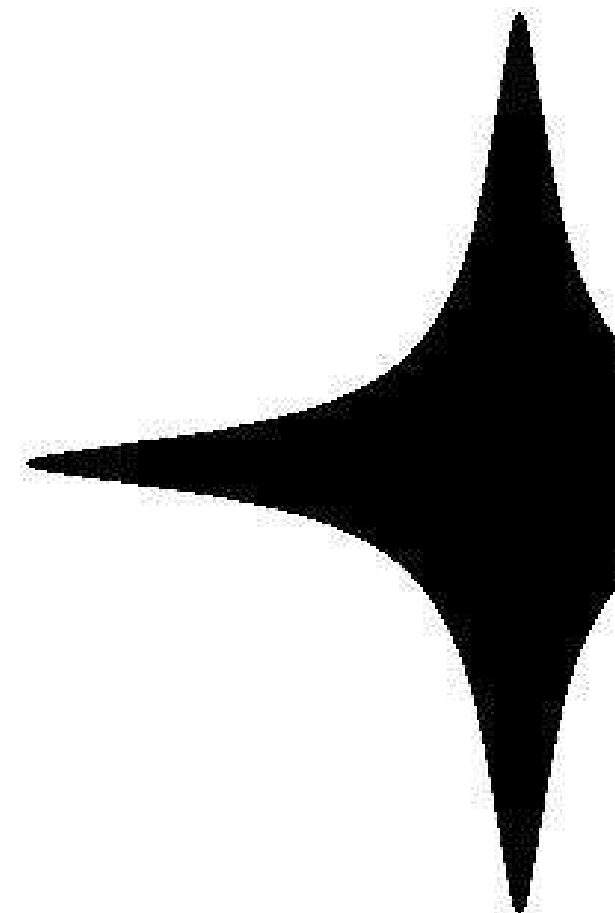


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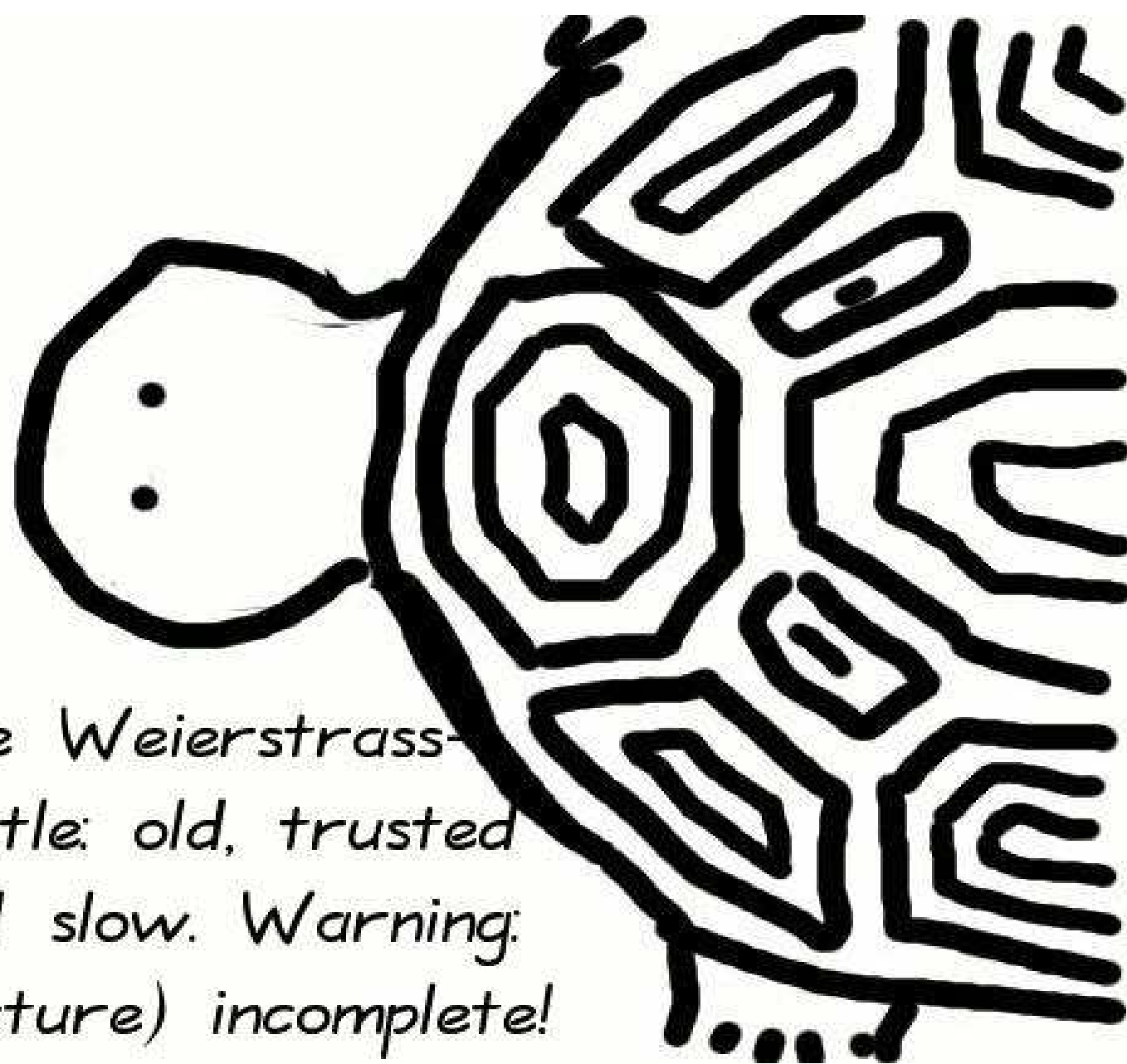


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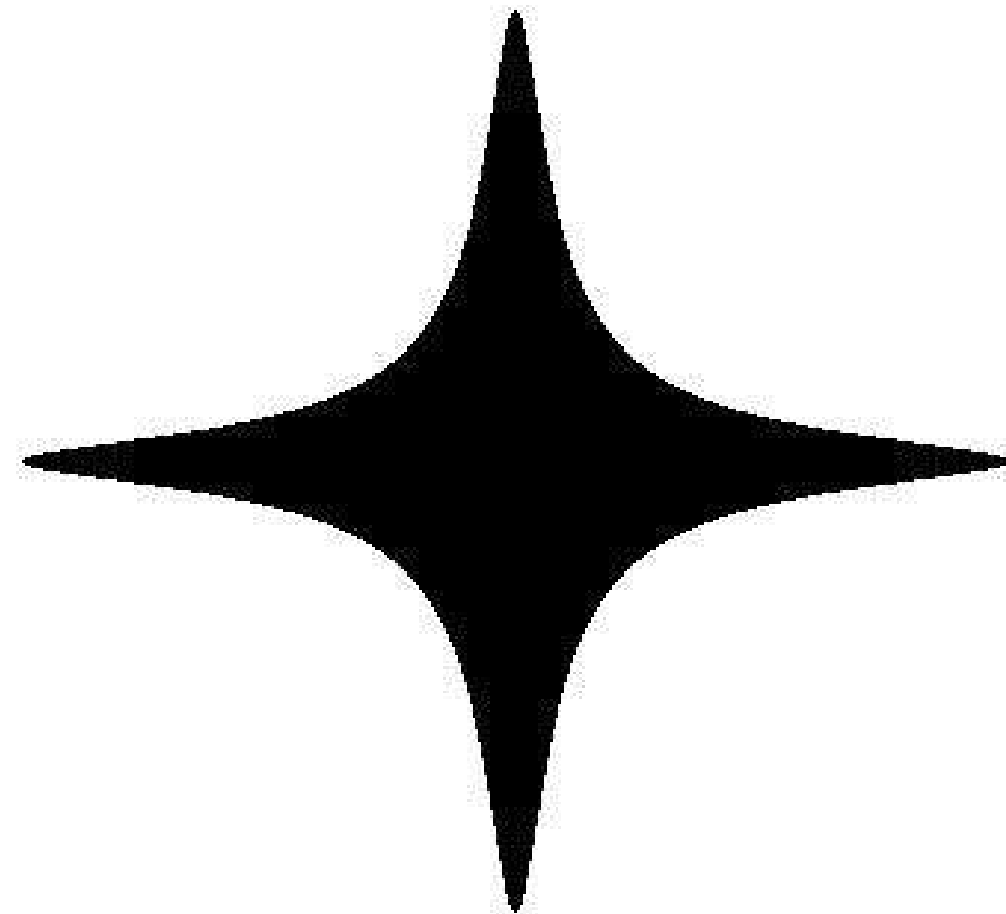


$$x^2 + y^2 = 1 - 30$$

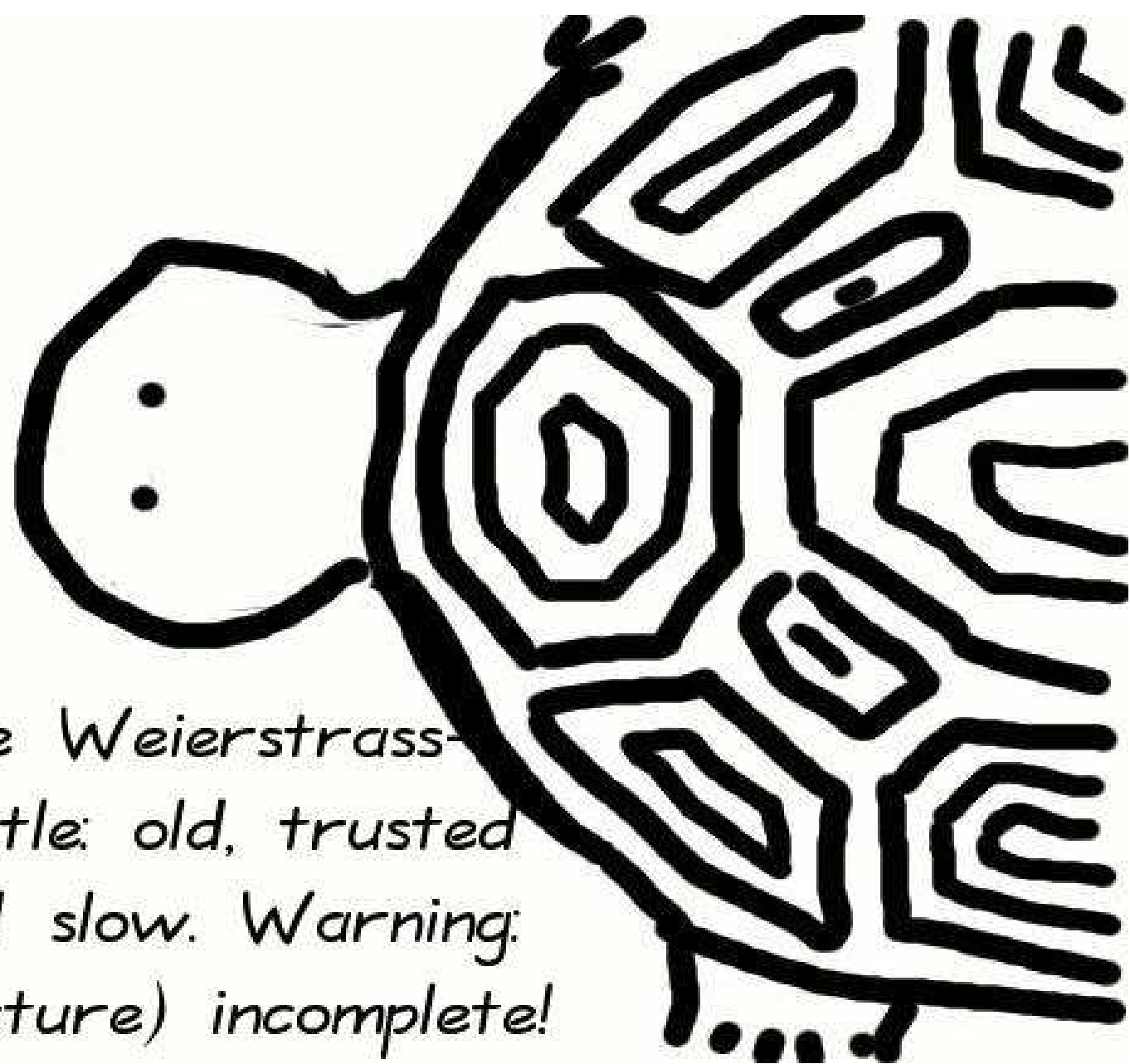


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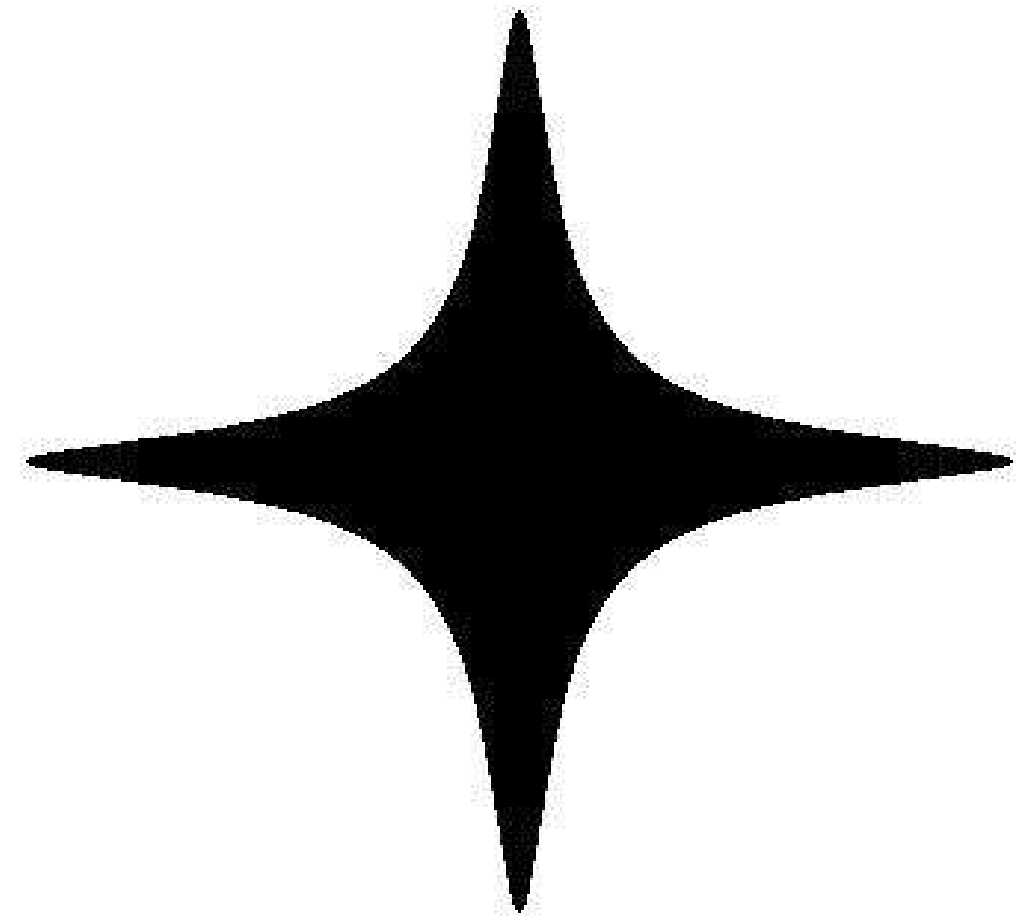


$$x^2 + y^2 = 1 - 300x^2y^2$$



The Weierstrass-turtle: old, trusted and slow. Warning: (picture) incomplete!

(Thanks to Tanja Lange for the pictures.)

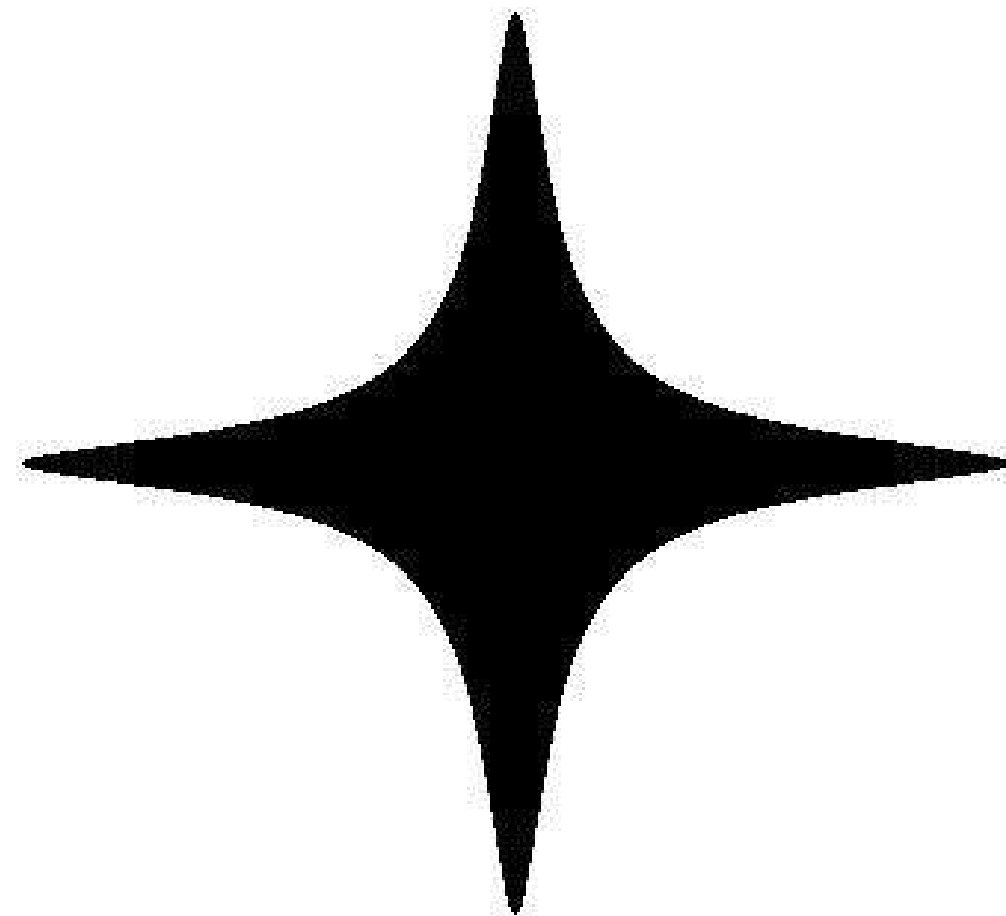


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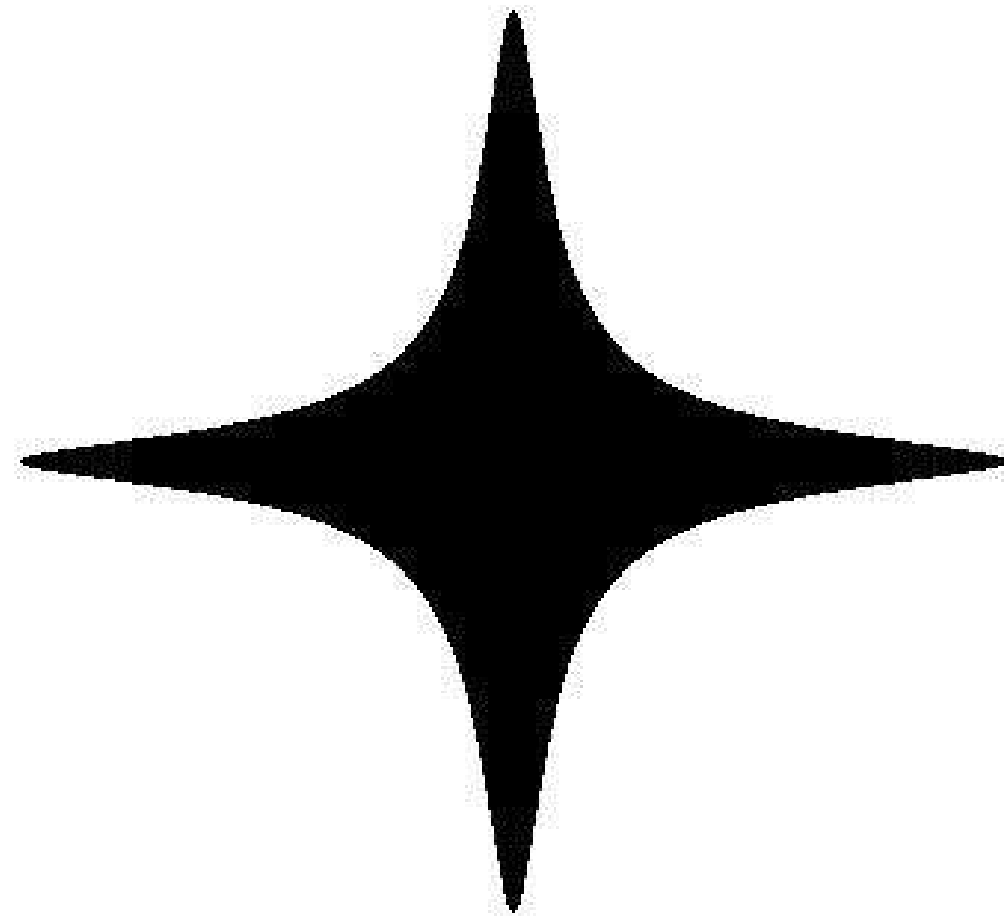


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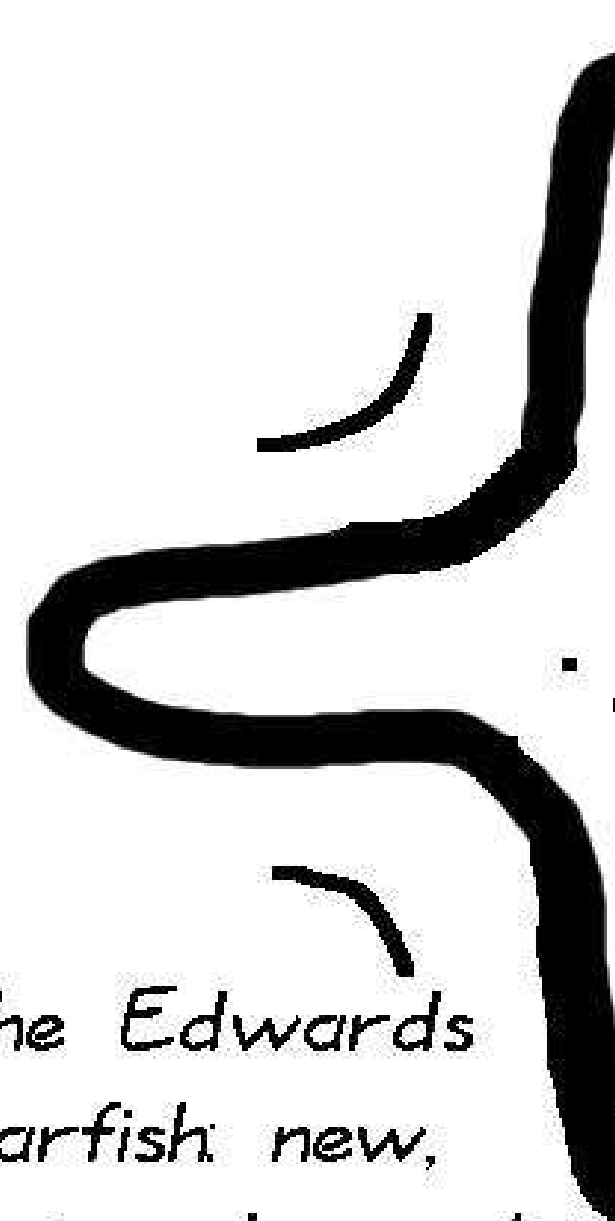
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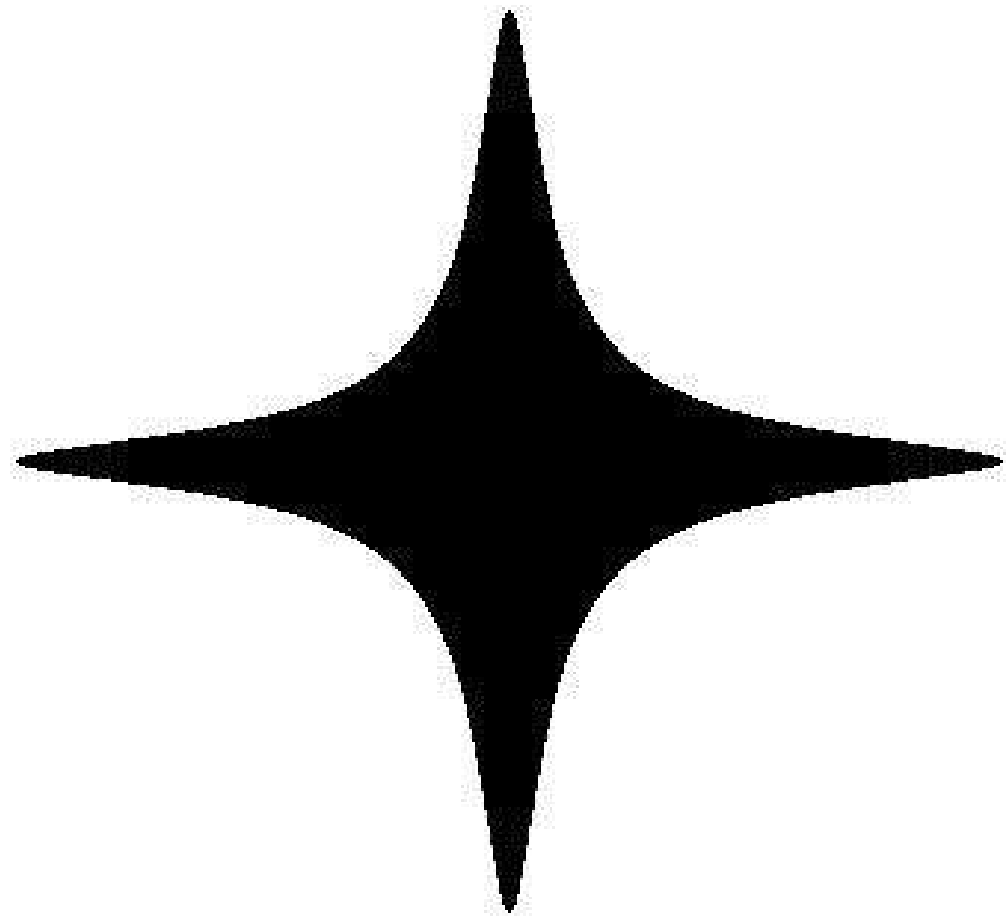
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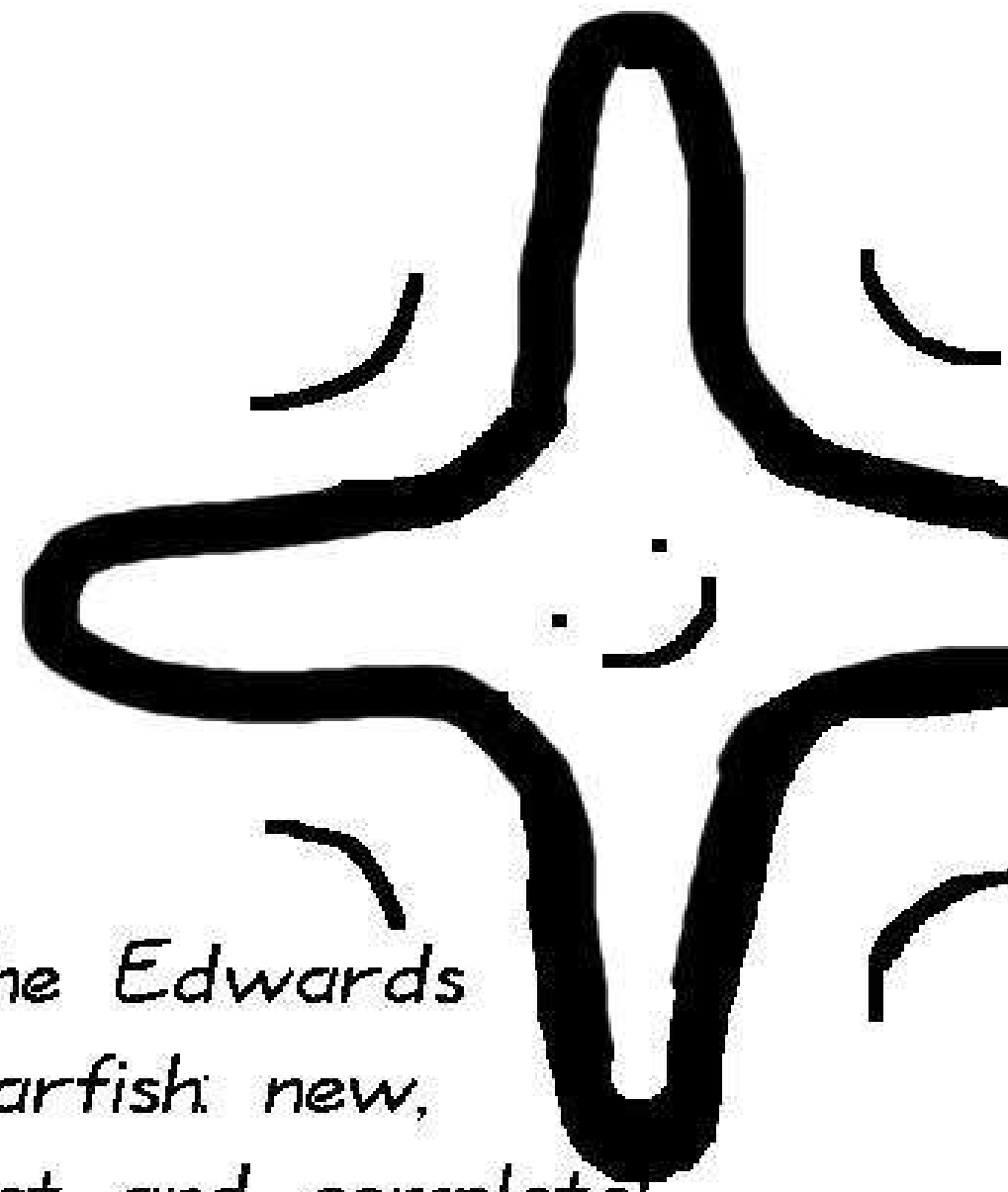
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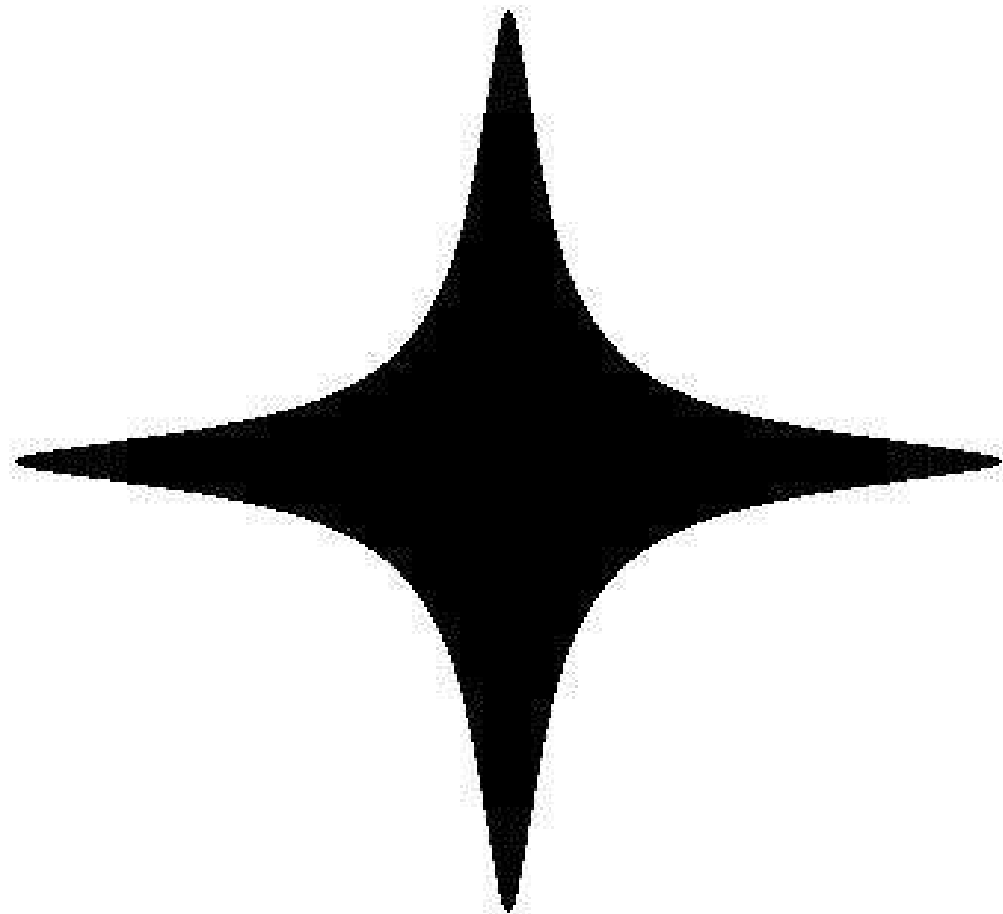
*The Edwards
starfish: new,
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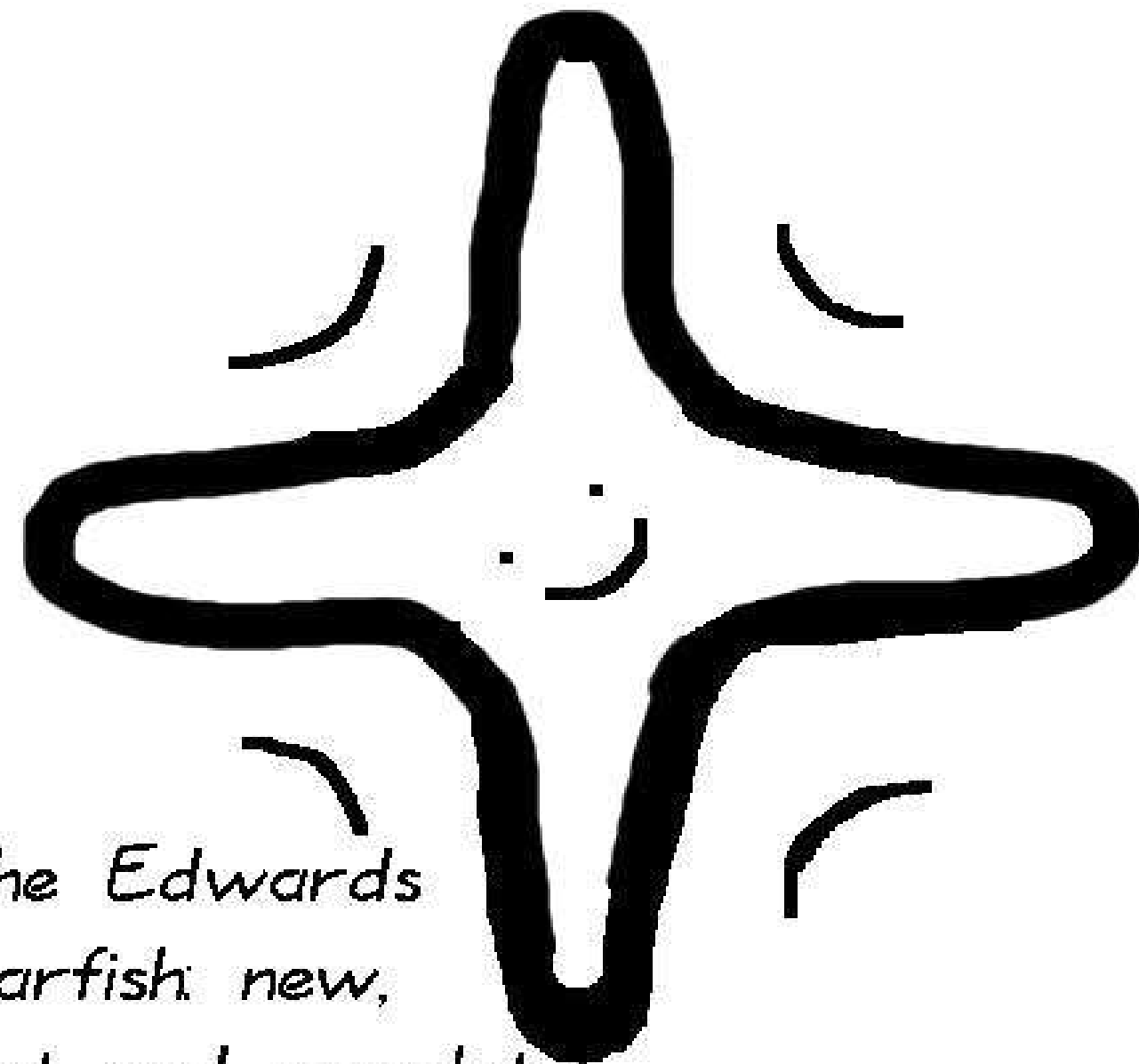
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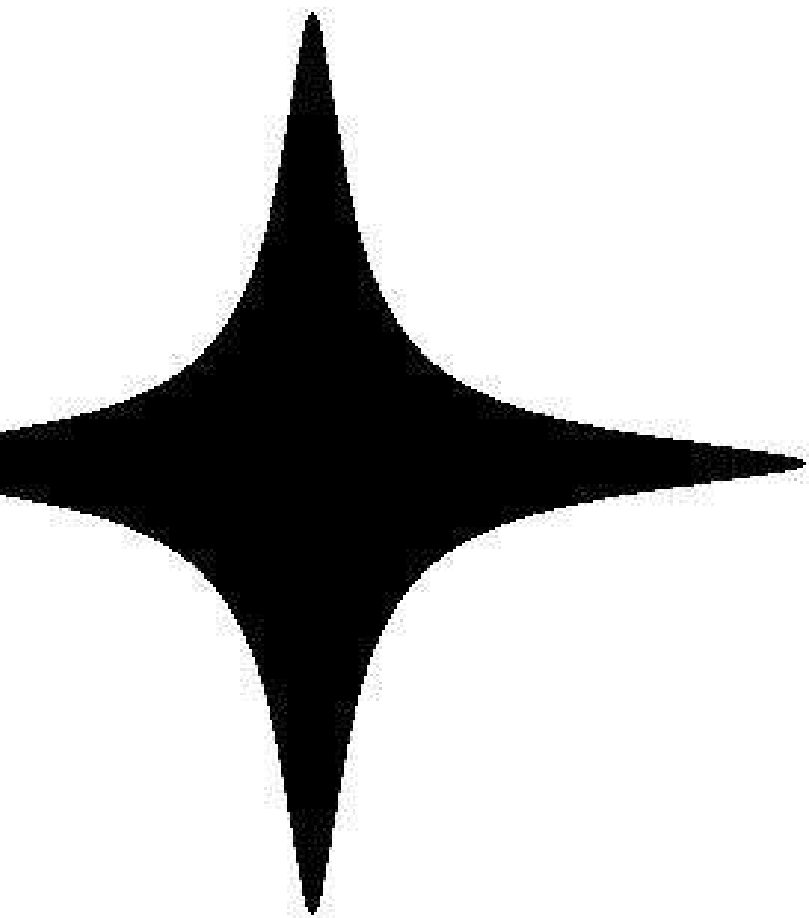
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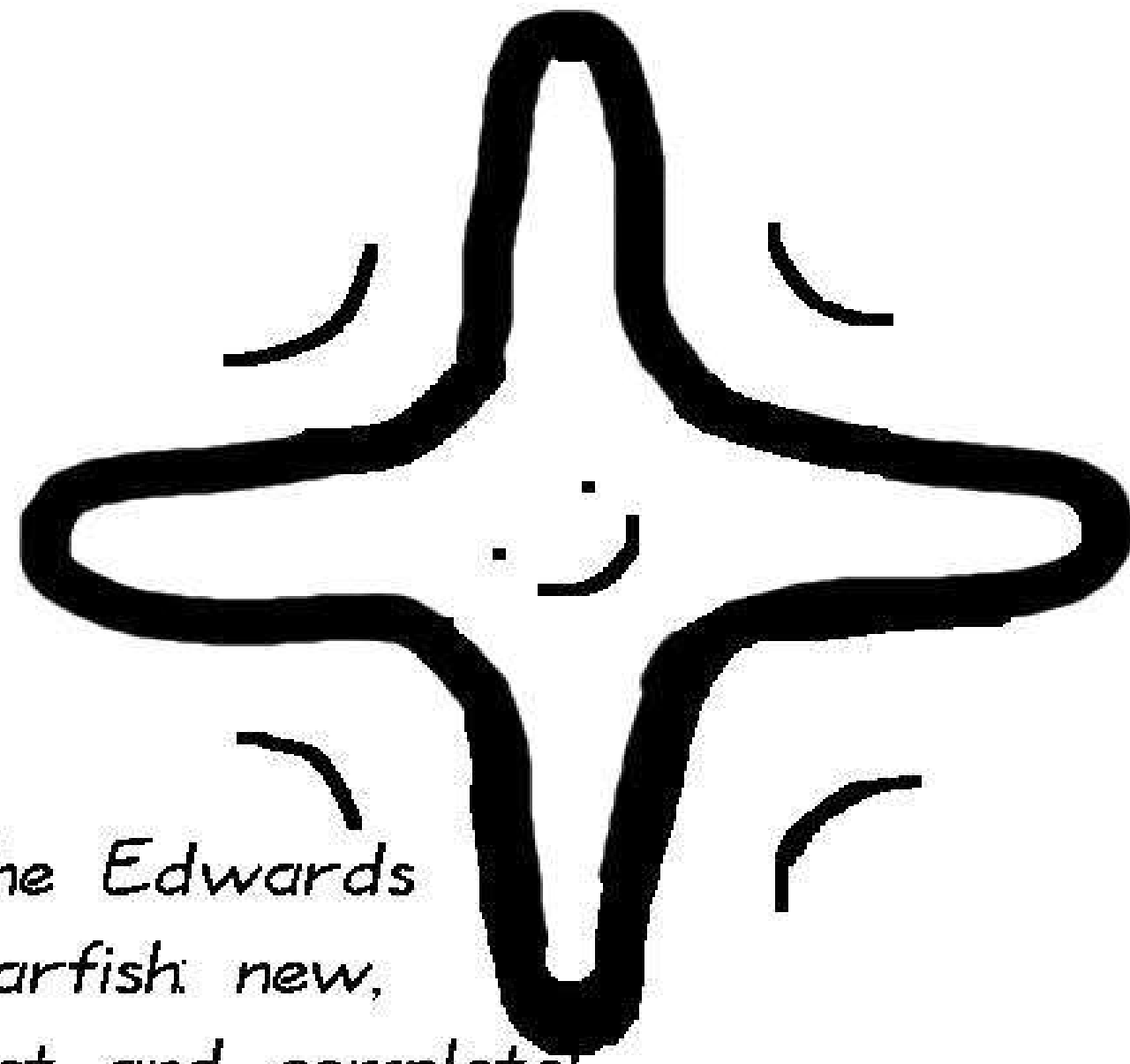
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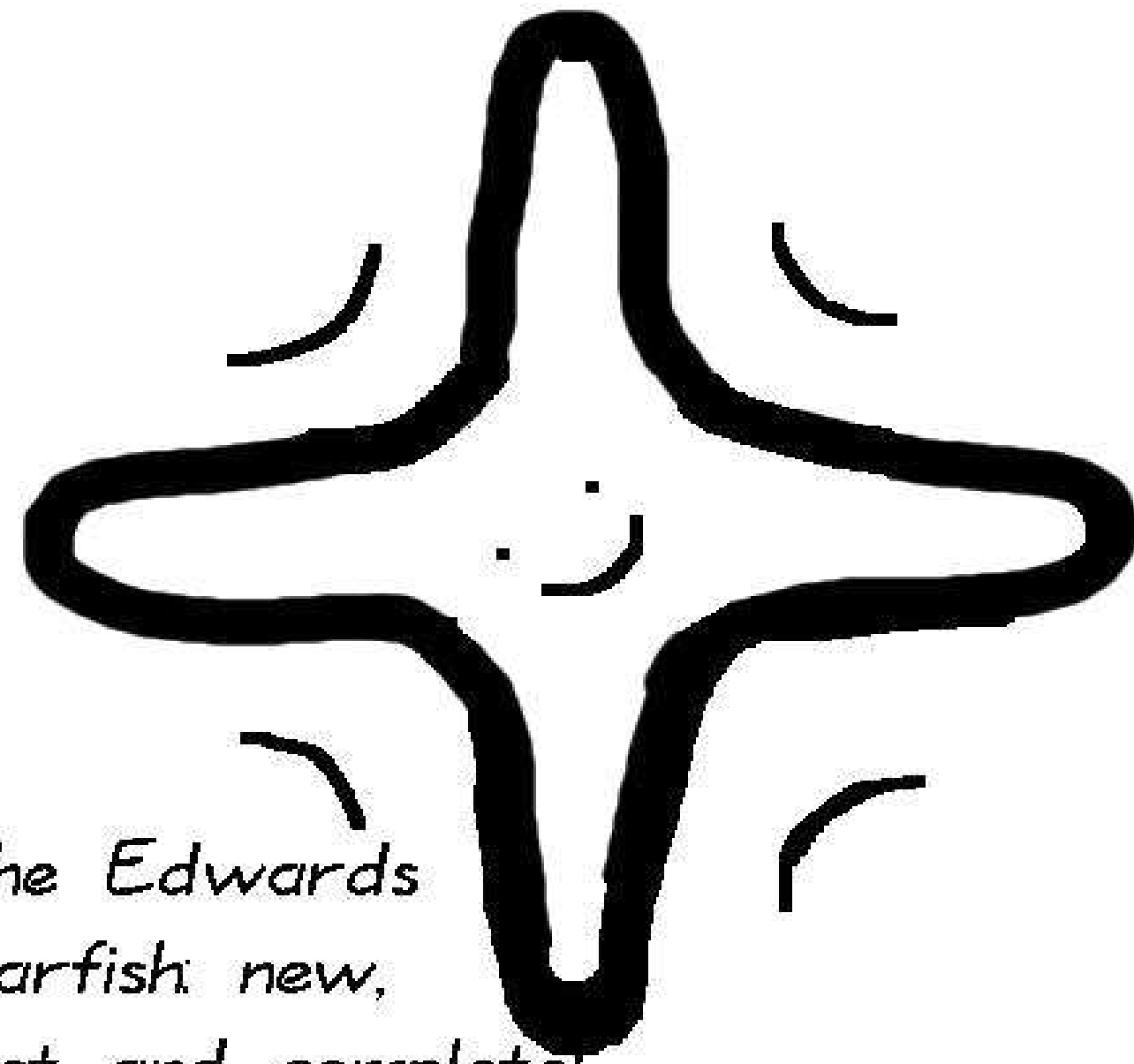


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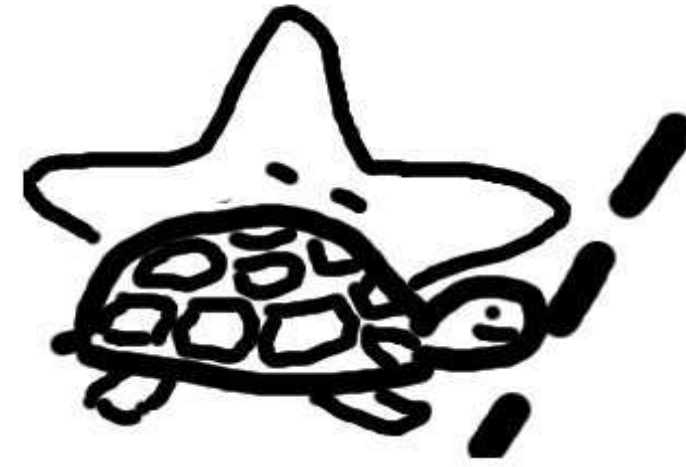


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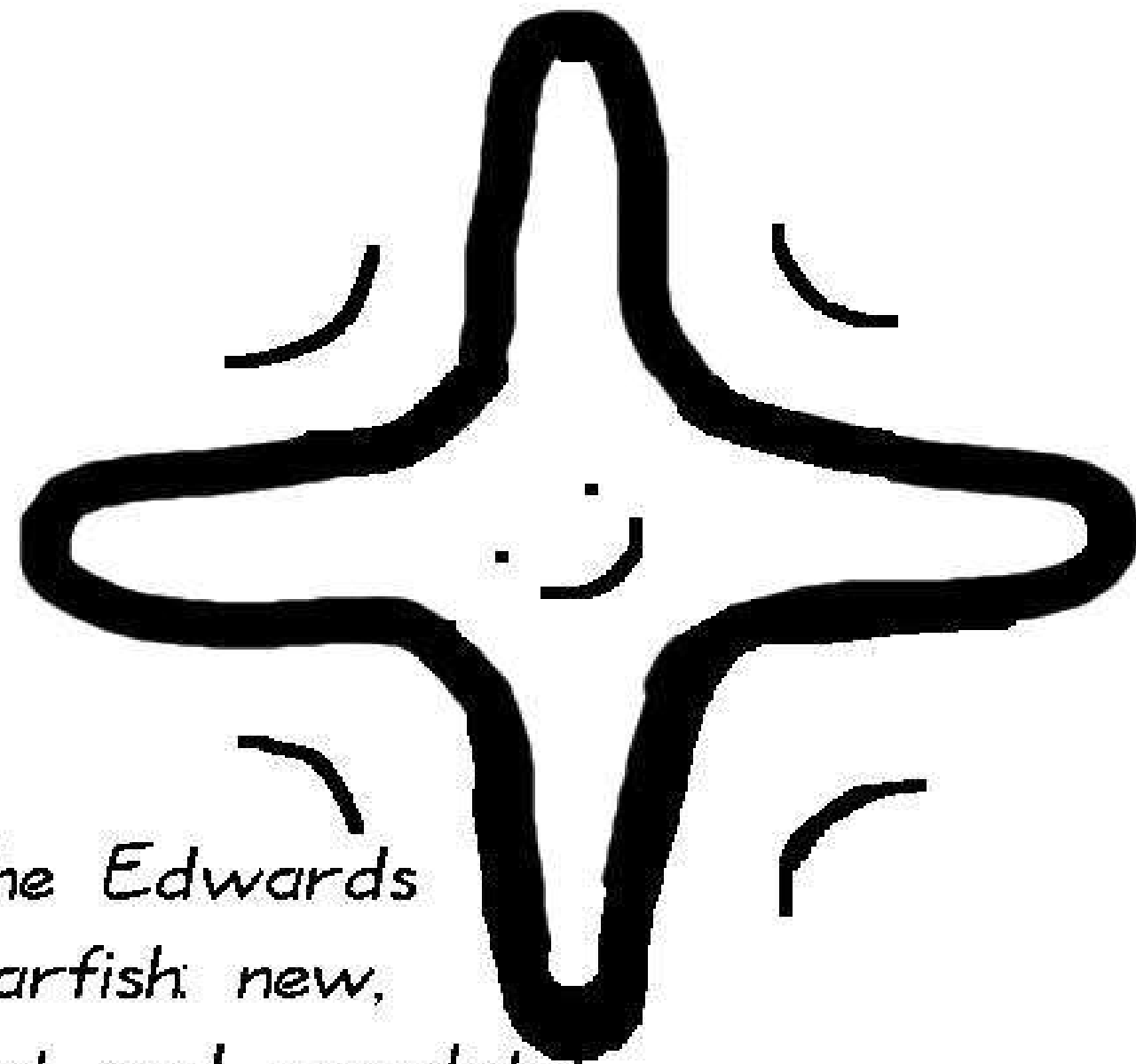
$00x^2y^2$



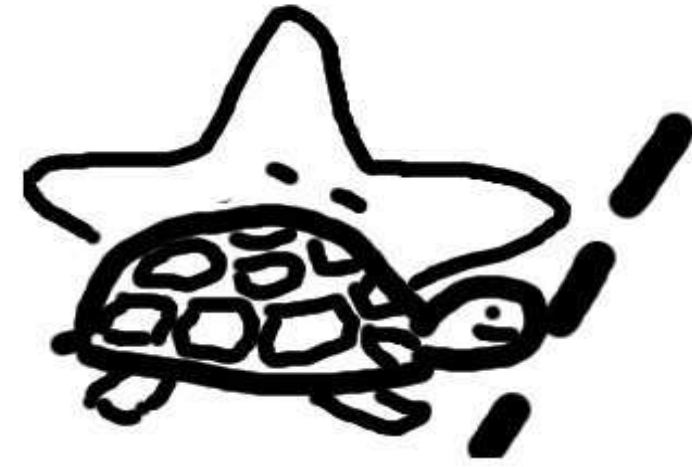
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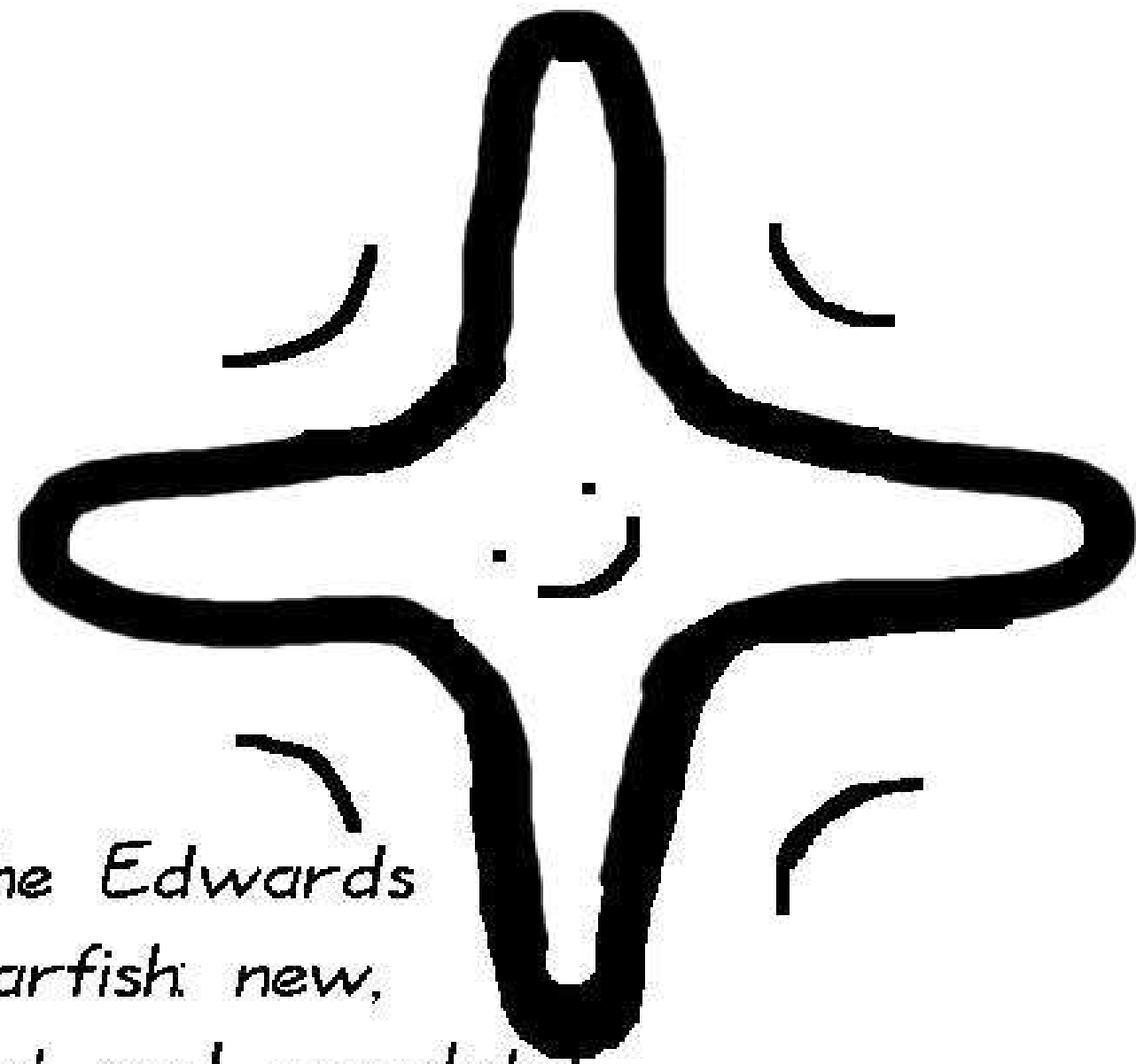
Start!



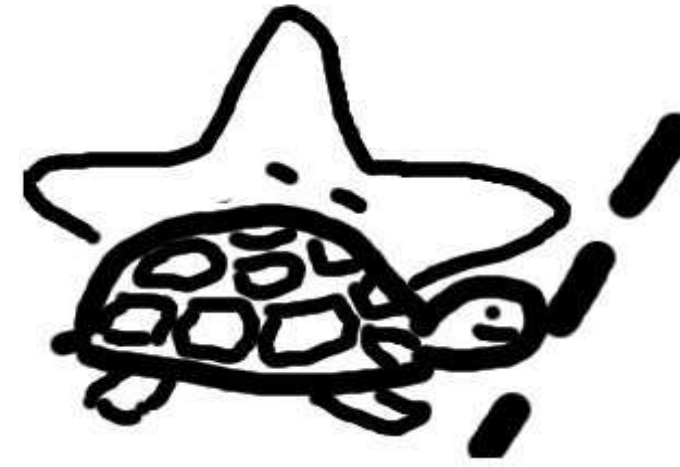
*The Edwards
starfish: new,
fast and complete!*



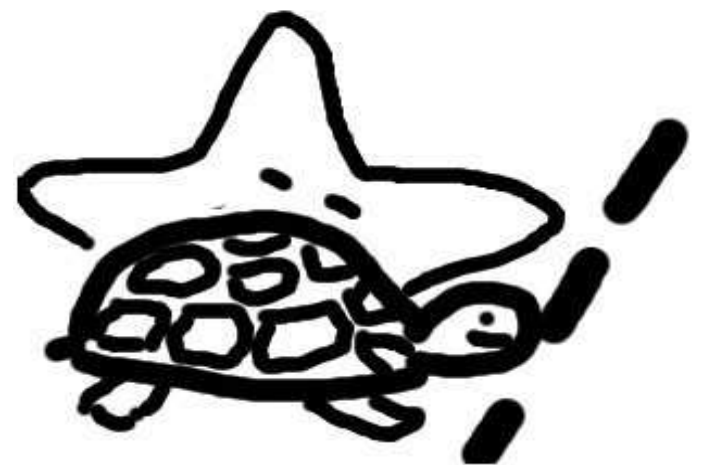
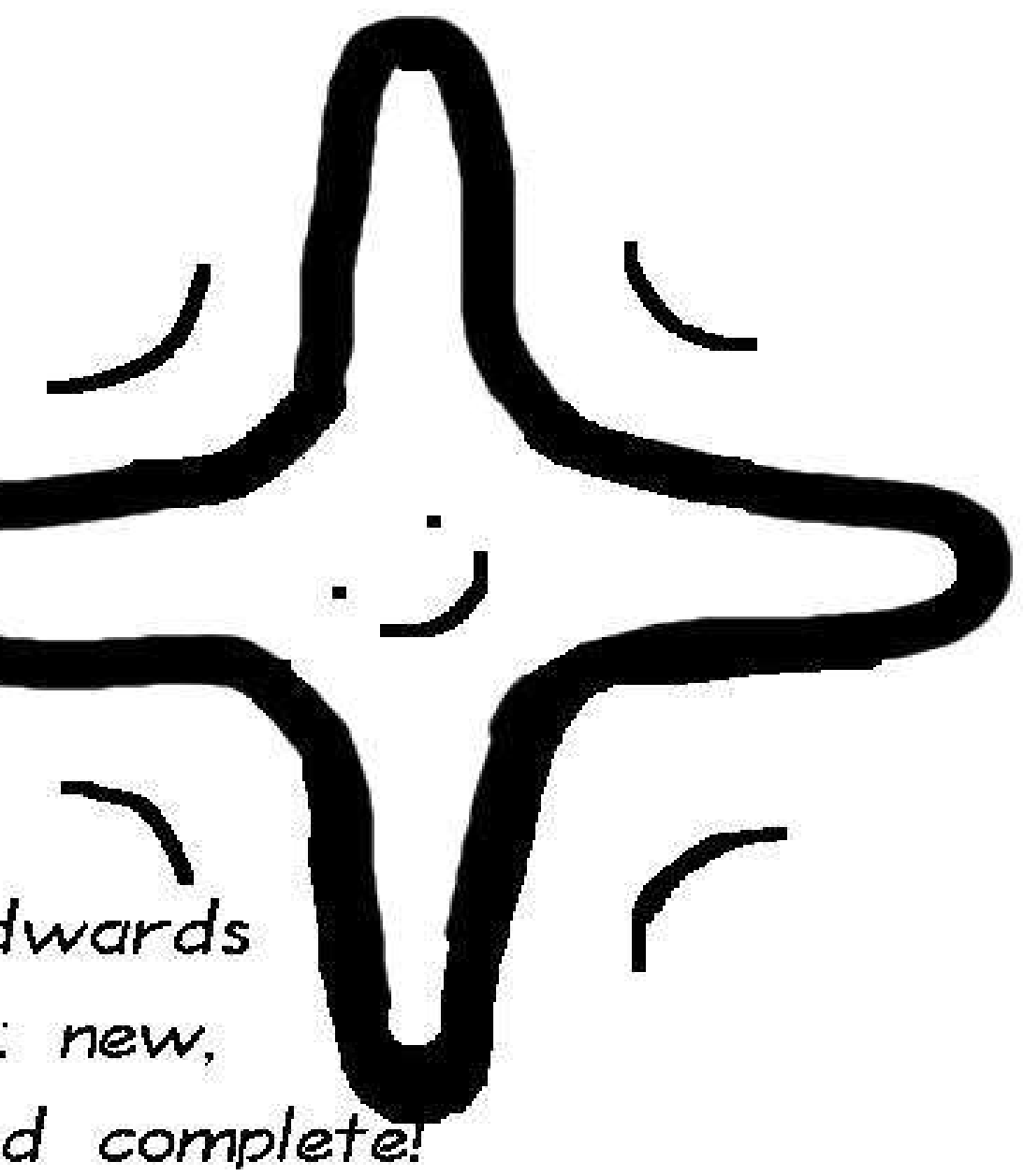
Start!



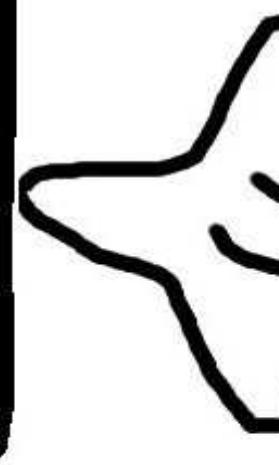
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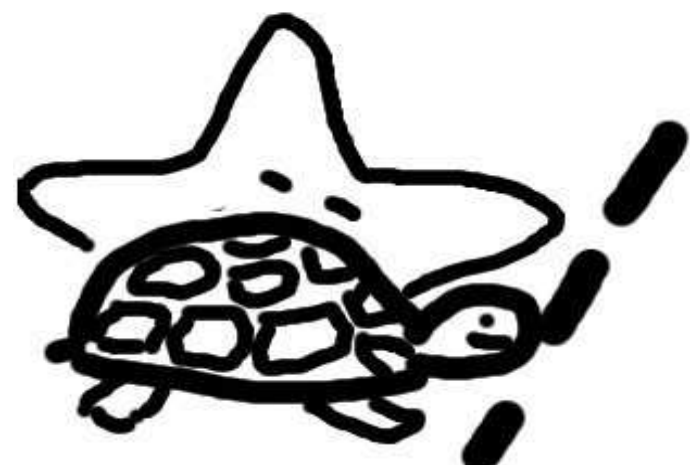
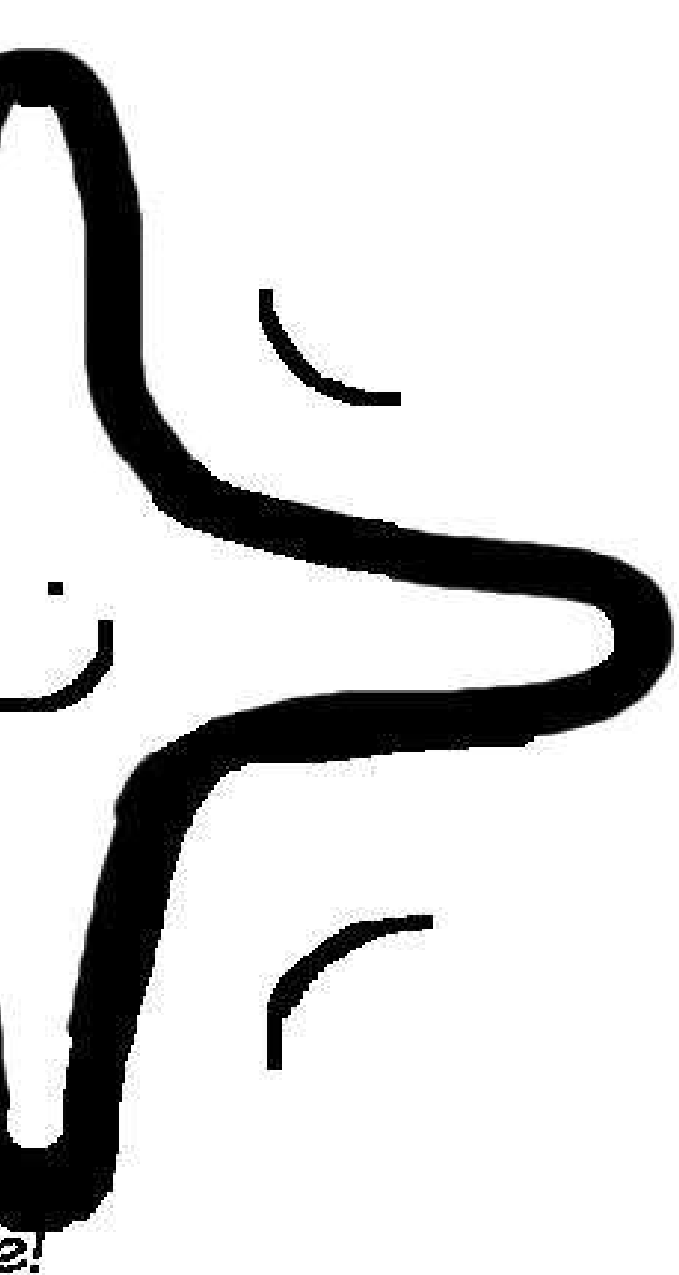
Start!



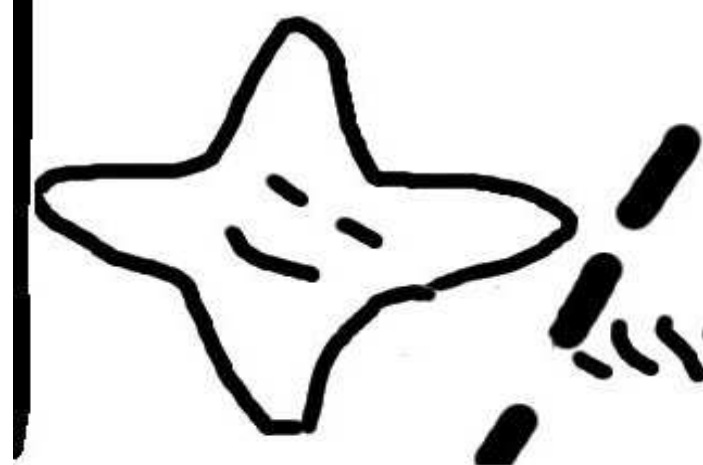
Start!



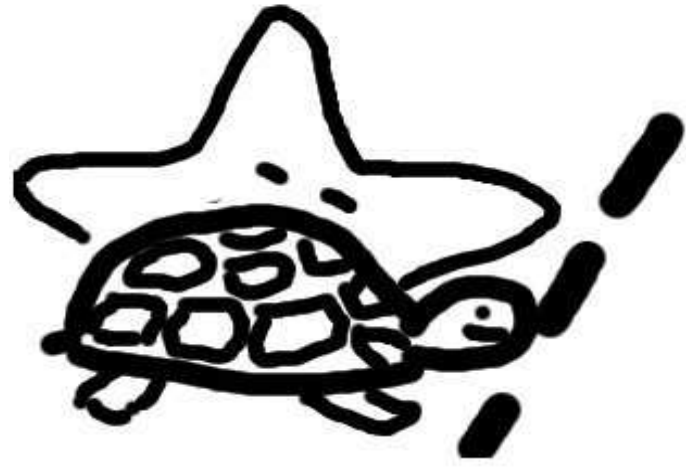
Weierstrass
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Start!



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Weierstrass sets off, E
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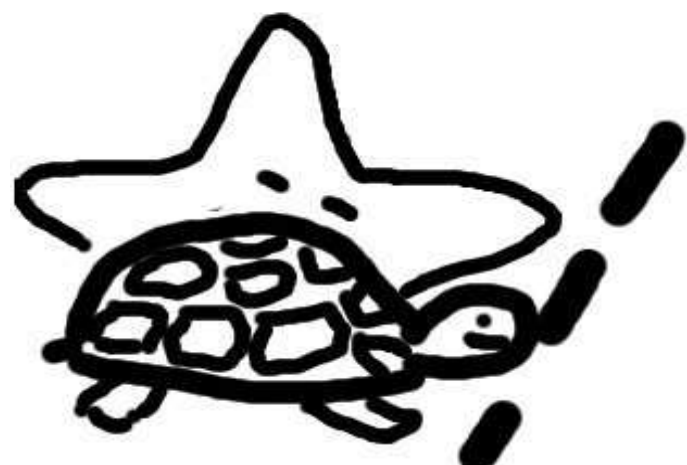


Start!

1985



*Weierstrass sets off, Edwards
left behind sleeping*



Start!

1985



Weierstrass sets off, Edwards
left behind sleeping



1985



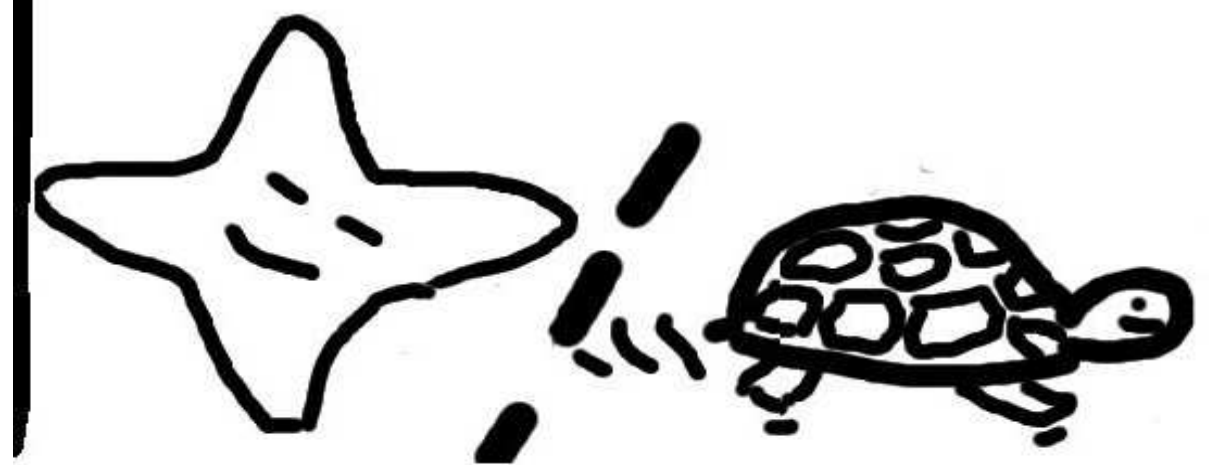
Weierstrass sets off, Edwards
left behind sleeping

20



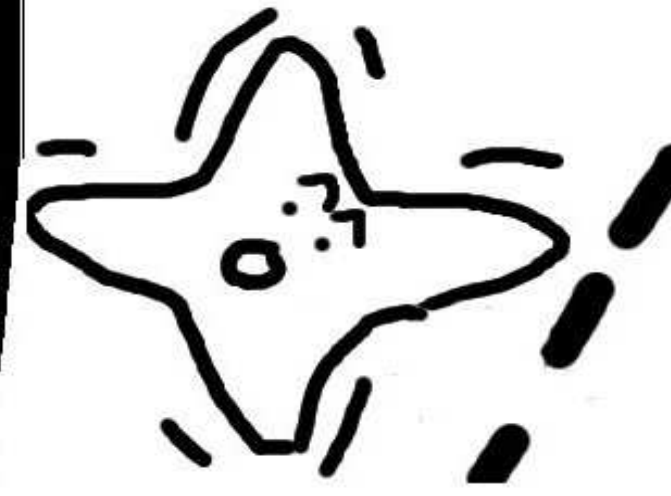
Weierstrass
finally Edwards

1985



Weierstrass sets off, Edwards left behind sleeping

2007-



Weierstrass has made finally Edwards wakes

1985



Weierstrass sets off, Edwards
left behind sleeping

2007-Jan



Weierstrass has made some progress
finally Edwards wakes up.

1985



Weierstrass sets off, Edwards
left behind sleeping

2007-Jan



Weierstrass has made some progress -
finally Edwards wakes up.

1985



Mass sets off, Edwards
and sleeping

2007 - Jan



Weierstrass has made some progress -
finally Edwards wakes up.

Feb



Exciting
about to



Edwards

2007-Jan



Weierstrass has made some progress -
finally Edwards wakes up.

Feb



Exciting progress: Edw
about to overtake!!

2007-Jan



Weierstrass has made some progress -
finally Edwards wakes up.

Feb



Exciting progress: Edwards
about to overtake!!

2007-Jan



Weierstrass has made some progress -
finally Edwards wakes up.

Feb



Exciting progress: Edwards
about to overtake!!

2007 - Jan



ass has made some progress -
wards wakes up.

Feb



Exciting progress: Edwards
about to overtake!!

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some progress -
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Exciting progress: Edwards
about to overtake!!

Mar



And the winner is: Ed



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Feb



Exciting progress: Edwards about to overtake!!

Mar



And the winner is: Edwards!

Feb

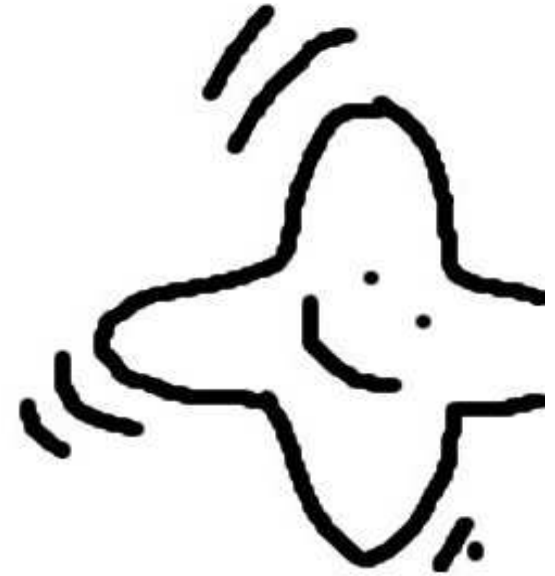


Exciting progress: Edwards
about to overtake!!

Mar



And the winner is: Edwards!



b

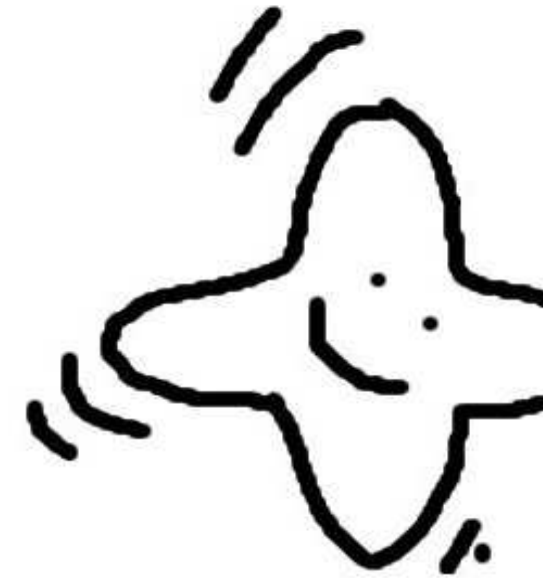


progress: Edwards
to overtake!!

Mar



And the winner is: Edwards!



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And the winner is: Edwards!



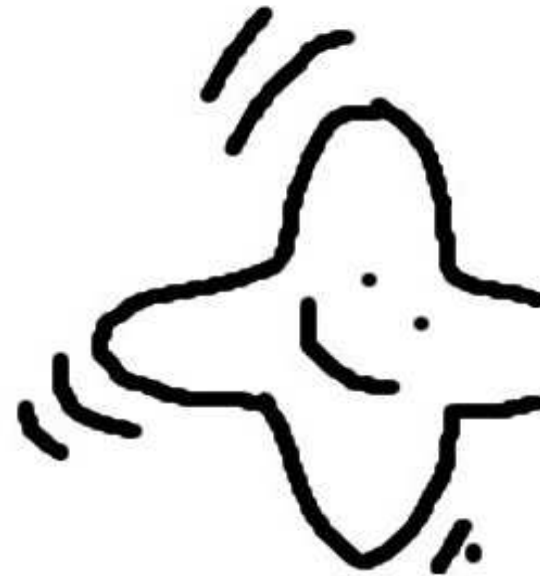
Speed-oriented J

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2000 NIST "FIPS
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And the winner is: Edwards!

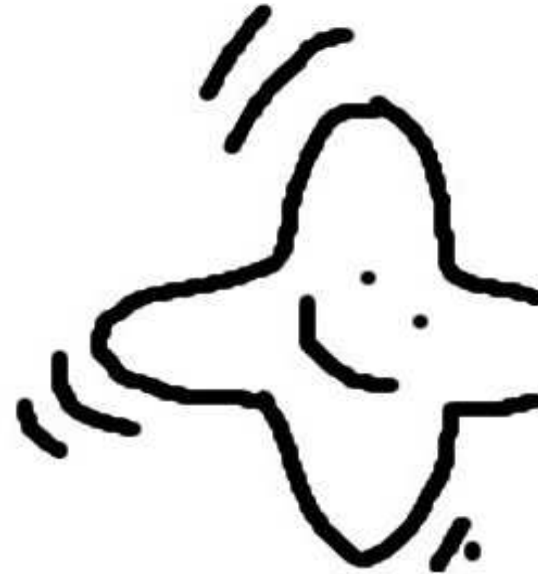
Speed-oriented Jacobian st

2000 IEEE “Std 1363”
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Mar



And the winner is: Edwards!

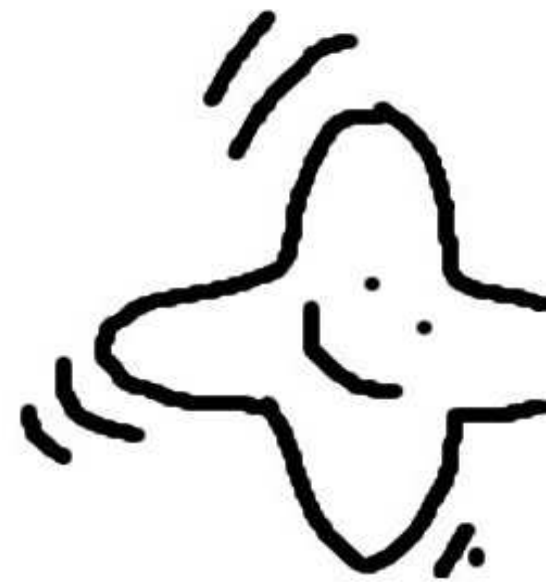
Speed-oriented Jacobian standards

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21



winner is: Edwards!

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Projective for We

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Speed up ADD b

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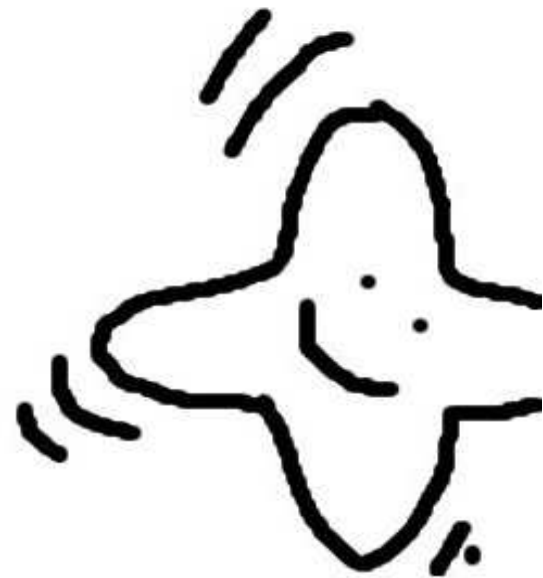
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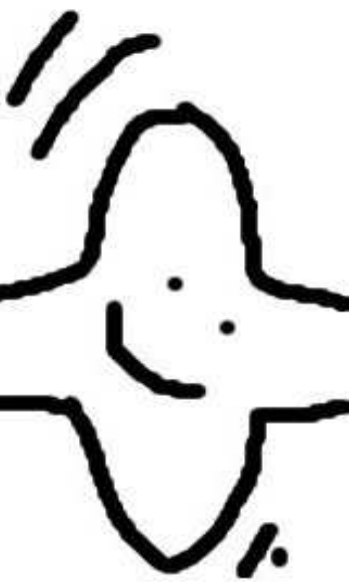
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1986 Chudnovsky–Chudnov

Speed up ADD by switching

$(X/Z^2, Y/Z^3)$ to $(X/Z, Y/Z^3)$

$7\mathbf{M} + 3\mathbf{S}$ for DBL if $a = -3$

$12\mathbf{M} + 2\mathbf{S}$ for ADD.

$12\mathbf{M} + 2\mathbf{S}$ for reADD.

Option has been mostly ignored

DBL dominates in ECDH e

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oriented Jacobian standards

IEEE “Std 1363”

Weierstrass curves

Jacobian coordinates

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specifies a method of

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Montgomery

1987 Montgomery

Use *by*

Choose

$2(x_2, y_2)$

$\Rightarrow x_4 =$

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(x_3, y_3)

$\Rightarrow x_5 =$

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Choose small (a

$$2(x_2, y_2) = (x_4, y_4)$$

$$\Rightarrow x_4 = \frac{(x_2^2 - a)^2}{4x_2(x_2^2 + a)}$$

$$(x_3, y_3) - (x_2, y_2)$$

$$(x_3, y_3) + (x_2, y_2)$$

$$\Rightarrow x_5 = \frac{(x_2x_3 - a)}{x_1(x_2 - x_3)}$$

standards

Projective for Weierstrass

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1987 Montgomery:

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Choose small $(a + 2)/4$.

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Alternative for Weierstrass

Chudnovsky–Chudnovsky:

Speed up ADD by switching from $(X/Z, Y/Z^3)$ to $(X/Z, Y/Z)$.

3S for DBL if $a = -3$.

2S for ADD.

2S for reADD.

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ADD dominates in

applications: e.g.,

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Represent

as $(X:Y:Z)$

$$B = (X_1:Y_1:Z_1)$$

$$C = (X_2:Y_2:Z_2)$$

$$D = B + C$$

$$Z_4 = D$$

$$2(X_2:Z_2)$$

$$(X_3:Z_3)$$

$$E = (X_4:Z_4)$$

$$F = (X_5:Z_5)$$

$$X_5 = Z_5$$

$$Z_5 = Y_5$$

$$(X_3:Z_3)$$

Weierstrass

Miller–Chudnovsky:

by switching from

$(X/Z, Y/Z)$.

is small if $a = -3$.

ADD.

ADD.

is mostly ignored:

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examples: e.g.,

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Represent (x, y)

as $(X:Z)$ satisfying

$$B = (X_2 + Z_2)^2,$$

$$C = (X_2 - Z_2)^2,$$

$$D = B - C, X_4 =$$

$$Z_4 = D \cdot (C + D)$$

$$2(X_2:Z_2) = (X_4:$$

$$(X_3:Z_3) - (X_2:Z_2)$$

$$E = (X_3 - Z_3) \cdot$$

$$F = (X_3 + Z_3) \cdot$$

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$$Z_5 = X_1 \cdot (E - F)$$

$$(X_3:Z_3) + (X_2:Z_2)$$

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e.g. $3H$

e.g. $6H$

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$4M + 2$

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y_4)

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$$+ ax_2 + 1).$$

$$2) = (x_1, y_1),$$

$$2) = (x_5, y_5)$$

$$- 1)^2$$

$$- x_3)^2.$$

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This representati

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DADD, "differen

$Q, R, Q - R \mapsto C$

e.g. $2P, P, P \mapsto$

e.g. $3P, 2P, P \mapsto$

e.g. $6P, 5P, P \mapsto$

2M + 2S + 1D f

4M + 2S for DA

Save **1M** if $Z_1 =$

Easily compute n

$\approx \lg n$ DBL, $\approx \lg$

Almost as fast as

Relatively slow fo

Represent (x, y)

as $(X:Z)$ satisfying $x = X/Z$.

$$B = (X_2 + Z_2)^2,$$

$$C = (X_2 - Z_2)^2,$$

$$D = B - C, X_4 = B \cdot C,$$

$$Z_4 = D \cdot (C + D(a + 2)/4) \Rightarrow$$

$$2(X_2:Z_2) = (X_4:Z_4).$$

$$(X_3:Z_3) - (X_2:Z_2) = (X_1:Z_1),$$

$$E = (X_3 - Z_3) \cdot (X_2 + Z_2),$$

$$F = (X_3 + Z_3) \cdot (X_2 - Z_2),$$

$$X_5 = Z_1 \cdot (E + F)^2,$$

$$Z_5 = X_1 \cdot (E - F)^2 \Rightarrow$$

$$(X_3:Z_3) + (X_2:Z_2) = (X_5:Z_5).$$

This representation

does not allow ADD but it

DADD, “differential addition”

$$Q, R, Q - R \mapsto Q + R.$$

$$\text{e.g. } 2P, P, P \mapsto 3P.$$

$$\text{e.g. } 3P, 2P, P \mapsto 5P.$$

$$\text{e.g. } 6P, 5P, P \mapsto 11P.$$

2M + 2S + 1D for DBL.

4M + 2S for DADD.

Save **1M** if $Z_1 = 1$.

Easily compute $n(X_1 : Z_1)$

$\approx \lg n$ DBL, $\approx \lg n$ DADD

Almost as fast as Edwards

Relatively slow for $mP + r$

Represent (x, y)

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Doubling

2006 D

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2006 Doche–Icar

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3M + 4S + 2D f

How? Factor DB

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2007 Bernstein–L

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Doubling-oriented curves

2006 Doche–Icart–Kohel:

Use $y^2 = x^3 + ax^2 + 16ax$

Choose small $a.$

Use $(X : Y : Z : Z^2)$

to represent $(X/Z, Y/Z^2).$

3M + 4S + 2D for DBL.

How? Factor DBL as $\hat{\varphi}(\varphi)$

where φ is a 2-isogeny.

2007 Bernstein–Lange:

2M + 5S + 2D for DBL

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 $Q + R$.
 $3P$.
 $5P$.
 $11P$.
 or DBL.
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 $n(X_1 : Z_1)$ using
 n DADD.
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fast DBL+DADD

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$$2\mathbf{M} + 5\mathbf{S} + 2\mathbf{D} \text{ for DBL}$$

on the same curves.

$$12\mathbf{M} + 5\mathbf{S} + 1\mathbf{D} \text{ for ADD.}$$

Slower ADD than other systems, typically outweighing benefits of the very fast DBL.

But isogenies are useful.

Example, 2005 Gaudry:

fast DBL+DADD on Jacobians of genus-2 hyperelliptic curves using similar factorization.

Tricky but potentially helpful: tripling-oriented curves (see 2006 Doche–Icart–Kohel double-base chains, ...)

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Bernstein–Lange:

$5\mathbf{S} + 2\mathbf{D}$ for DBL

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Hessian

Credite

by 198

$(X : Y$

on $x^3 -$

$12\mathbf{M}$ fo

$X_3 = Y$

$Y_3 = X$

$Z_3 = Z$

$6\mathbf{M} + 3$

add curves

Doche–Kohel:

$$x^2 + 16ax.$$

Z^2)

$(X, Y/Z^2)$.

or DBL.

DBL as $\hat{\varphi}(\varphi)$

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ADD than other systems,
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le, 2005 Gaudry:

$3\mathbf{L} + \mathbf{DADD}$ on Jacobians of

2 hyperelliptic curves,

similar factorization.

but potentially helpful:

\mathbb{F}_q -oriented curves

(2006 Doche–Icart–Kohel),

-base chains, ...

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$6\mathbf{M} + 3\mathbf{S}$ for DBL.

2001 J

$2(X_1 :$

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$(X : Y$

$: 2$

$6\mathbf{M} + 6$

$3\mathbf{M} + 6$

for ADD.

in other systems,

giving benefit

DBL.

is useful.

Gaudry:

based on Jacobians of

elliptic curves,

linearization.

is initially helpful:

elliptic curves

(Montgomery–Lauter–Kohel),

and, . . .

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“Unified addition

helpful against side-channel

But not strongly

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2008.02 Hisil–Wang

$$(X : Y : Z : X^2 :$$

$$: 2XY : 2XZ$$

6M + 6S for AD

3M + 6S for DB

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But not strongly unified:

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2008.02 Hisil–Wong–Carter

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2008.02 Hisil–Wong–Carter–Dawson:

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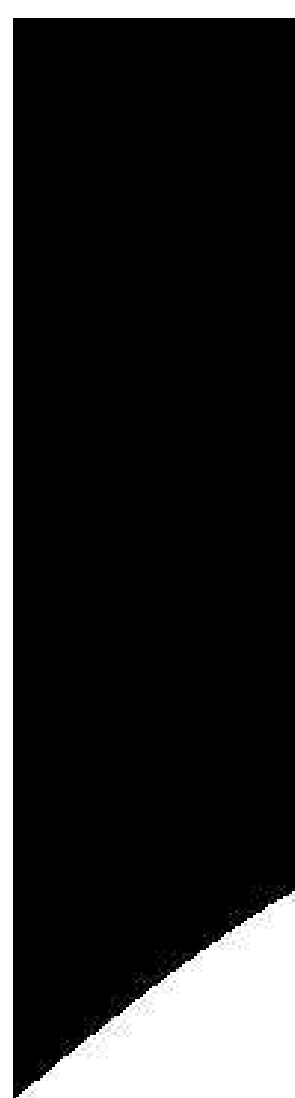
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$$x^3 - y$$

ester

vsky–Chudnovsky:

esent $(X/Z, Y/Z)$

$= 3dxy.$

$Z_2 - Z_1 Y_2 \cdot X_1 Y_2,$

$Z_2 - Y_1 X_2 \cdot Z_1 X_2,$

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6M + **6S** for ADD.

3M + **6S** for DBL.


$$x^3 - y^3 + 1 = 0.$$

Inovsky:

$(Z, Y/Z)$

$X_1Y_2,$

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$Y_1Z_2.$

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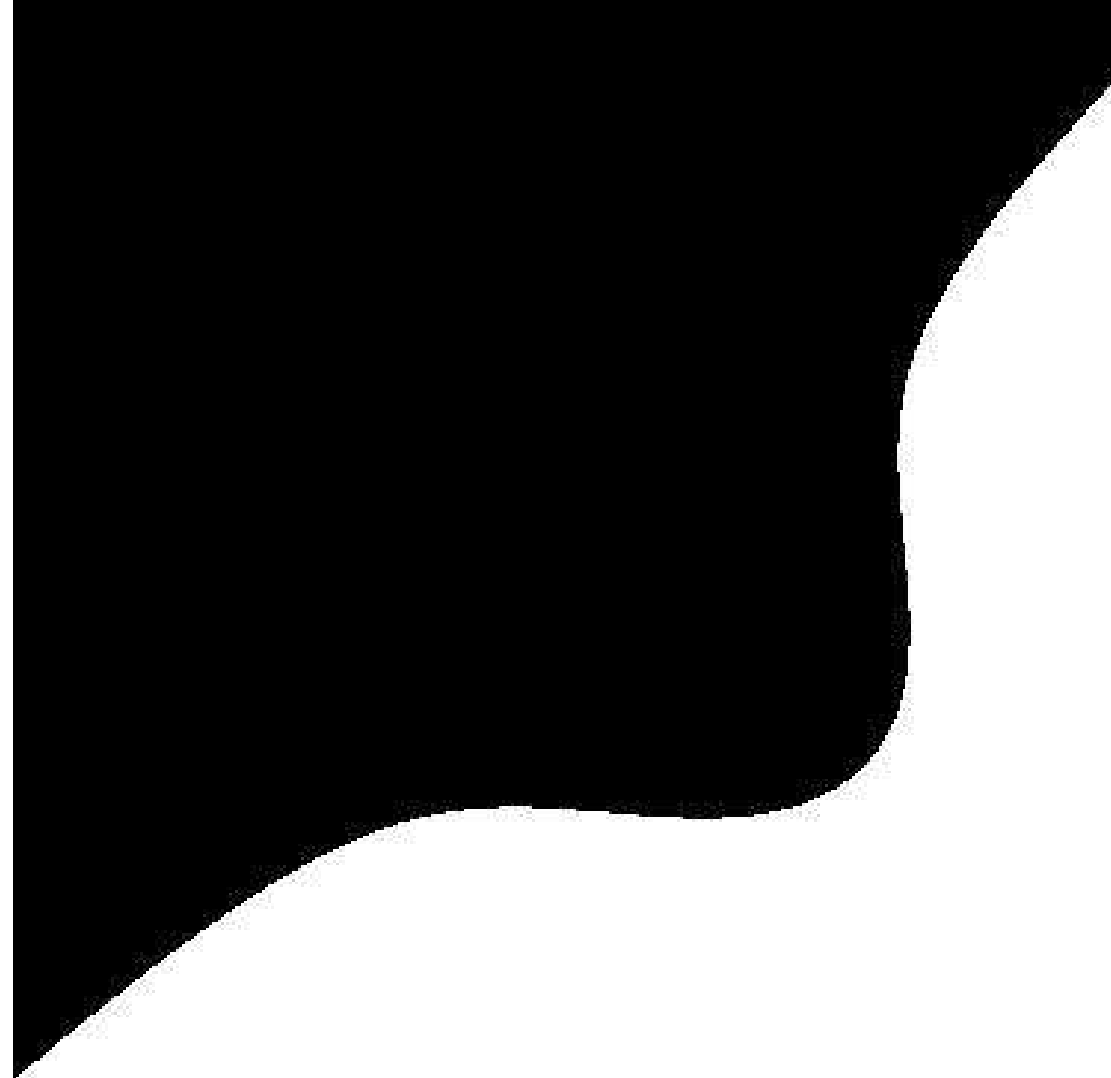
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$$x^3 - y^3 + 1 = 0.3xy$$

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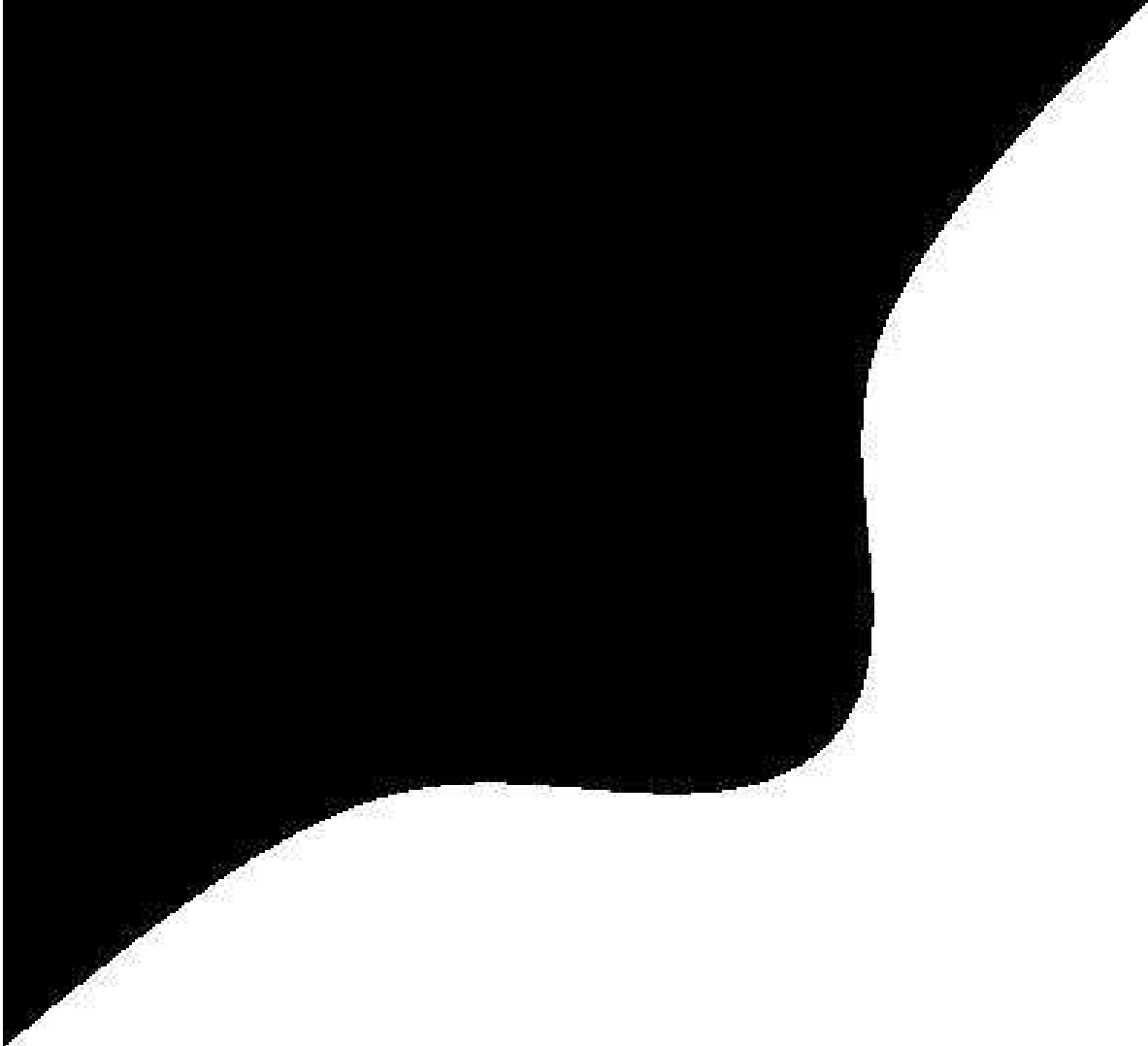
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Boyer–Quisquater:

$(Y_1 : Z_1) =$

$(X_1 : Y_1) + (Y_1 : Z_1 : X_1)$

use ADD to double.

and addition formulas,”

against side channels.

is strongly unified:

to permute inputs.

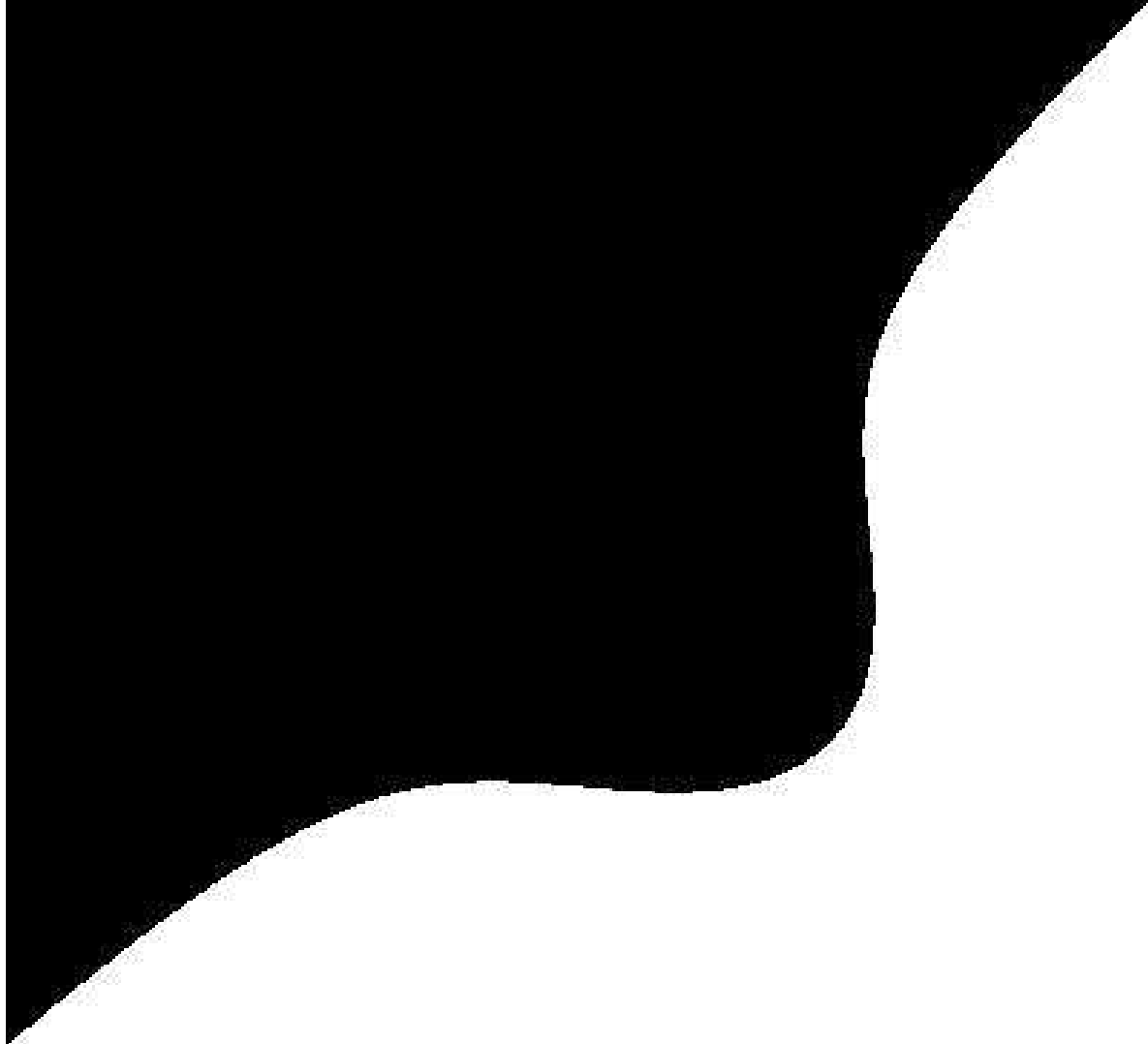
2 Hisil–Wong–Carter–Dawson:

$(X : Z : X^2 : Y^2 : Z^2$

$: 2XY : 2XZ : 2YZ)$.

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6S for DBL.


$$x^3 - y^3 + 1 = 0.3xy$$

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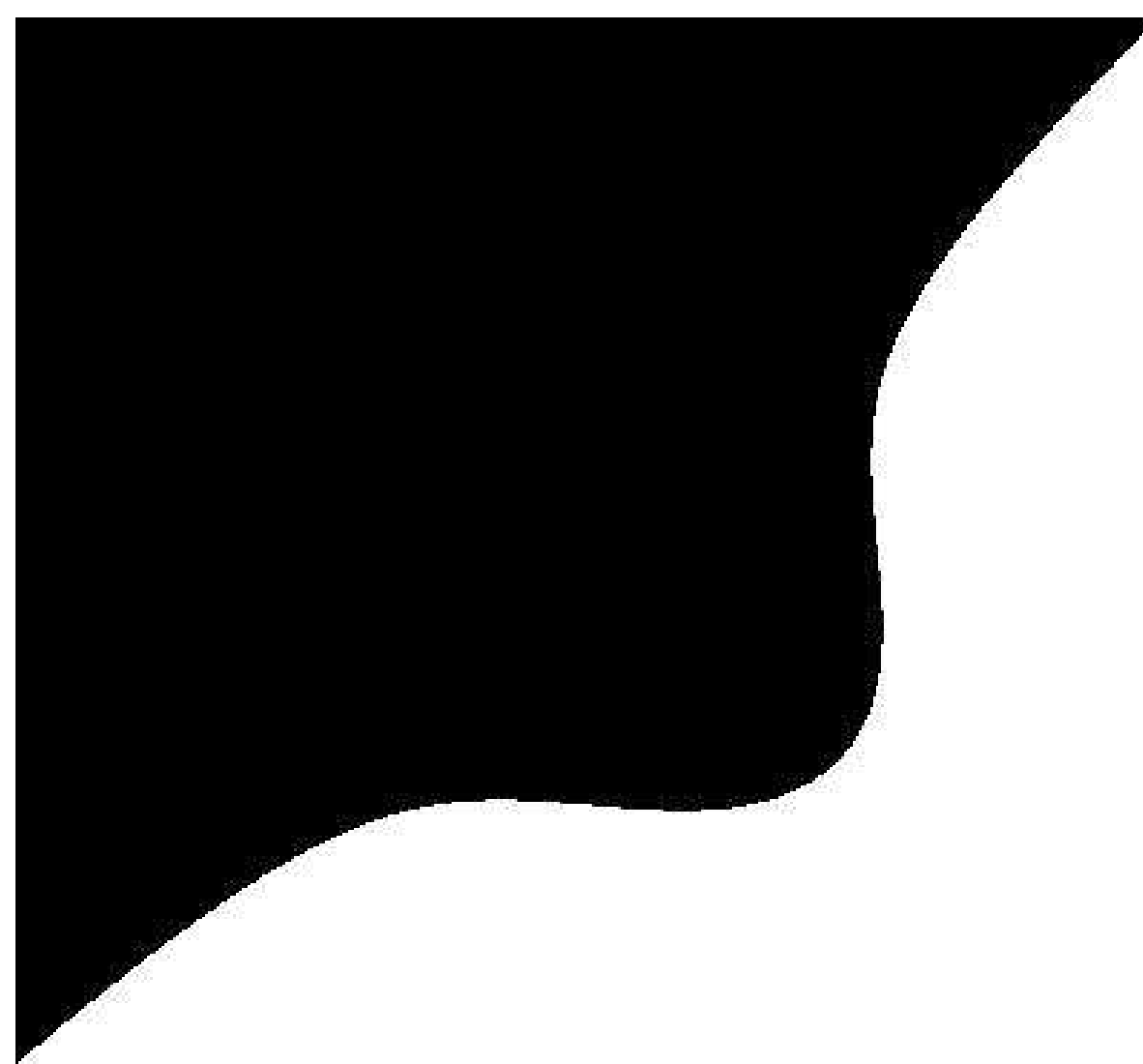
ong-Carter-Dawson:

$Y^2 : Z^2$

$Z : 2YZ$).

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$$x^3 - y^3 + 1 = 0.3xy$$

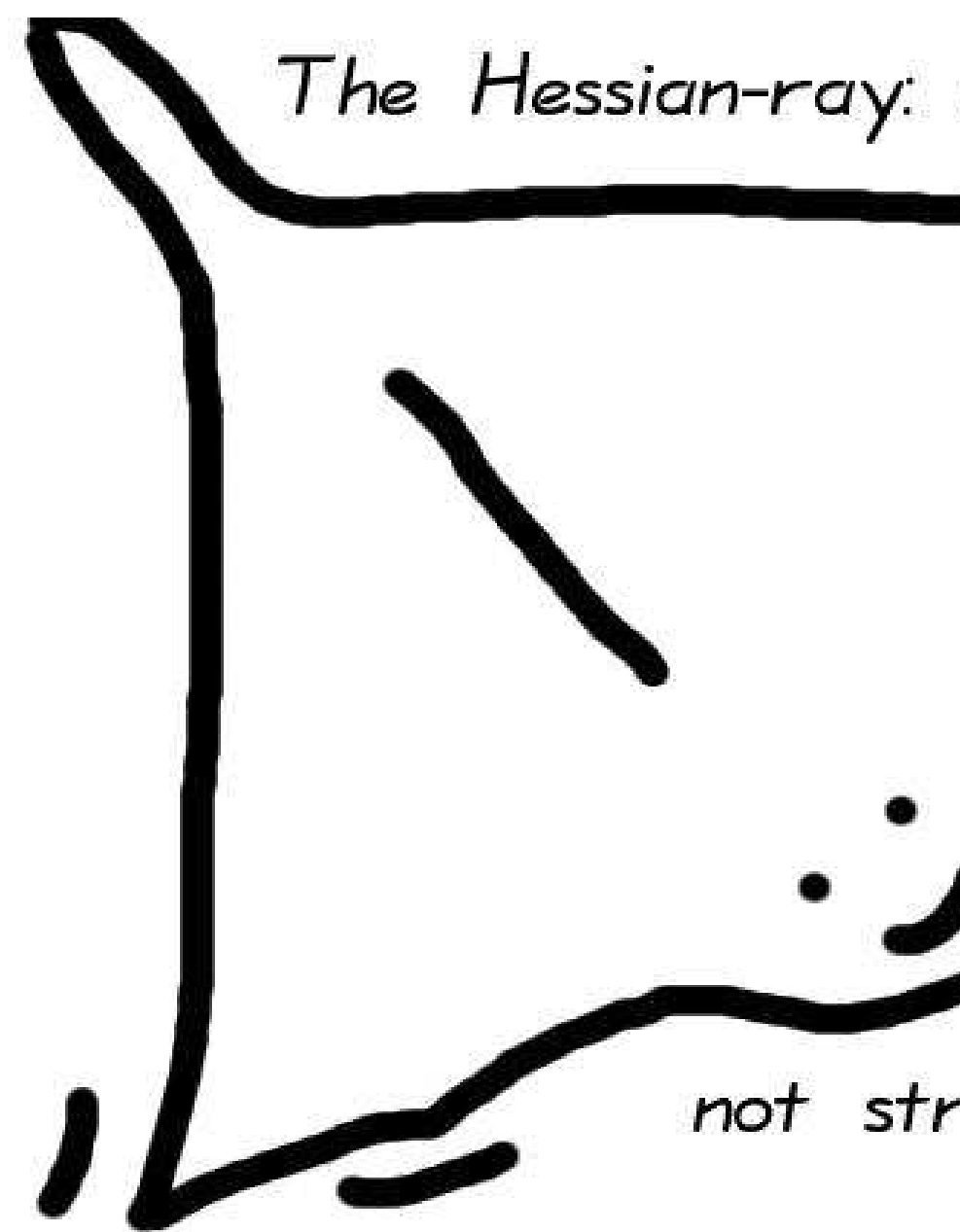
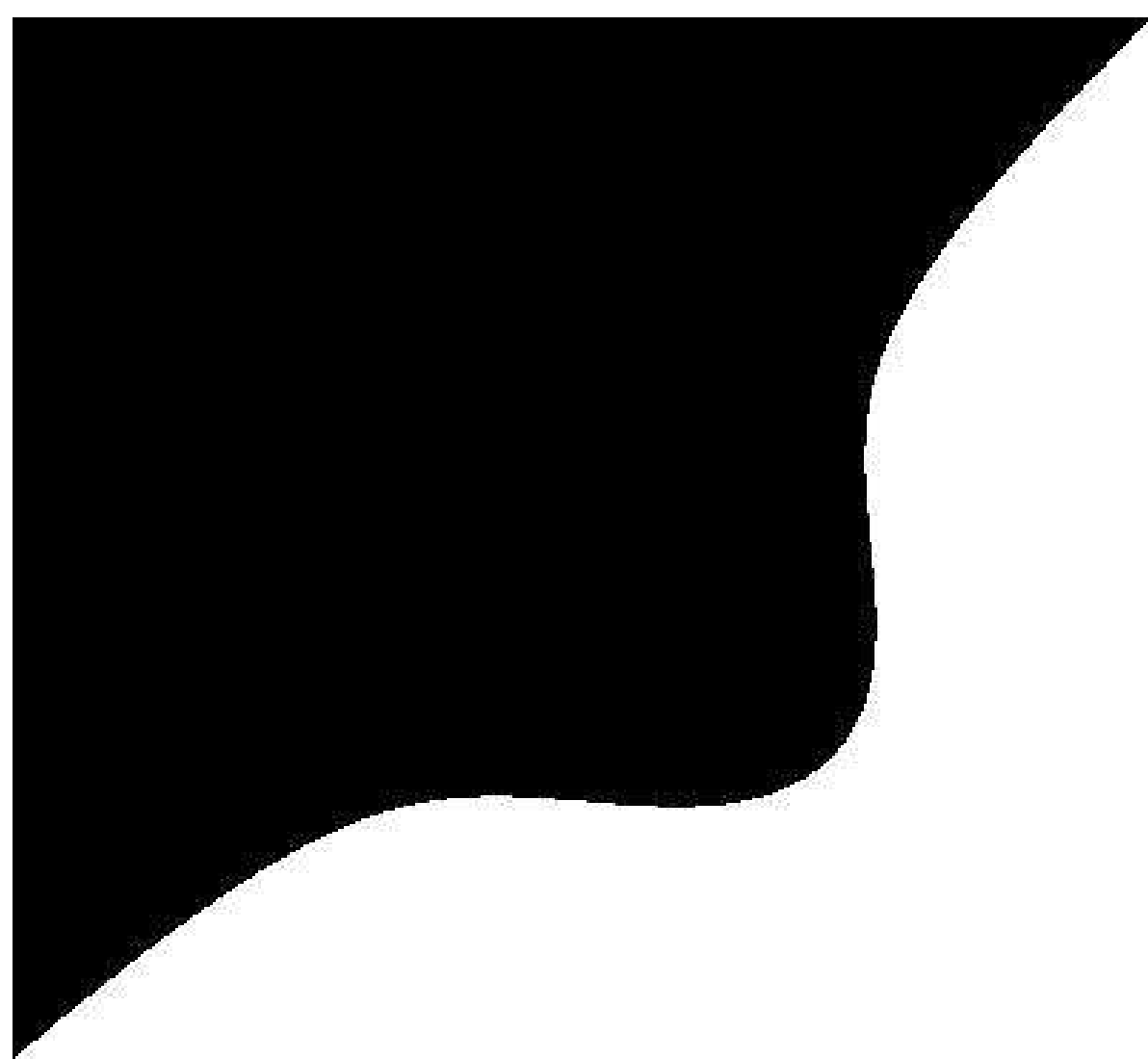


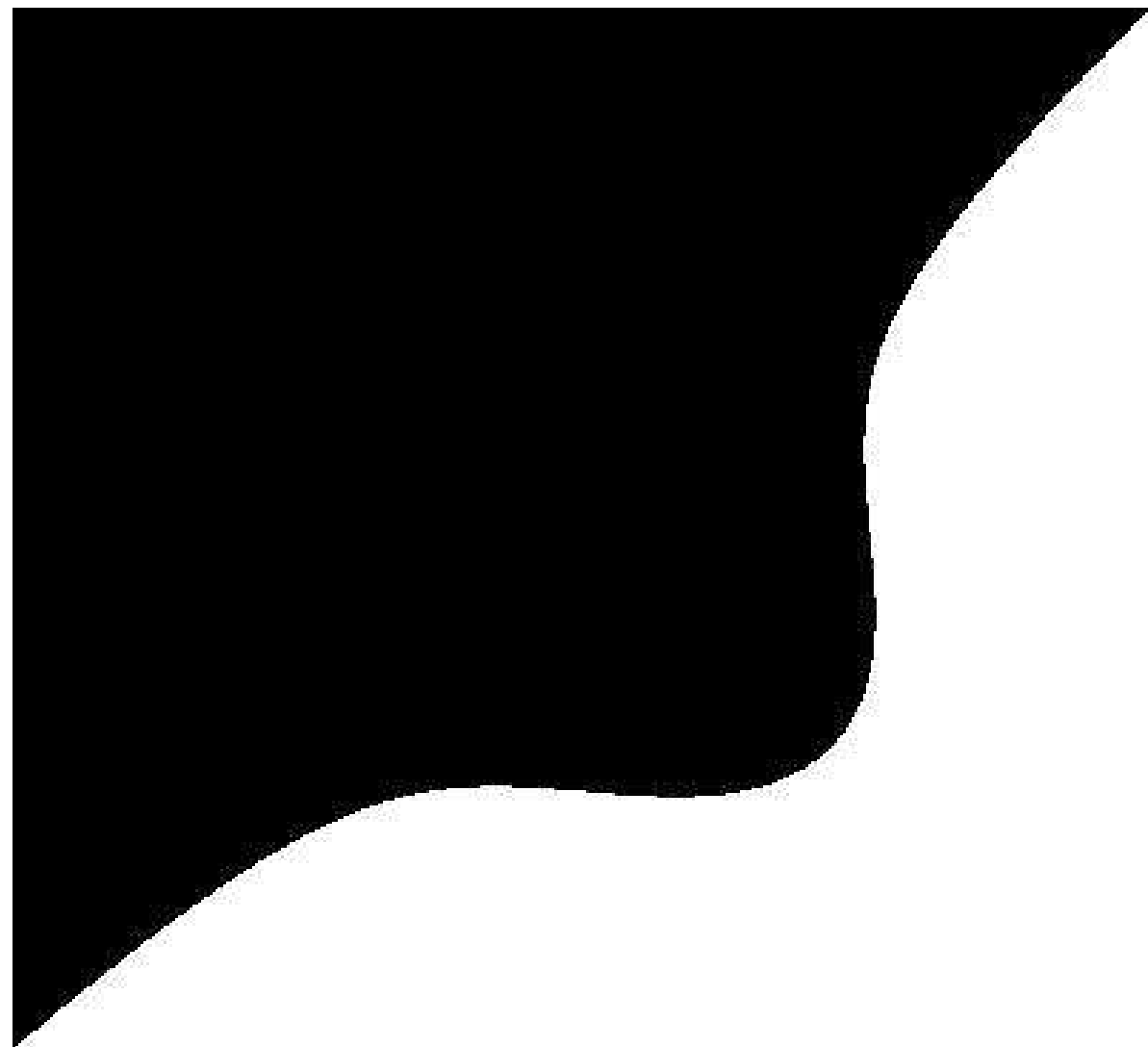
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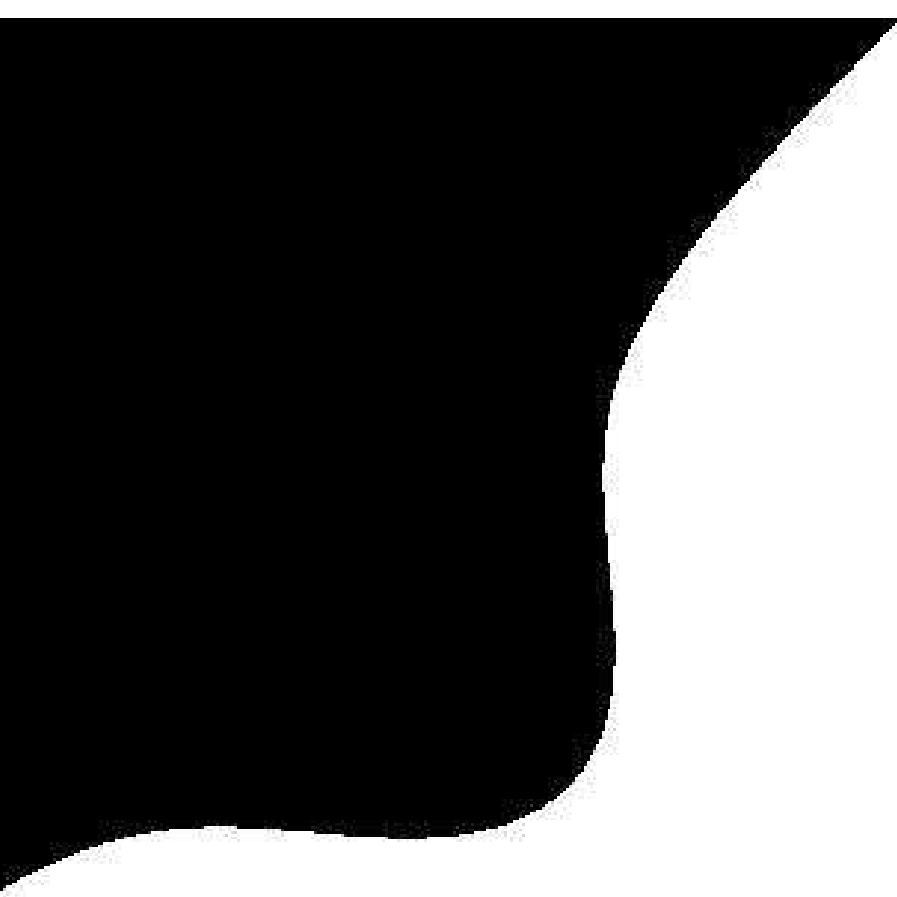
r-Dawson:

$$x^3 - y^3 + 1 = 0.3xy$$




$$x^3 - y^3 + 1 = 0.3xy$$





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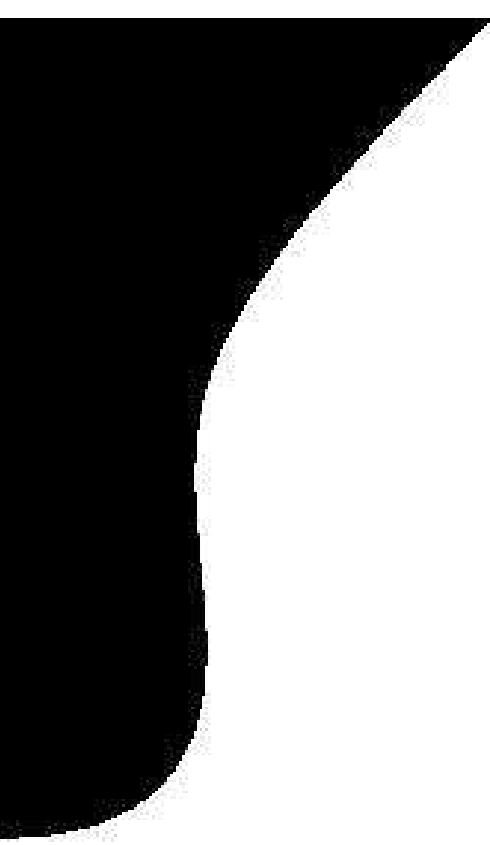
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Jacobi intersection

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*but
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Jacobi intersections

1986 Chudnovsky–Chudnov

$(S : C : D : Z)$ represent
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$14\mathbf{M} + 2\mathbf{S} + 1\mathbf{D}$ for ADD.

“Tremendous advantage”
of being strongly unified.

$5\mathbf{M} + 3\mathbf{S}$ for DBL.

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The Hessian-ray: uniform



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Jacobi intersections

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$(S : C : D : Z)$ represent

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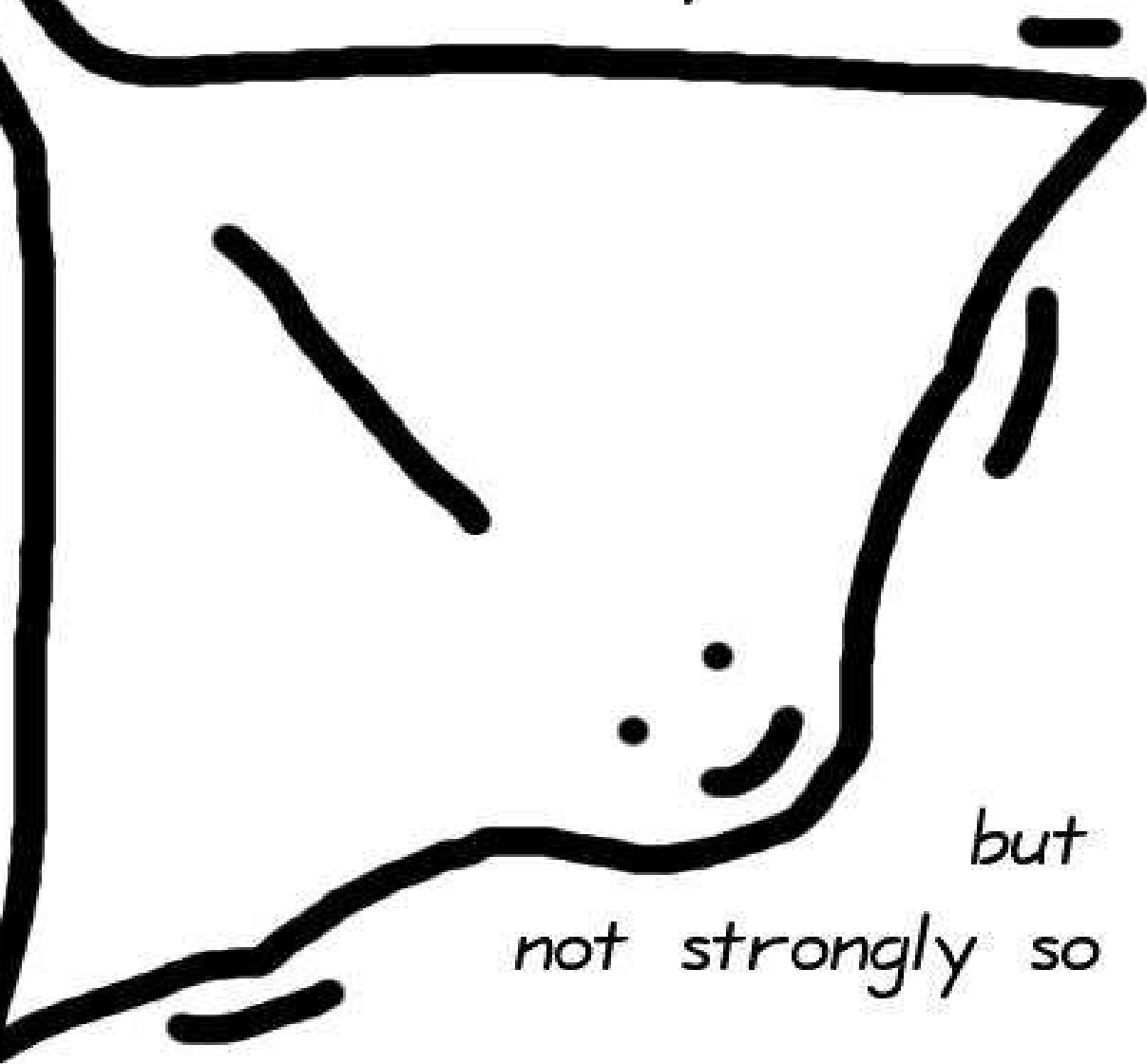
14M + 2S + 1D for ADD.

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Jacobi intersections

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5M + 3S for DBL.

“Perhaps (?) ... the most
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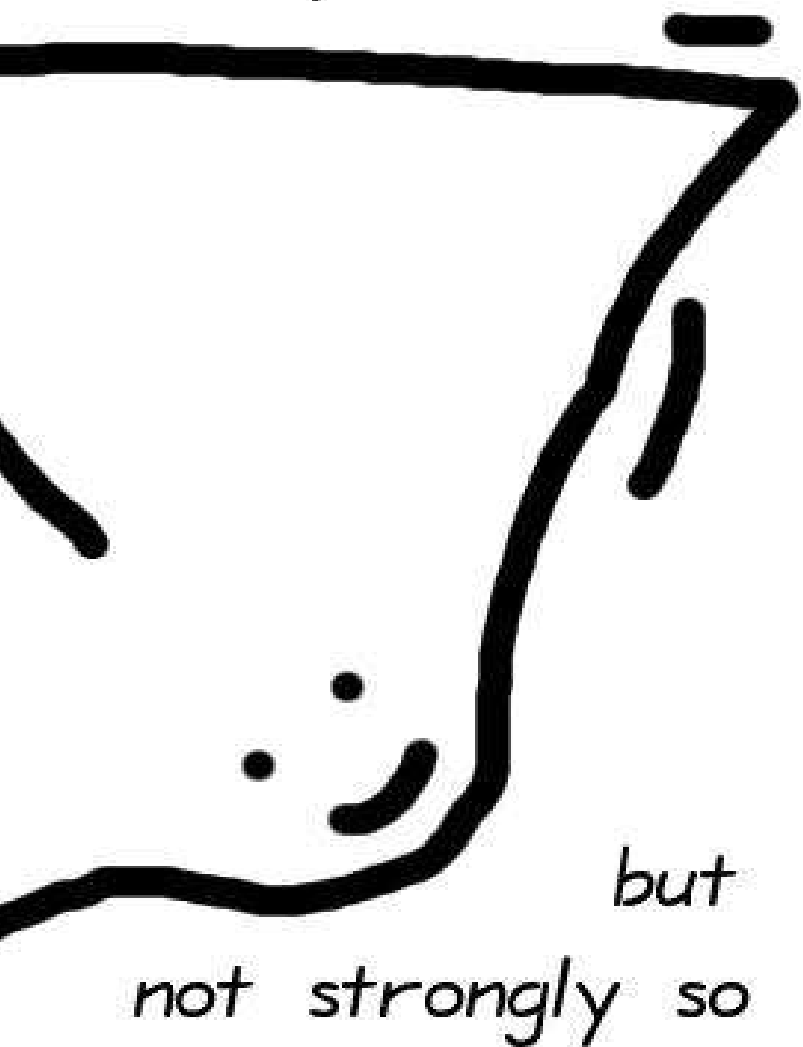
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Jacobi intersections

1986 Chudnovsky–Chudnovsky:

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“Tremendous advantage”
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“Perhaps (?) ... the most
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coefficients of an elliptic curve.”

2001 Liardet–Sm

$$13\mathbf{M} + 2\mathbf{S} + 1\mathbf{D}$$

$$4\mathbf{M} + 3\mathbf{S} \text{ for DB}$$

2007 Bernstein–L

$$3\mathbf{M} + 4\mathbf{S} \text{ for DB}$$

2008.02 Hisil–Wc

$$13\mathbf{M} + 1\mathbf{S} + 2\mathbf{D}$$

$$2\mathbf{M} + 5\mathbf{S} + 1\mathbf{D} \text{ f}$$

Also $(S : C : D :$

$$11\mathbf{M} + 1\mathbf{S} + 2\mathbf{D}$$

$$2\mathbf{M} + 5\mathbf{S} + 1\mathbf{D} \text{ f}$$

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*but
strongly so*

Jacobi intersections

1986 Chudnovsky–Chudnovsky:

$(S : C : D : Z)$ represent
 $(S/Z, C/Z, D/Z)$ on
 $s^2 + c^2 = 1, as^2 + d^2 = 1.$

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2001 Liardet–Smart:

13M + 2S + 1D for ADD.

4M + 3S for DBL.

2007 Bernstein–Lange:

3M + 4S for DBL.

2008.02 Hisil–Wong–Carter

13M + 1S + 2D for ADD.

2M + 5S + 1D for DBL.

Also $(S : C : D : Z : SC :$

11M + 1S + 2D for ADD.

2M + 5S + 1D for DBL.

Jacobi intersections

1986 Chudnovsky–Chudnovsky:

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2M + 5S + 1D for DBL.

Also $(S : C : D : Z : SC : DZ)$:

11M + 1S + 2D for ADD.

2M + 5S + 1D for DBL.

intersections

Chudnovsky–Chudnovsky:

$(C : D : Z)$ represent
 $(C/Z, D/Z)$ on
 $x^2 = 1, as^2 + d^2 = 1.$

$2S + 1D$ for ADD.

“tremendous advantage”
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$3S$ for DBL.

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2001 Liardet–Smart:

$13M + 2S + 1D$ for ADD.

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$3M + 4S$ for DBL.

2008.02 Hisil–Wong–Carter–Dawson:

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Jacobi

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$$4\mathbf{M} + 3\mathbf{S} \text{ for DBL.}$$

2007 Bernstein–Lange:

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$$2\mathbf{M} + 5\mathbf{S} + 1\mathbf{D} \text{ for DBL.}$$

Jacobi quartics

$(X:Y:Z)$ represent

on $y^2 = x^4 + 2ax$

1986 Chudnovsky

$$3\mathbf{M} + 6\mathbf{S} + 2\mathbf{D} \text{ f}$$

Slow ADD.

2002 Billet–Joye:

New choice of ne

$$10\mathbf{M} + 3\mathbf{S} + 1\mathbf{D}$$

strongly unified.

2007 Bernstein–L

$$1\mathbf{M} + 9\mathbf{S} + 1\mathbf{D} \text{ f}$$

2001 Liardet–Smart:

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2007 Bernstein–Lange:

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2008.02 Hisil–Wong–Carter–Dawson:

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$2\mathbf{M} + 5\mathbf{S} + 1\mathbf{D}$ for DBL.

Jacobi quartics

$(X:Y:Z)$ represent $(X/Z, Y/Z)$ on $y^2 = x^4 + 2ax^2 + 1$.

1986 Chudnovsky–Chudnovsky:

$3\mathbf{M} + 6\mathbf{S} + 2\mathbf{D}$ for DBL.

Slow ADD.

2002 Billet–Joye:

New choice of neutral element

$10\mathbf{M} + 3\mathbf{S} + 1\mathbf{D}$ for ADD,
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2007 Bernstein–Lange:

$1\mathbf{M} + 9\mathbf{S} + 1\mathbf{D}$ for DBL.

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2007 Bernstein–Lange:

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iardet–Smart:

$2\mathbf{S} + 1\mathbf{D}$ for ADD.

$3\mathbf{S}$ for DBL.

Bernstein–Lange:

$4\mathbf{S}$ for DBL.

2 Hisil–Wong–Carter–Dawson:

$1\mathbf{S} + 2\mathbf{D}$ for ADD.

$5\mathbf{S} + 1\mathbf{D}$ for DBL.

$(S : C : D : Z : SC : DZ)$:

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2007 Bernstein–Lange:

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Jacobi quartics

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1986 Chudnovsky–Chudnovsky:

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New choice of neutral element.

10M + 3S + 1D for ADD,

strongly unified.

2007 Bernstein–Lange:

1M + 9S + 1D for DBL.

2007 Hisil–Carter

2M + 6S + 2D f

2007 Feng–Wu:

2M + 6S + 1D f

1M + 7S + 3D f

on curves chosen

More speedups:

2007 Hisil–Carter

2008.02 Hisil–Wo

use $(X : Y : Z : X$

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Jacobi quartics

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2M + 6S + 2D for DBL.

2007 Feng–Wu:

2M + 6S + 1D for DBL.

1M + 7S + 3D for DBL

on curves chosen with $a^2 + 4$

More speedups: 2007 Duq

2007 Hisil–Carter–Dawson,

2008.02 Hisil–Wong–Carter

use $(X : Y : Z : X^2 : Z^2)$

or $(X : Y : Z : X^2 : Z^2 : 2XZ)$

Can combine with Feng–Wu

Competitive with Edwards!

Jacobi quartics

$(X:Y:Z)$ represent $(X/Z, Y/Z^2)$
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1986 Chudnovsky–Chudnovsky:
3M + 6S + 2D for DBL.
Slow ADD.

2002 Billet–Joye:
New choice of neutral element.
10M + 3S + 1D for ADD,
strongly unified.

2007 Bernstein–Lange:
1M + 9S + 1D for DBL.

2007 Hisil–Carter–Dawson:
2M + 6S + 2D for DBL.

2007 Feng–Wu:
2M + 6S + 1D for DBL.
1M + 7S + 3D for DBL
on curves chosen with $a^2 + c^2 = 1$.

More speedups: 2007 Duquesne,
2007 Hisil–Carter–Dawson,
2008.02 Hisil–Wong–Carter–Dawson:
use $(X : Y : Z : X^2 : Z^2)$
or $(X : Y : Z : X^2 : Z^2 : 2XZ)$.
Can combine with Feng–Wu.
Competitive with Edwards!

quartics

(Z) represent $(X/Z, Y/Z^2)$
 $= x^4 + 2ax^2 + 1.$

Chudnovsky–Chudnovsky:

$6\mathbf{S} + 2\mathbf{D}$ for DBL.

ADD.

Billet–Joye:

choice of neutral element.

$3\mathbf{S} + 1\mathbf{D}$ for ADD,

very unified.

Bernstein–Lange:

$9\mathbf{S} + 1\mathbf{D}$ for DBL.

2007 Hisil–Carter–Dawson:

$2\mathbf{M} + 6\mathbf{S} + 2\mathbf{D}$ for DBL.

2007 Feng–Wu:

$2\mathbf{M} + 6\mathbf{S} + 1\mathbf{D}$ for DBL.

$1\mathbf{M} + 7\mathbf{S} + 3\mathbf{D}$ for DBL

on curves chosen with $a^2 + c^2 = 1.$

More speedups: 2007 Duquesne,

2007 Hisil–Carter–Dawson,

2008.02 Hisil–Wong–Carter–Dawson:

use $(X : Y : Z : X^2 : Z^2)$

or $(X : Y : Z : X^2 : Z^2 : 2XZ).$

Can combine with Feng–Wu.

Competitive with Edwards!

$$x^2 = y$$

point $(X/Z, Y/Z^2)$
 $x^2 + 1$.

Miller–Chudnovsky:
for DBL.

Neutral element.
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2007 Hisil–Carter–Dawson:
 $2\mathbf{M} + 6\mathbf{S} + 2\mathbf{D}$ for DBL.

2007 Feng–Wu:

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More speedups: 2007 Duquesne,

2007 Hisil–Carter–Dawson,

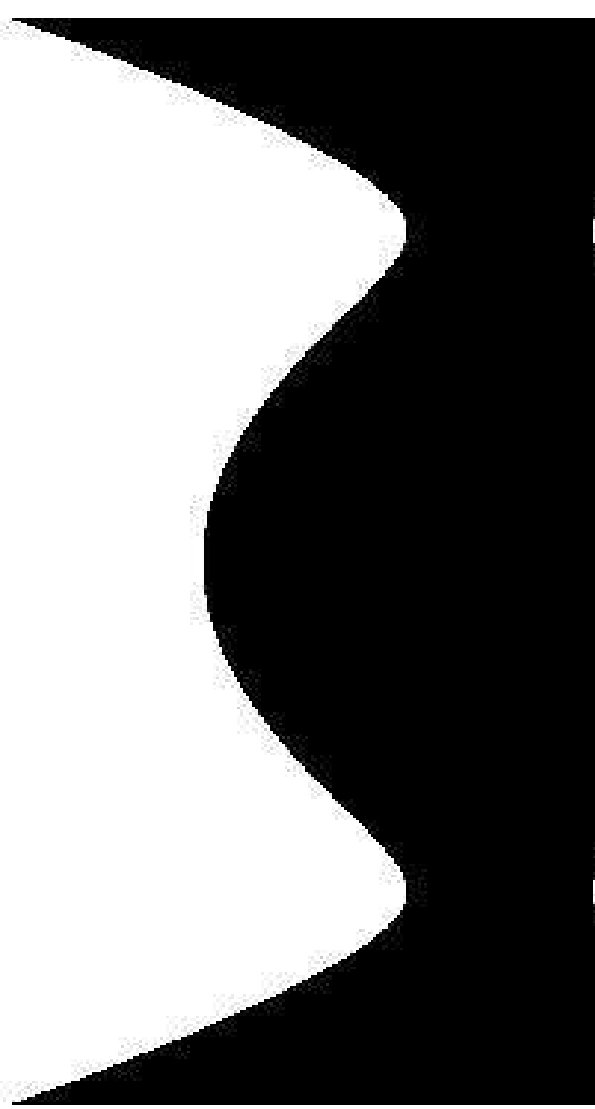
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Can combine with Feng–Wu.

Competitive with Edwards!


$$x^2 = y^4 - 1.9y^2$$

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2007 Hisil–Carter–Dawson:

$2\mathbf{M} + 6\mathbf{S} + 2\mathbf{D}$ for DBL.

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$2\mathbf{M} + 6\mathbf{S} + 1\mathbf{D}$ for DBL.

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More speedups: 2007 Duquesne,

2007 Hisil–Carter–Dawson,

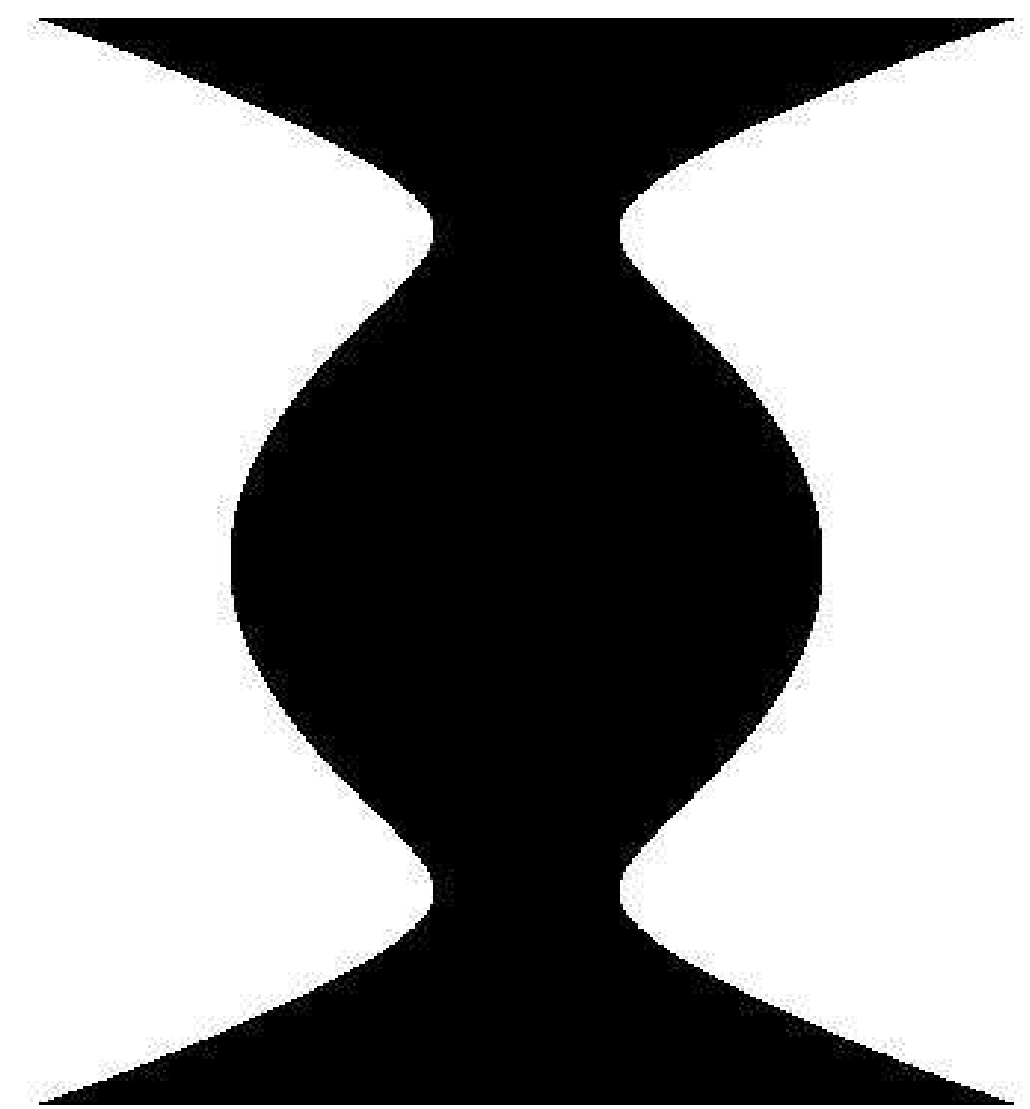
2008.02 Hisil–Wong–Carter–Dawson:

use $(X : Y : Z : X^2 : Z^2)$

or $(X : Y : Z : X^2 : Z^2 : 2XZ)$.

Can combine with Feng–Wu.

Competitive with Edwards!



$$x^2 = y^4 - 1.9y^2 + 1$$

2007 Hisil–Carter–Dawson:

$2\mathbf{M} + 6\mathbf{S} + 2\mathbf{D}$ for DBL.

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More speedups: 2007 Duquesne,

2007 Hisil–Carter–Dawson,

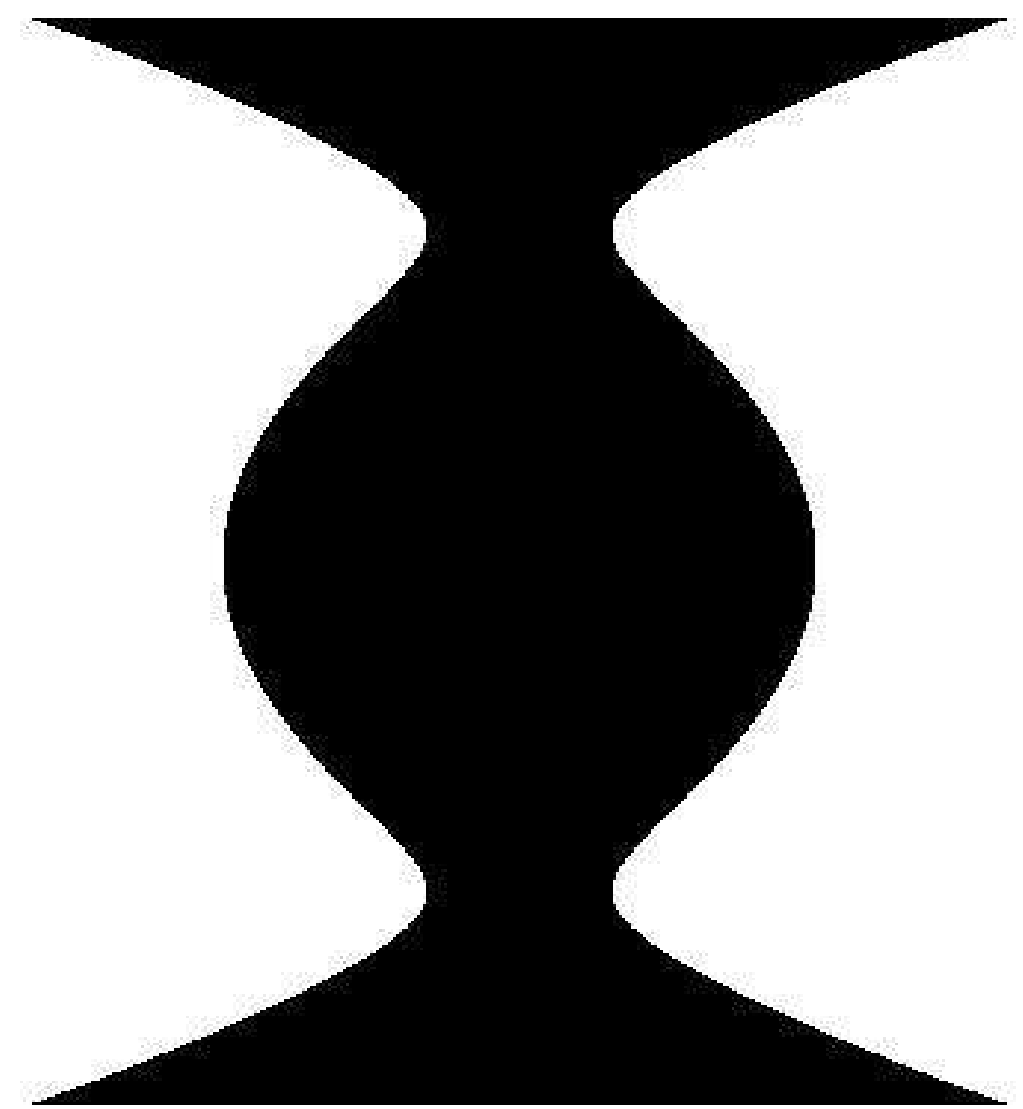
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Can combine with Feng–Wu.

Competitive with Edwards!



$$x^2 = y^4 - 1.9y^2 + 1$$

Hisil–Carter–Dawson:

$6\mathbf{S} + 2\mathbf{D}$ for DBL.

Feng–Wu:

$6\mathbf{S} + 1\mathbf{D}$ for DBL.

$7\mathbf{S} + 3\mathbf{D}$ for DBL

values chosen with $a^2 + c^2 = 1$.

speedups: 2007 Duquesne,

Hisil–Carter–Dawson,

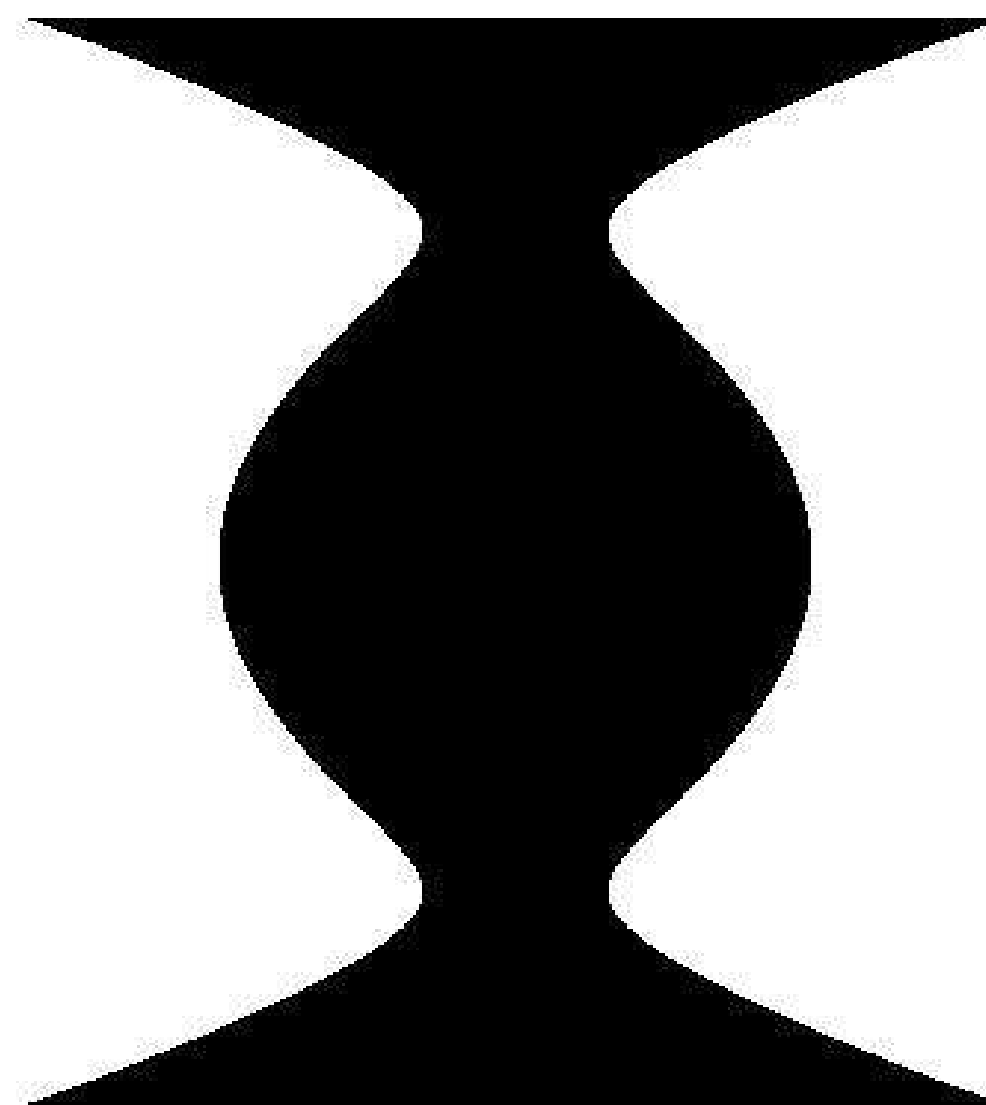
2 Hisil–Wong–Carter–Dawson:

($Y : Z : X^2 : Z^2$)

($Y : Z : X^2 : Z^2 : 2XZ$).

combine with Feng–Wu.

competitive with Edwards!



$$x^2 = y^4 - 1.9y^2 + 1$$

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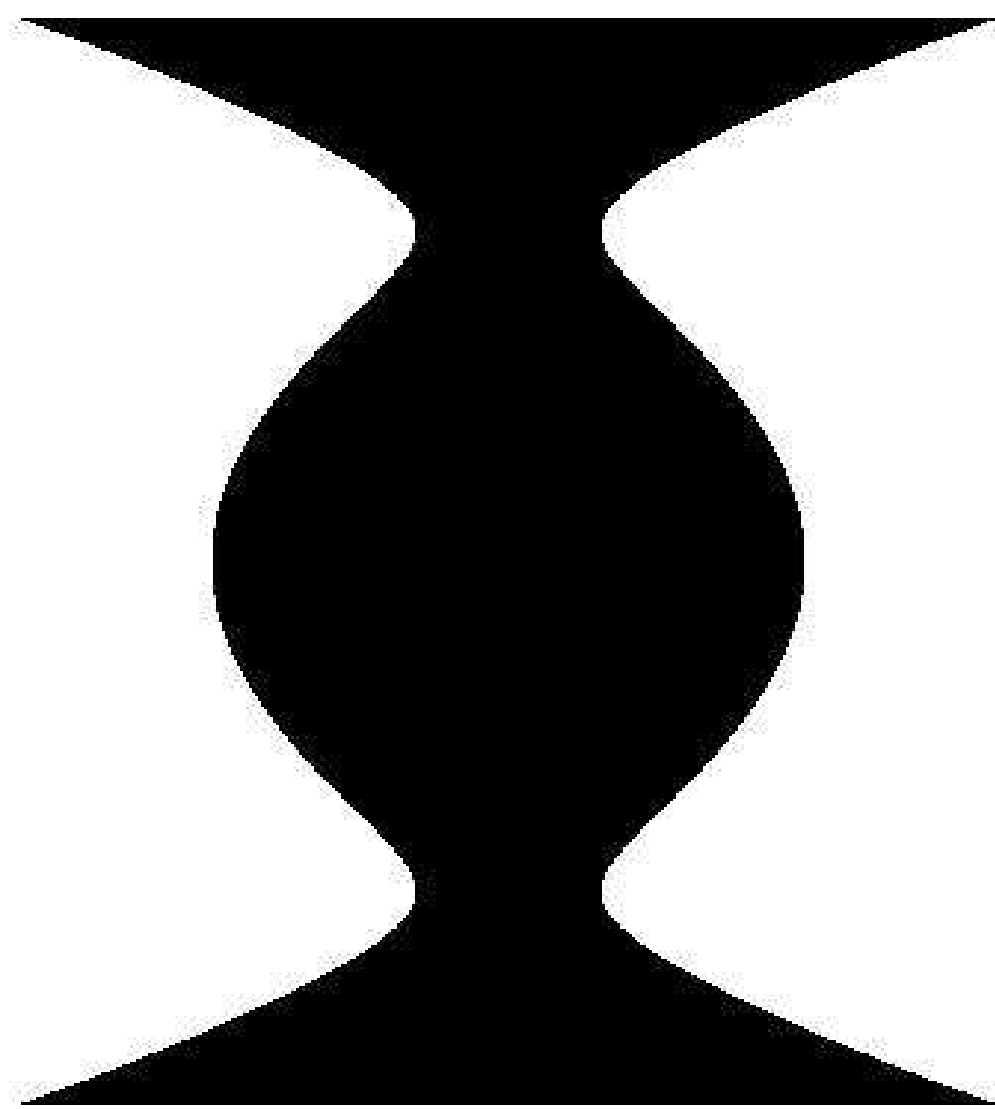
ong–Carter–Dawson:

$(X^2 : Z^2)$

$(Y^2 : Z^2 : 2XZ)$.

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Edwards!



$$x^2 = y^4 - 1.9y^2 + 1$$

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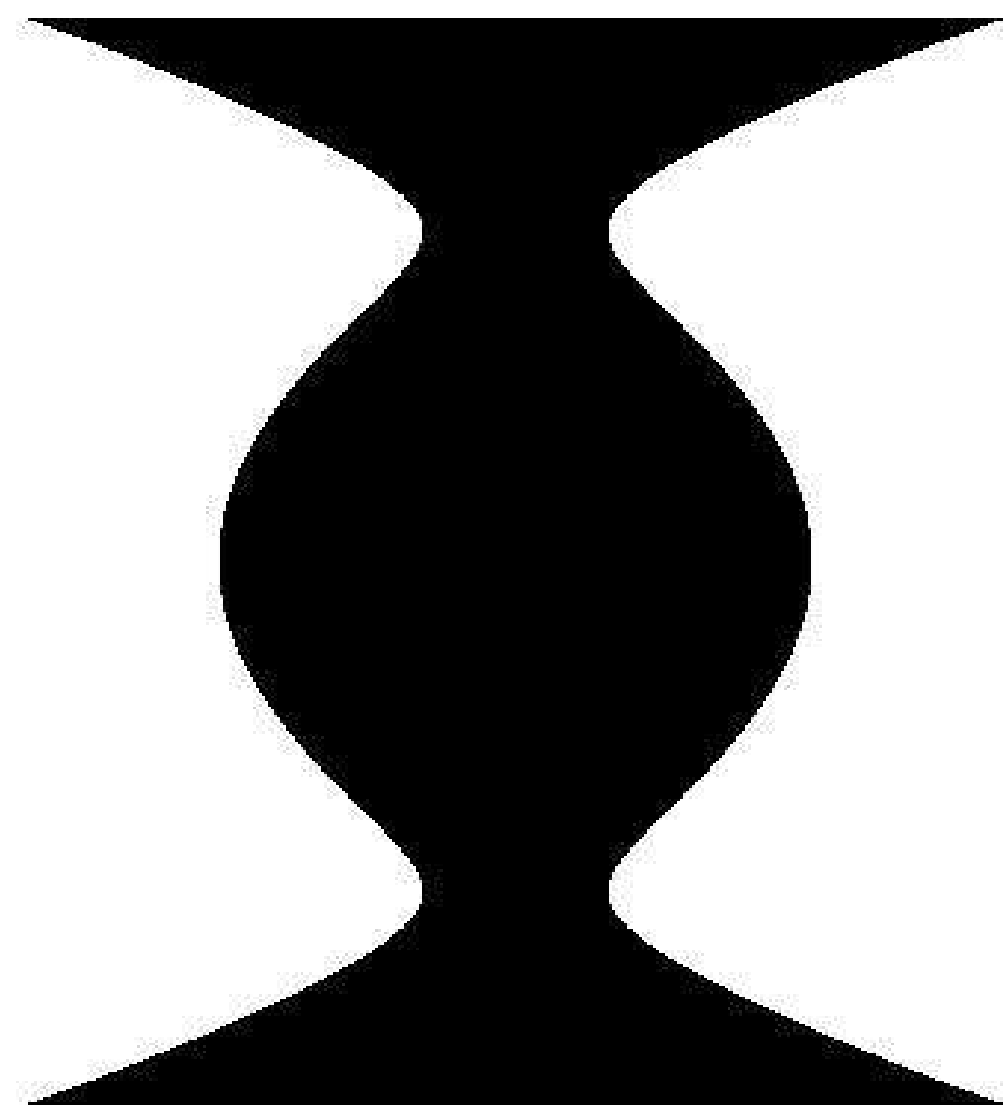
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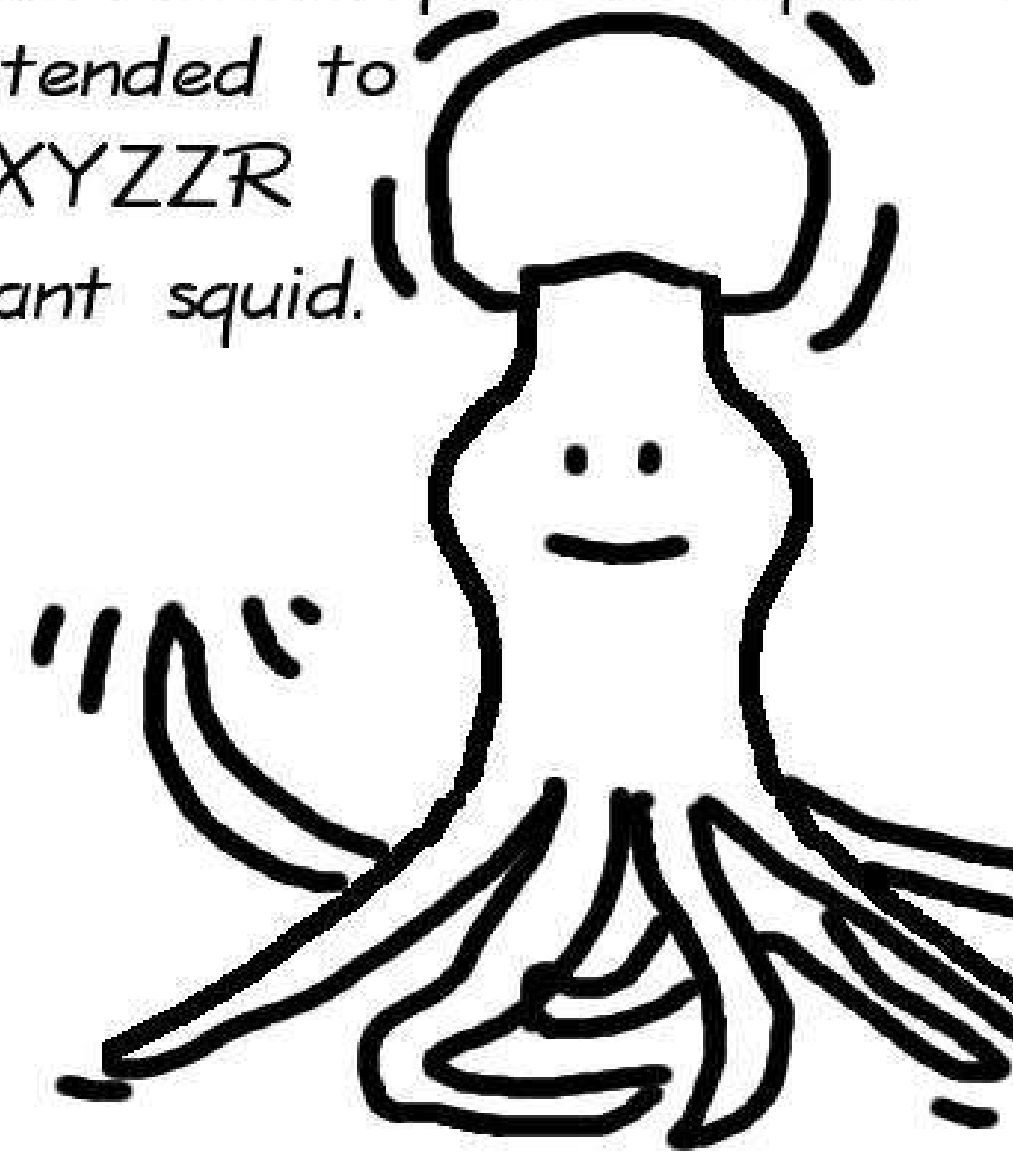
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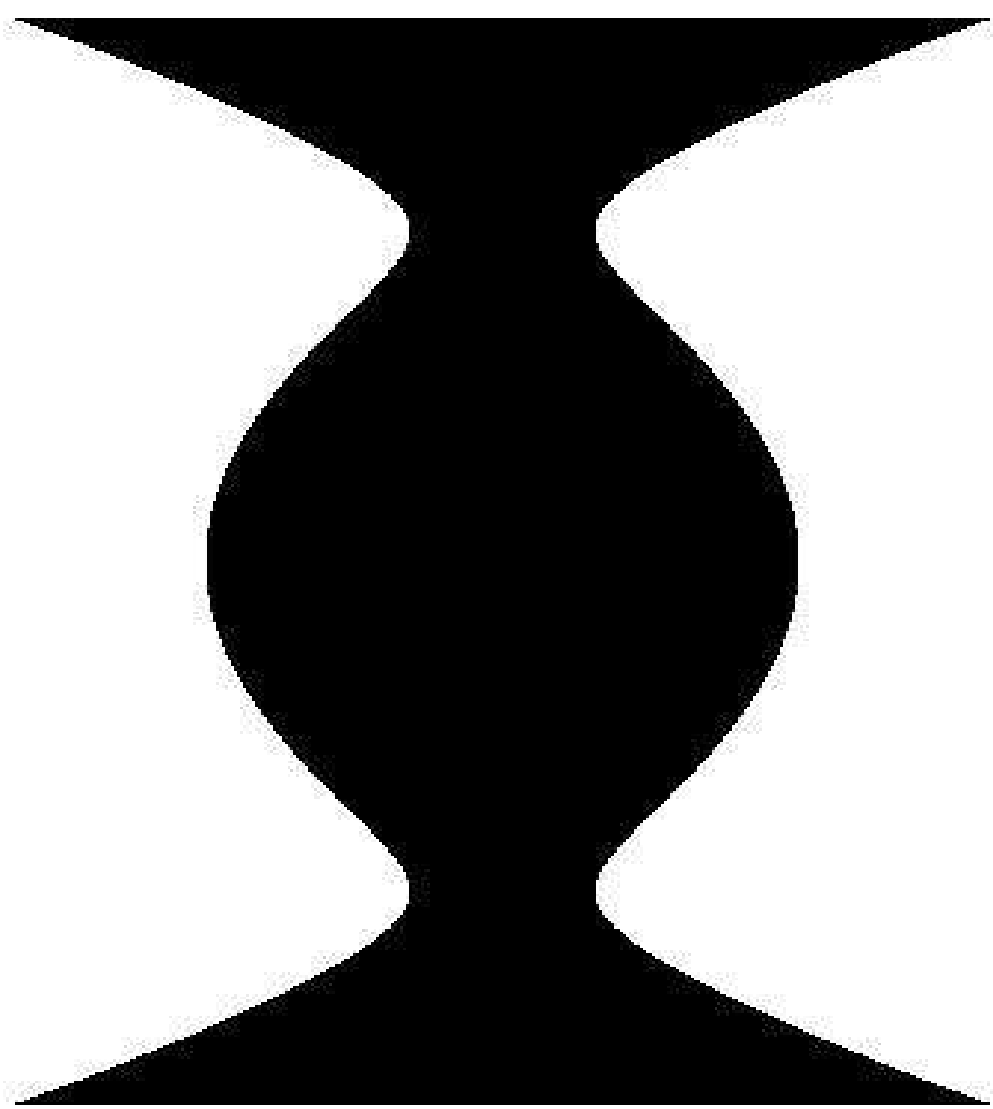
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$$x^2 = y^4 - 1.9y^2 + 1$$

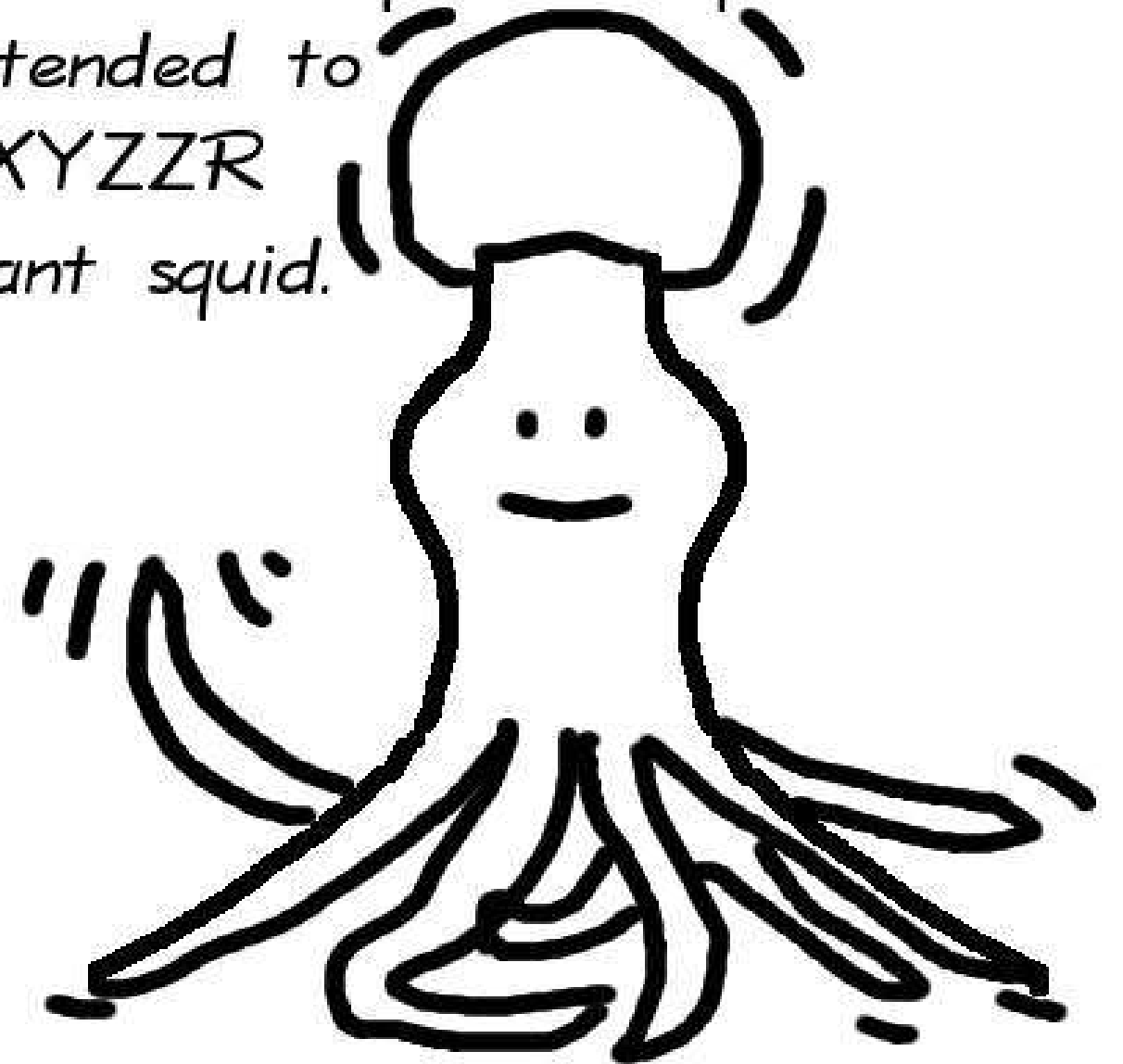
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extended to
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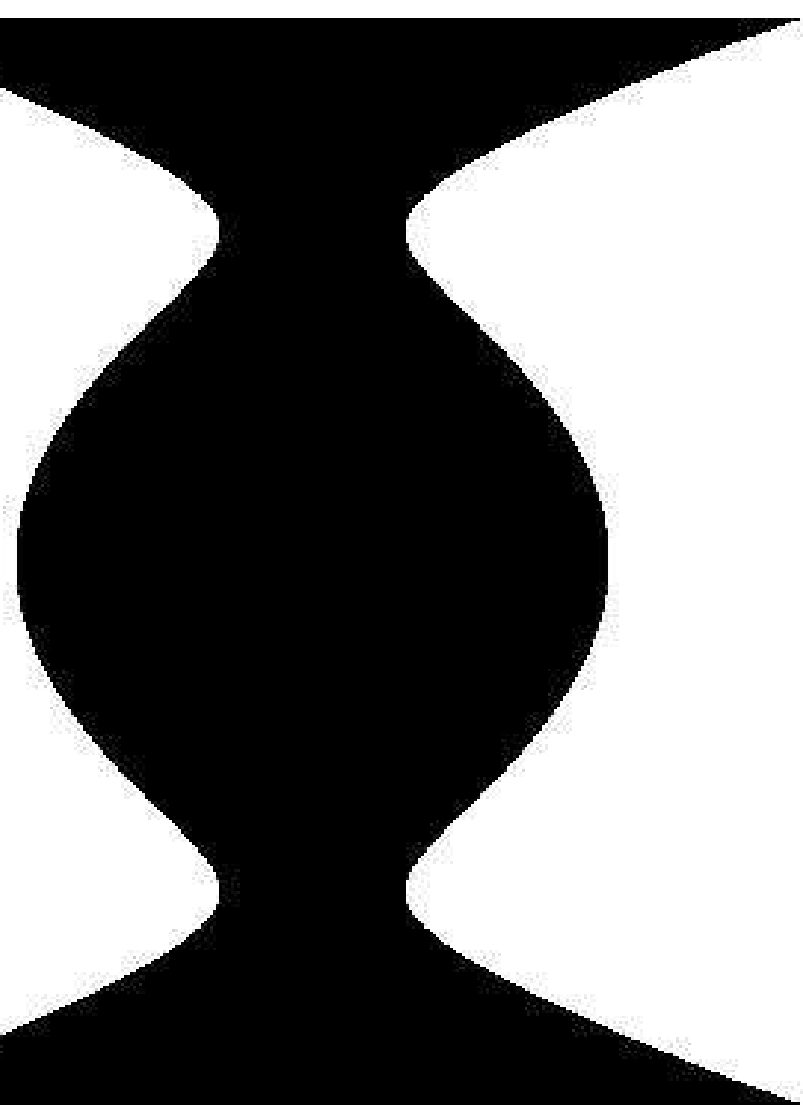




$$x^2 = y^4 - 1.9y^2 + 1$$

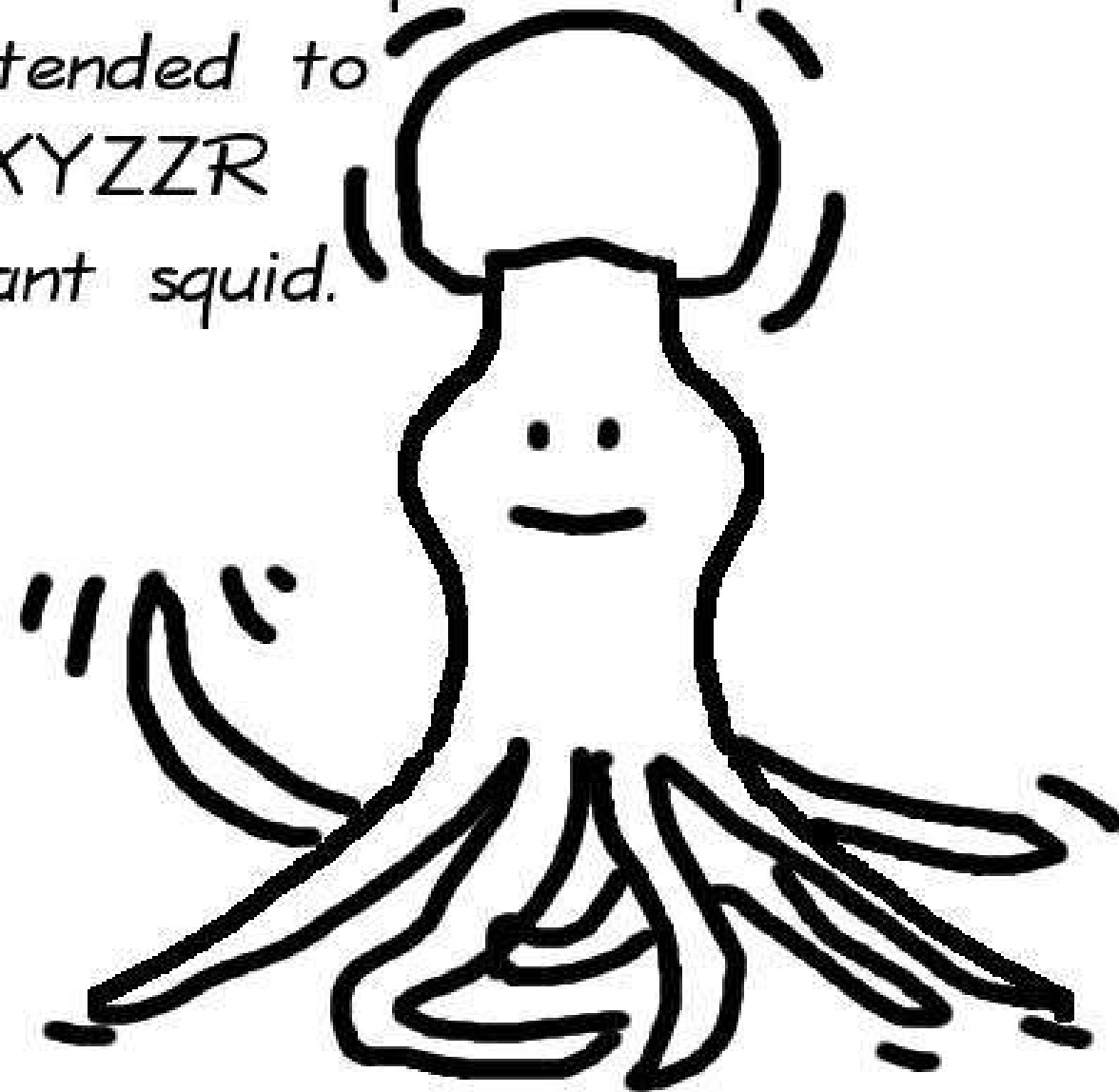
The Jacobi-quartic squid: can be
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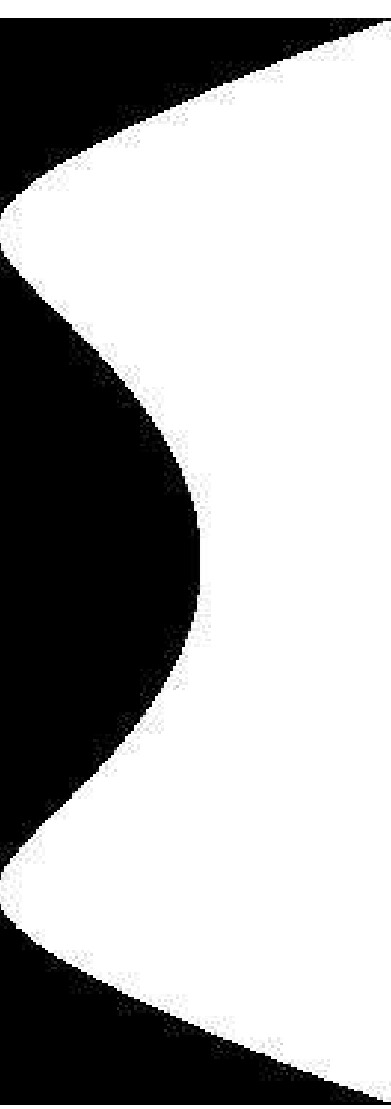




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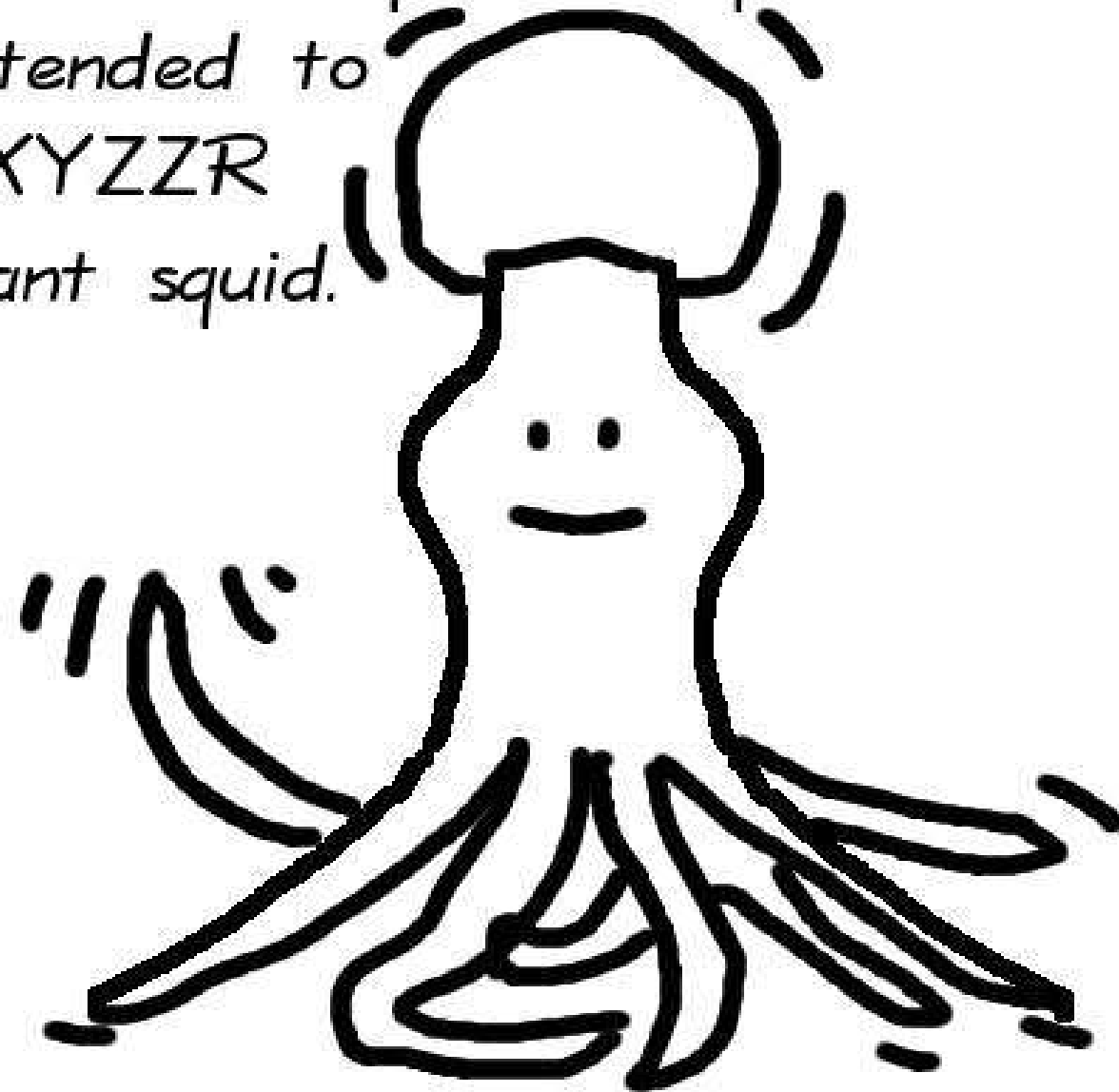
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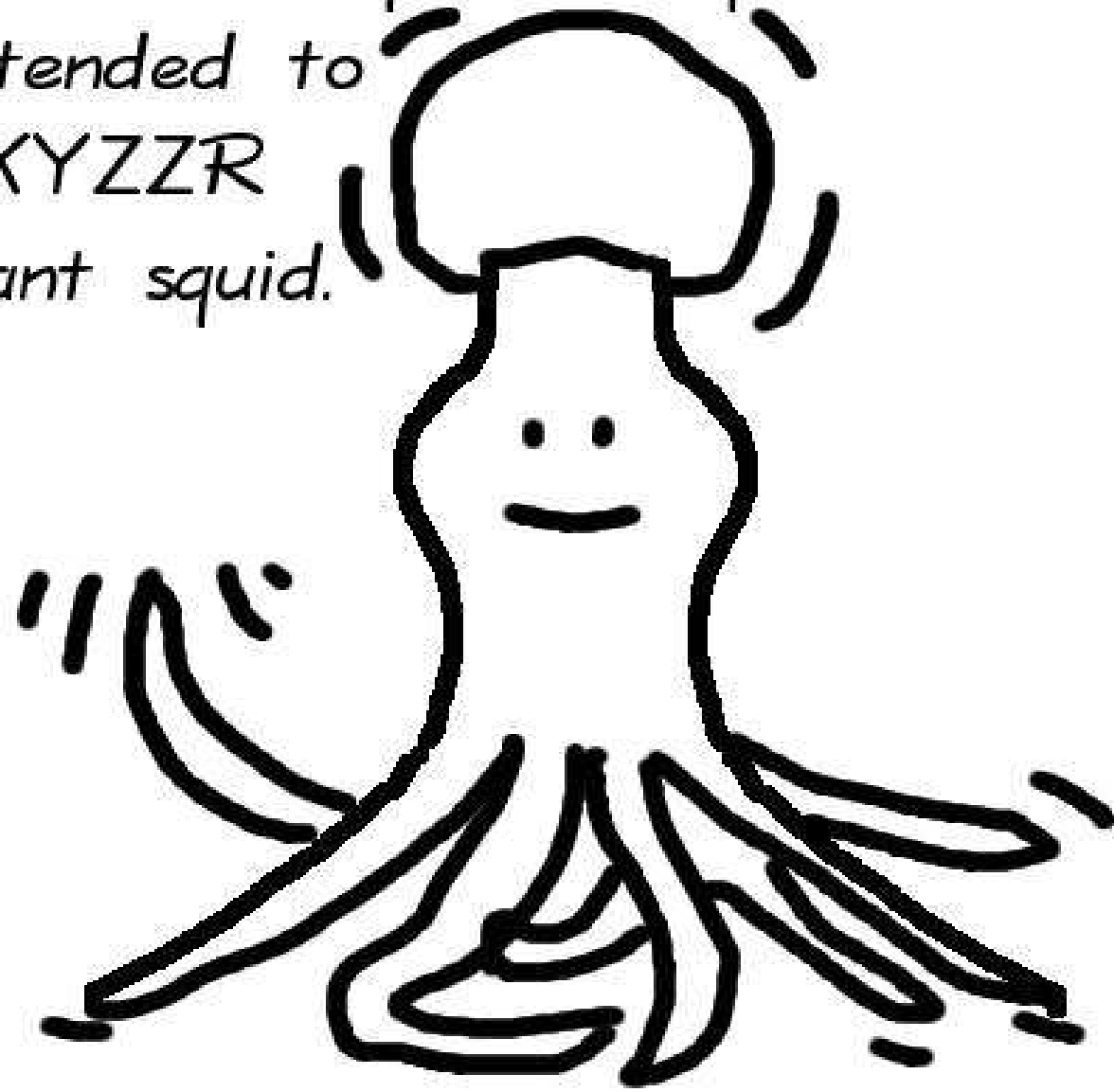


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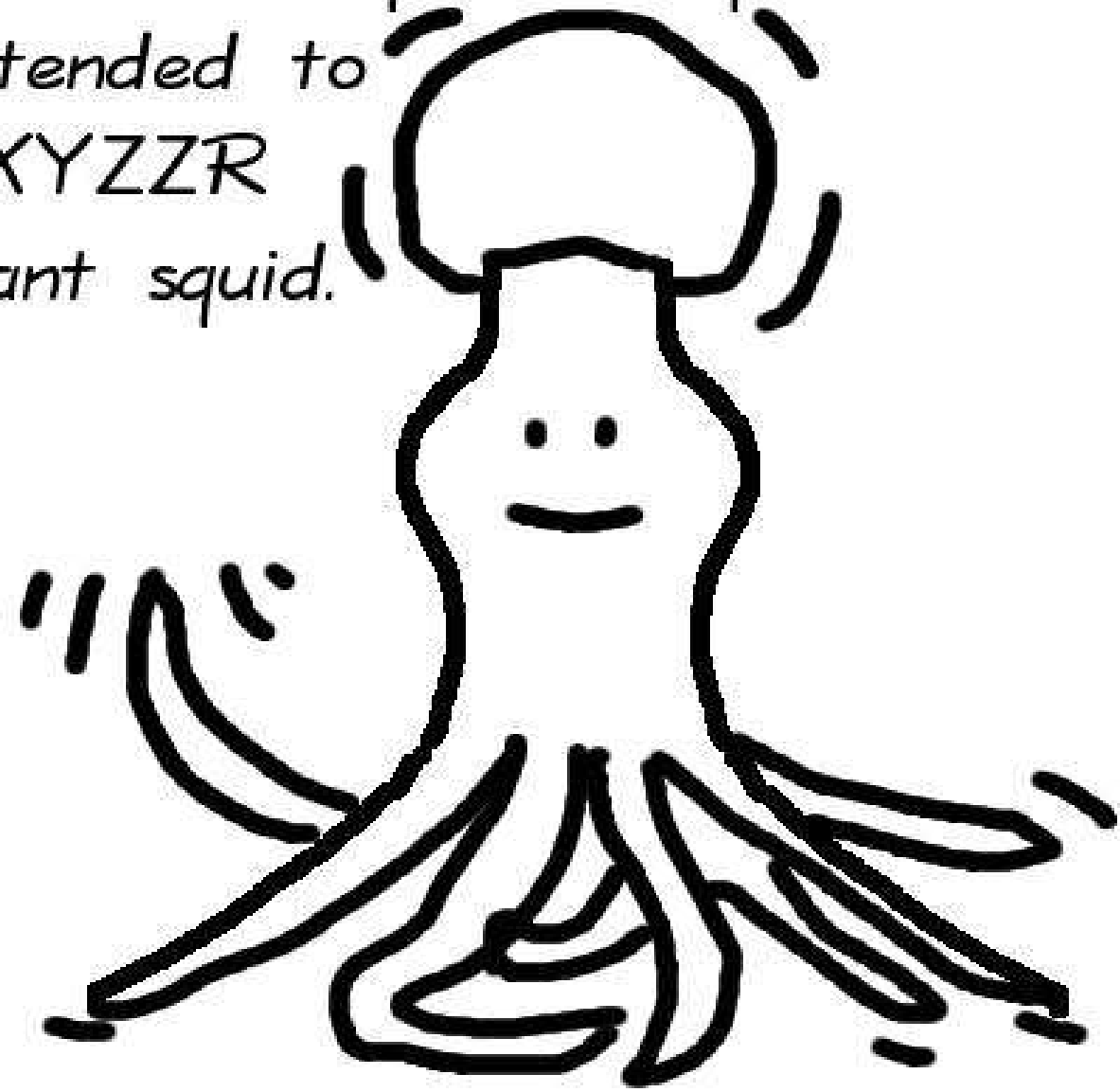
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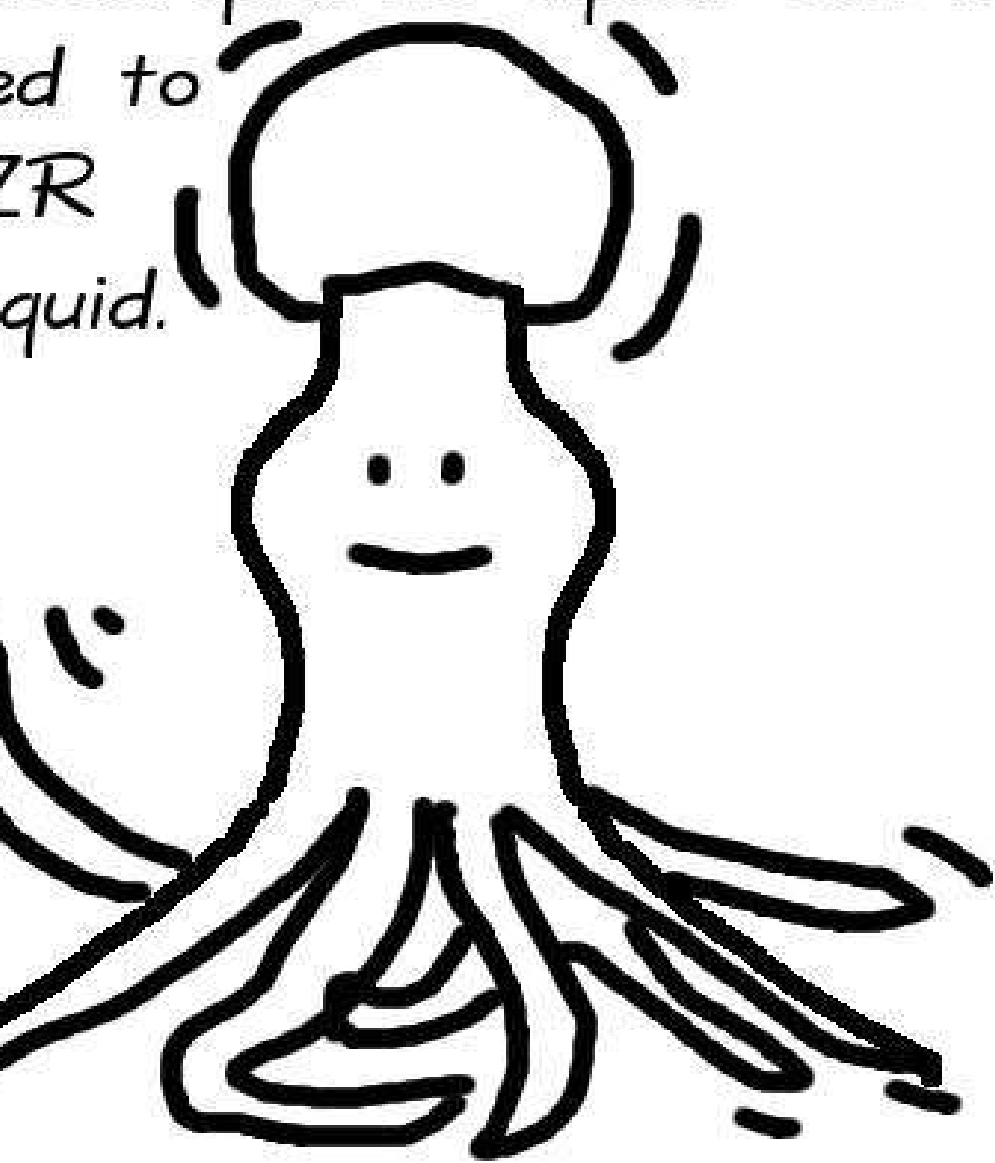
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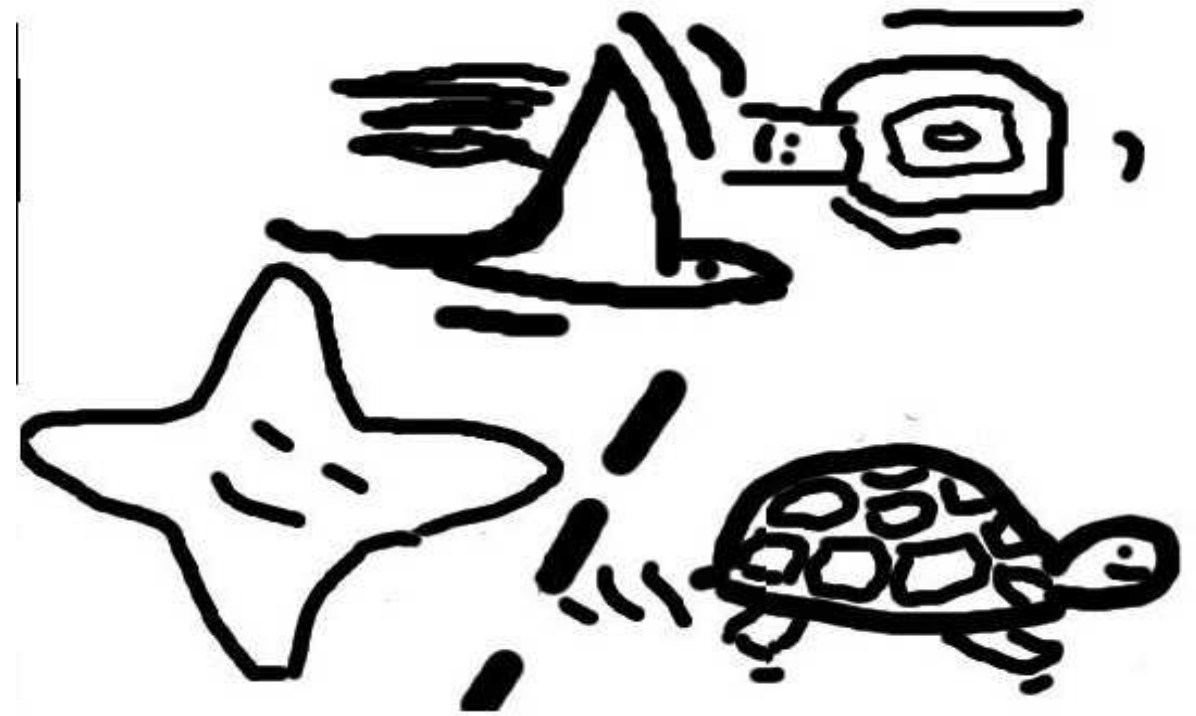


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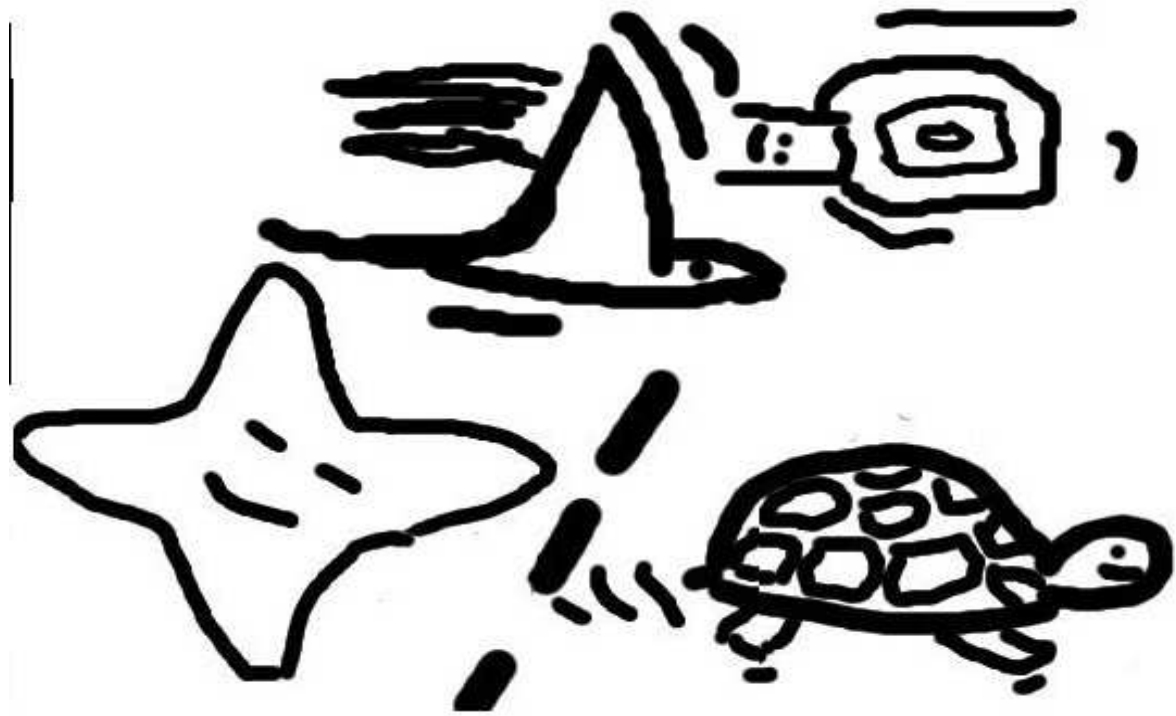


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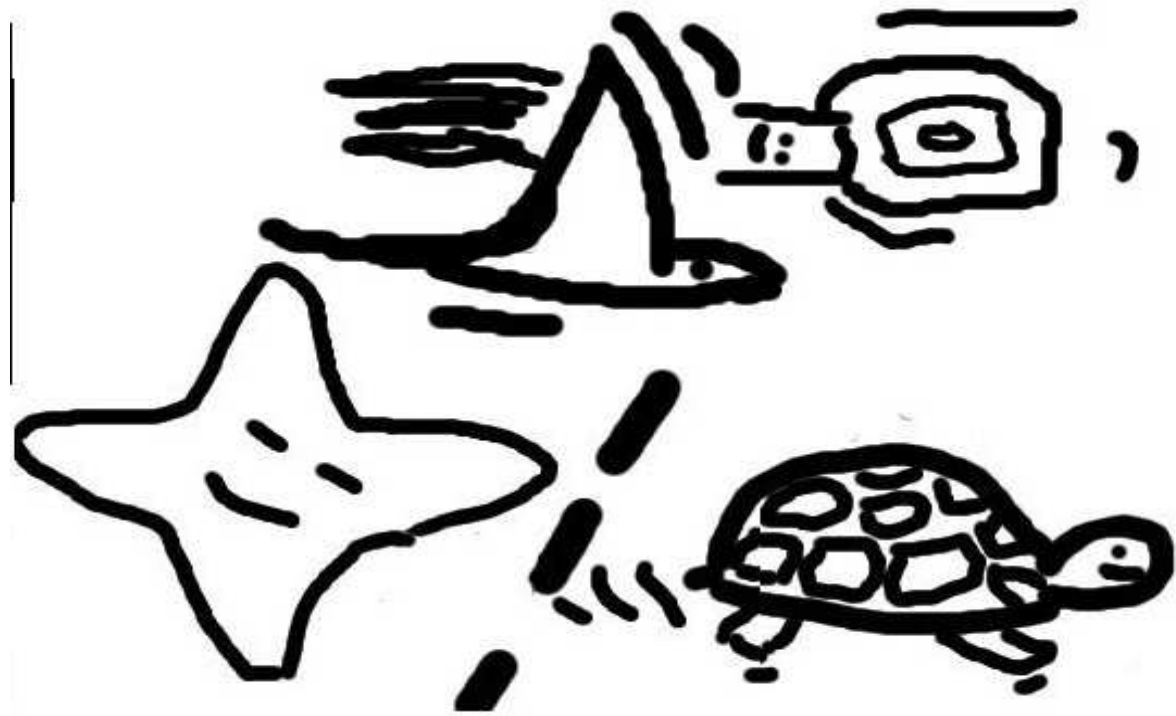
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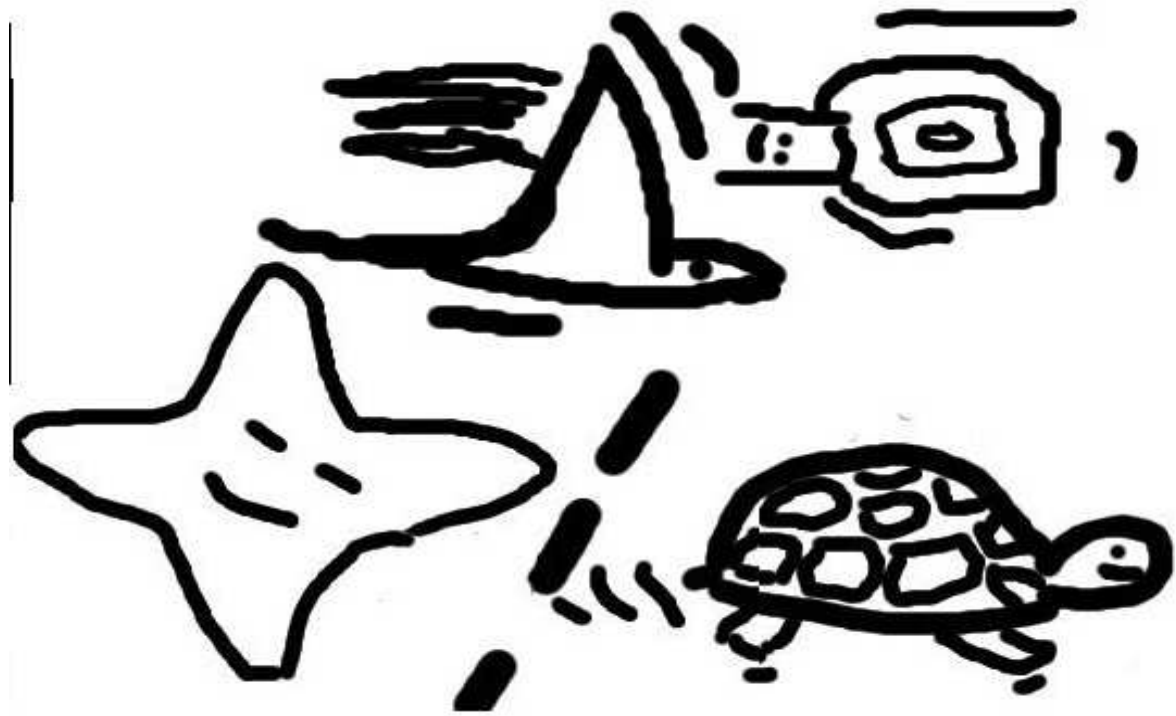
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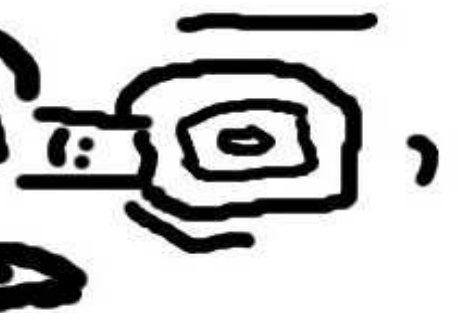


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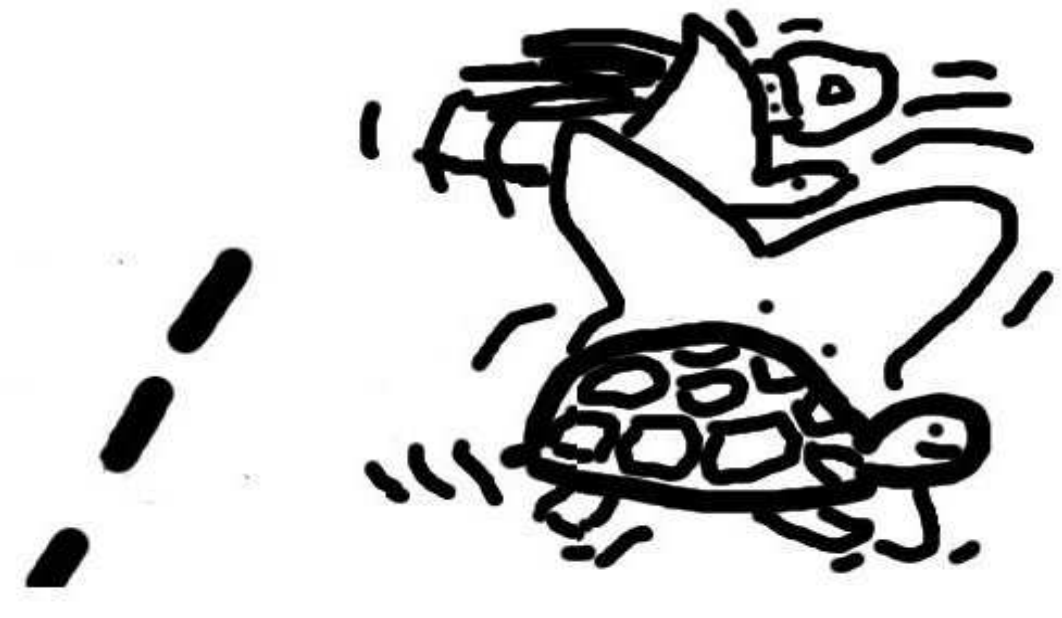
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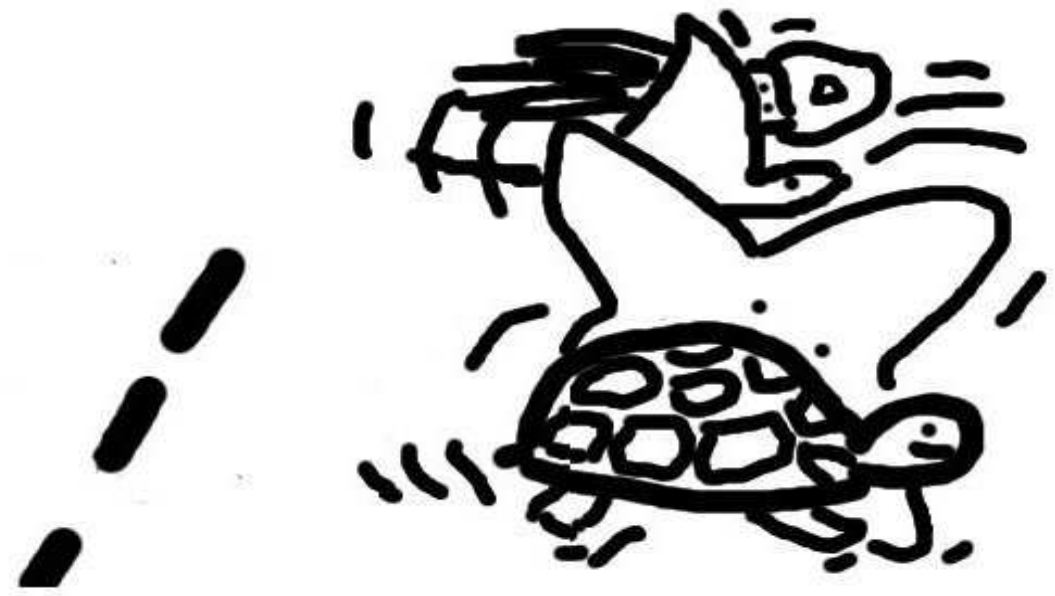
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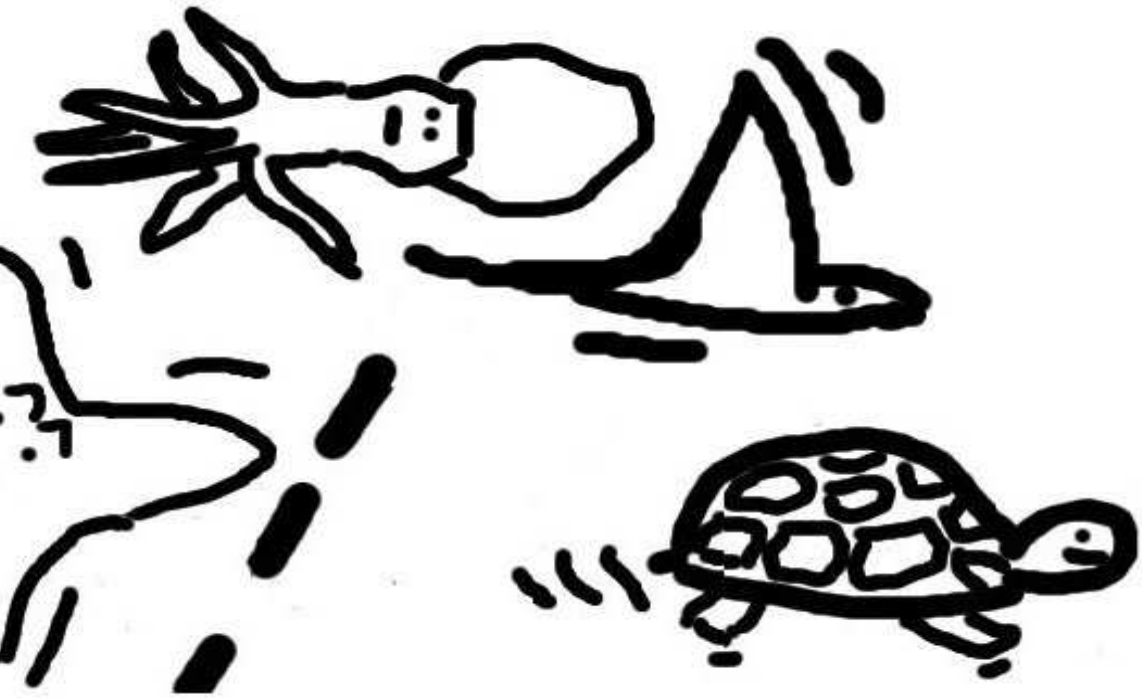
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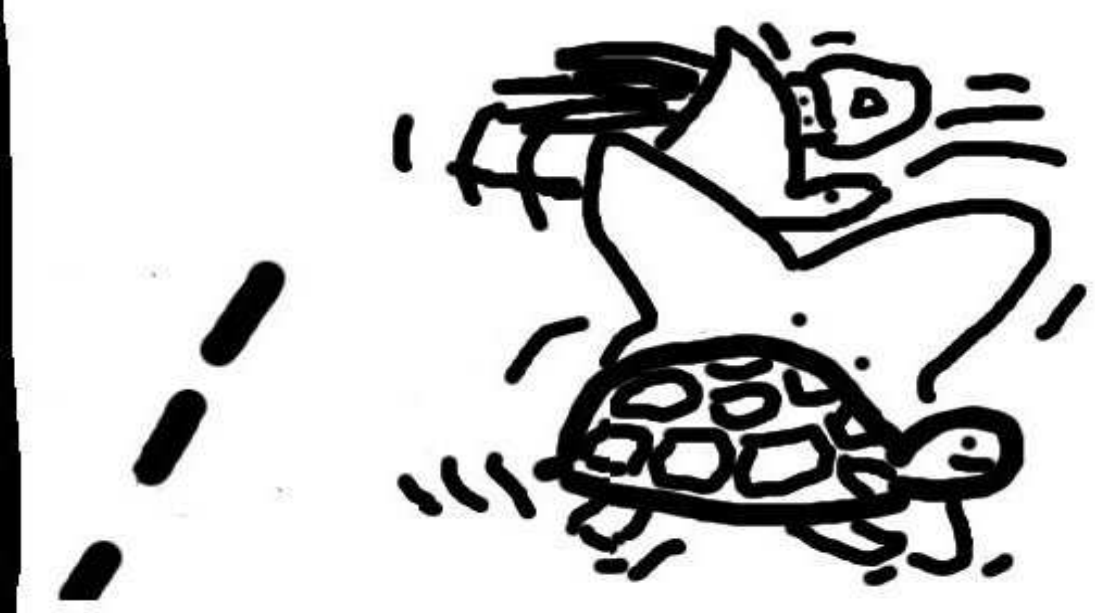
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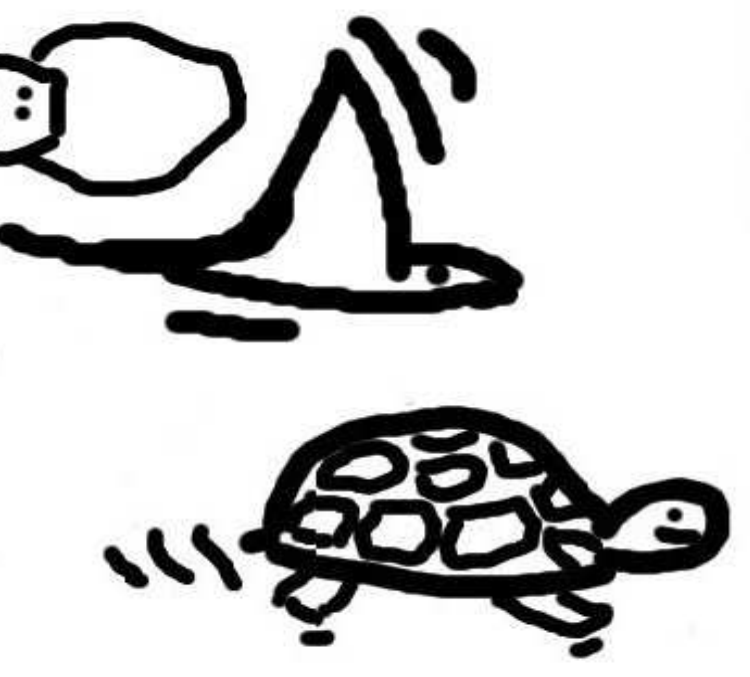
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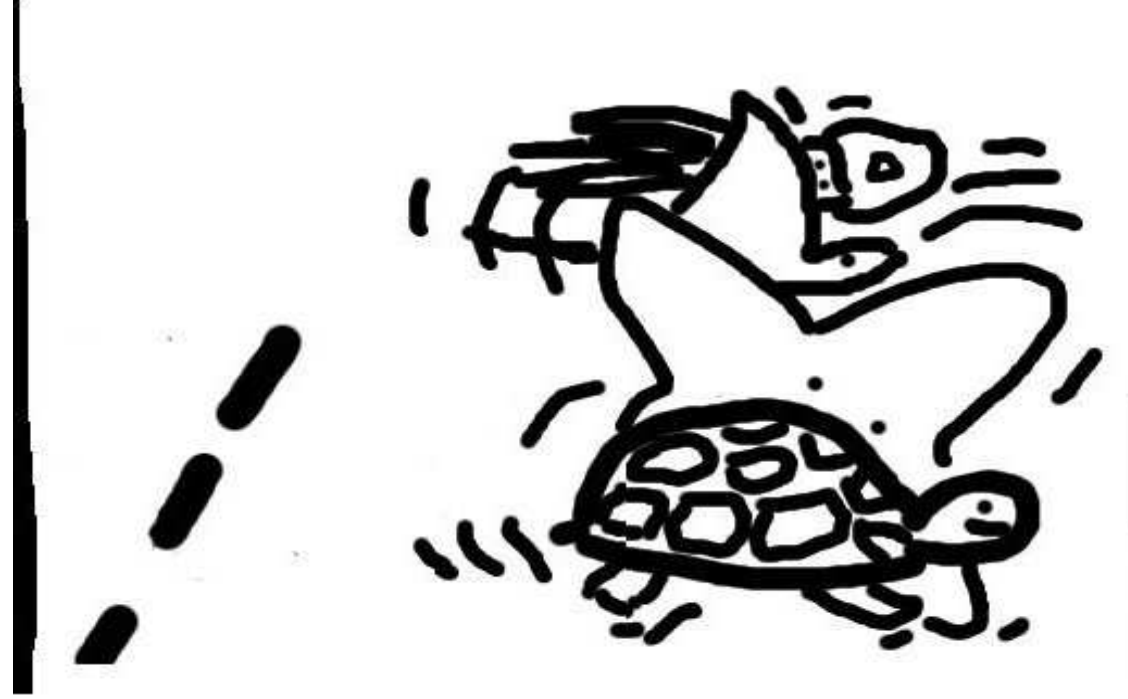
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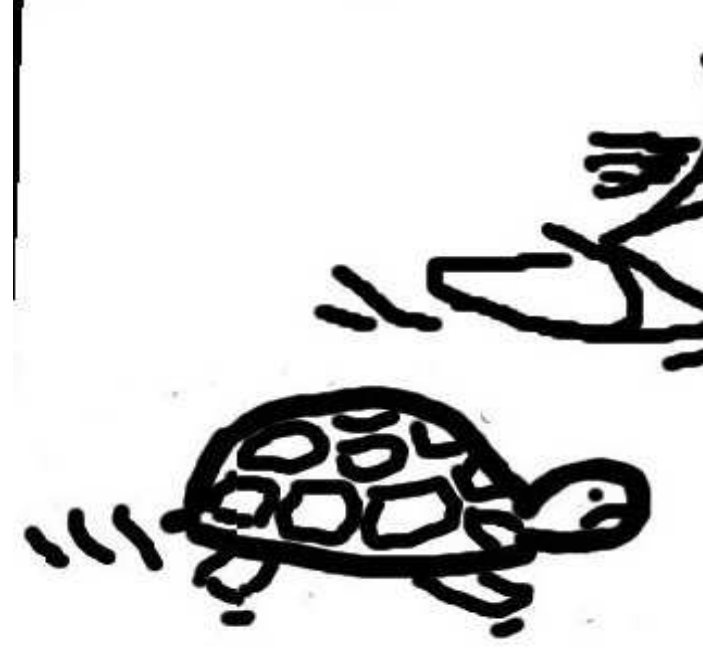
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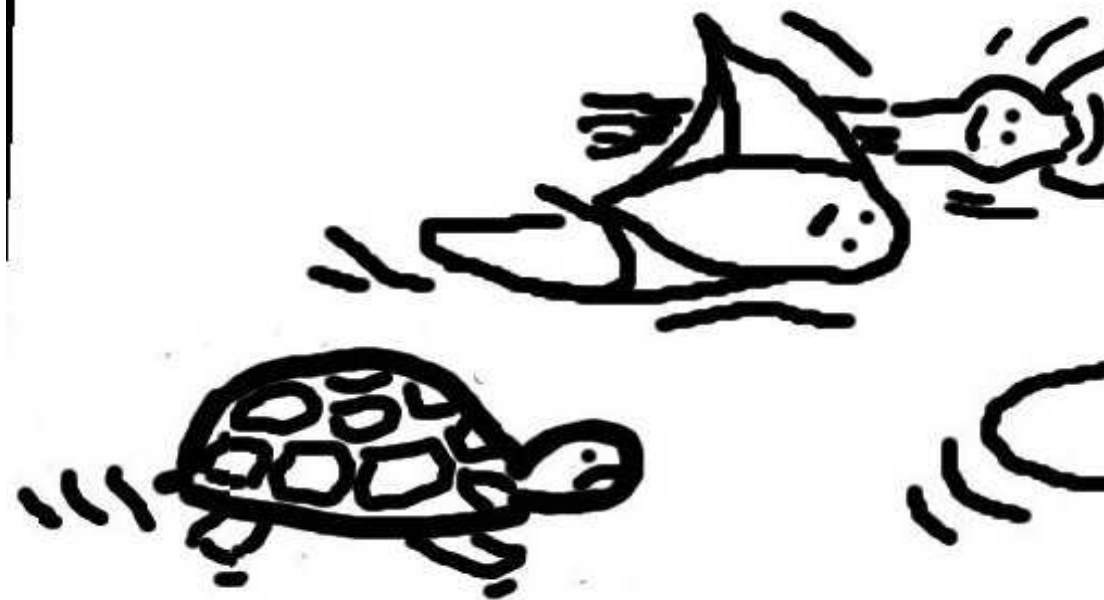




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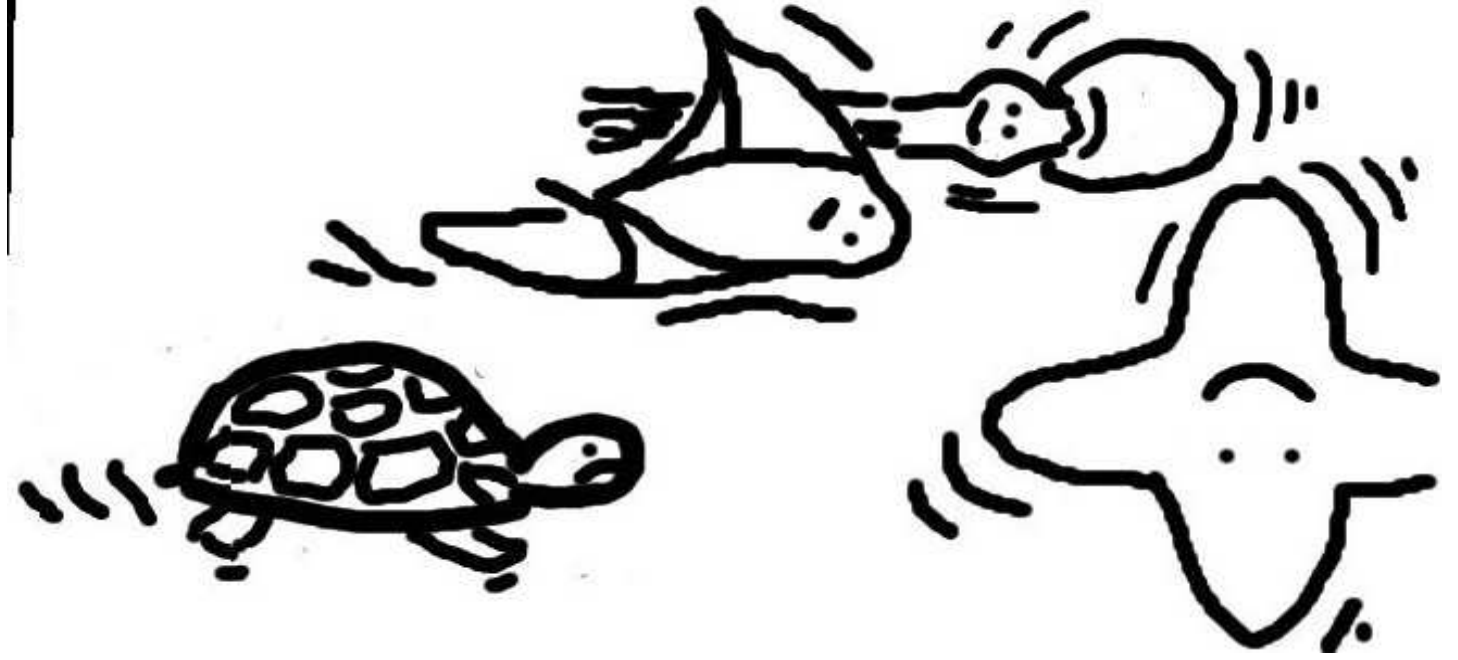
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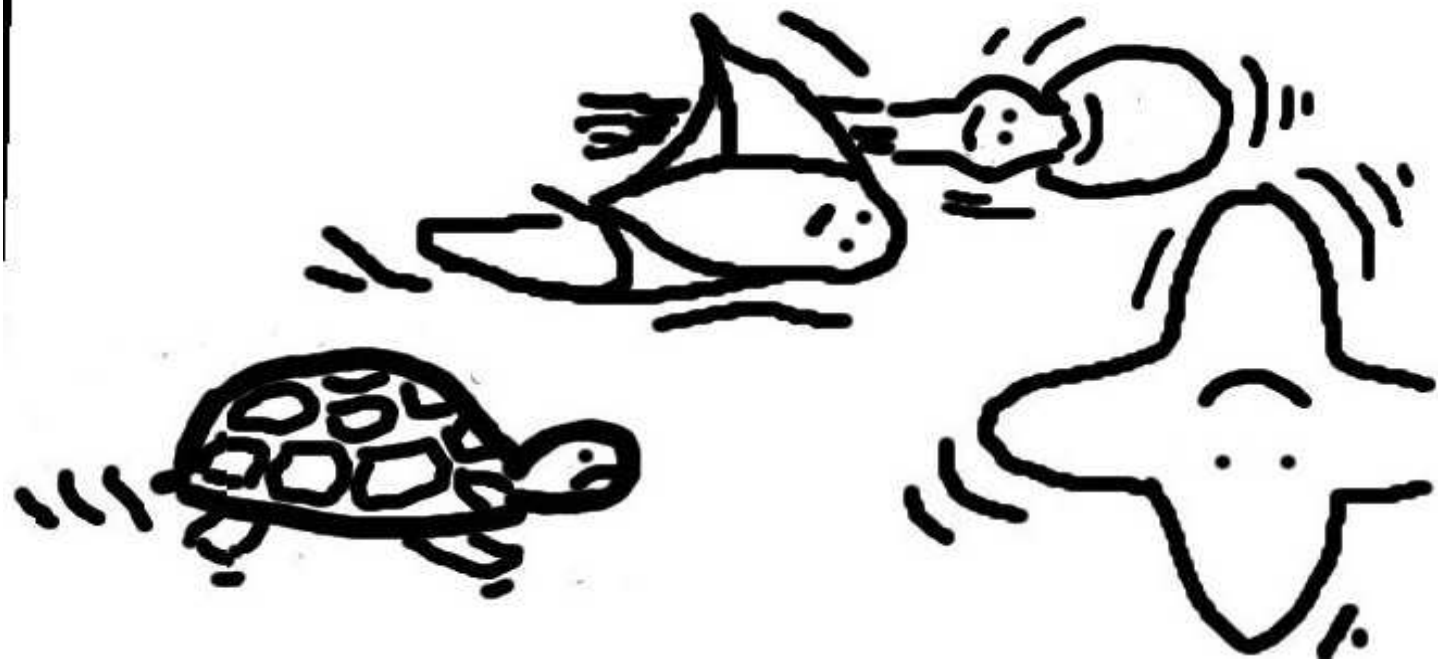
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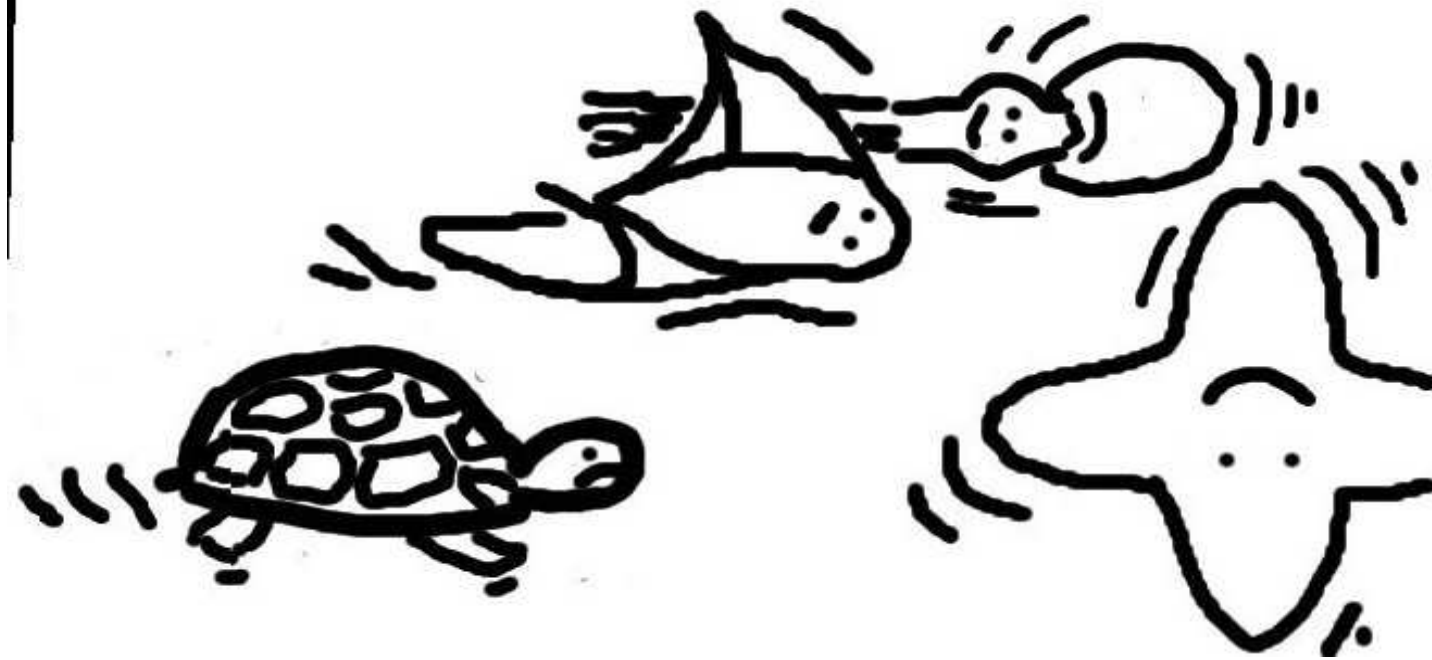
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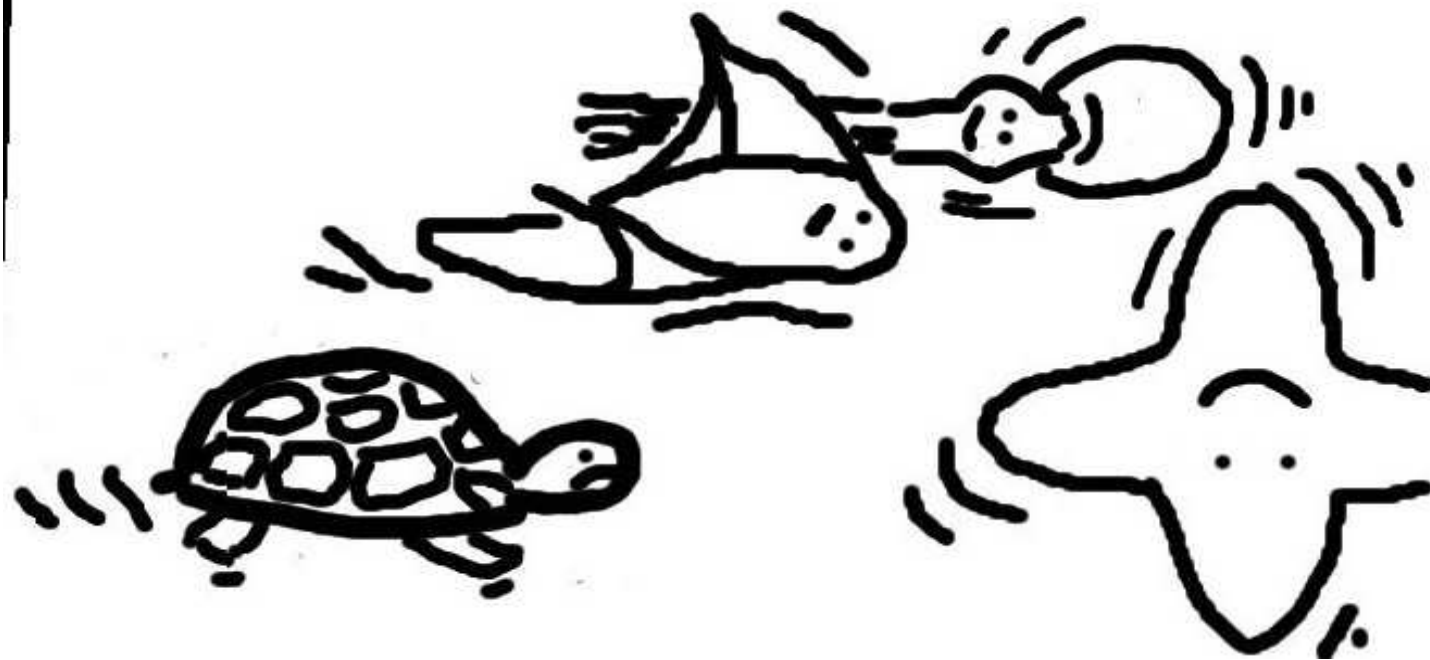
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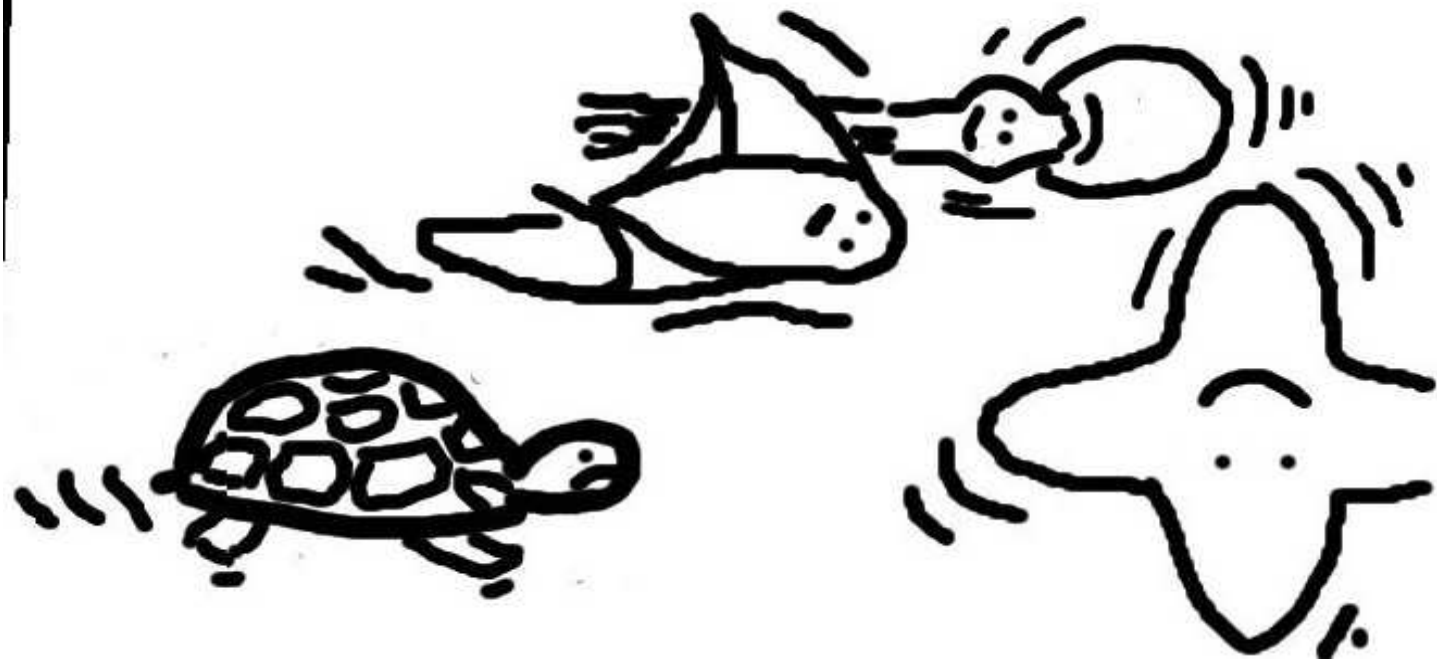
Explicit-Formulas Database
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hyperelliptic.org/EFD

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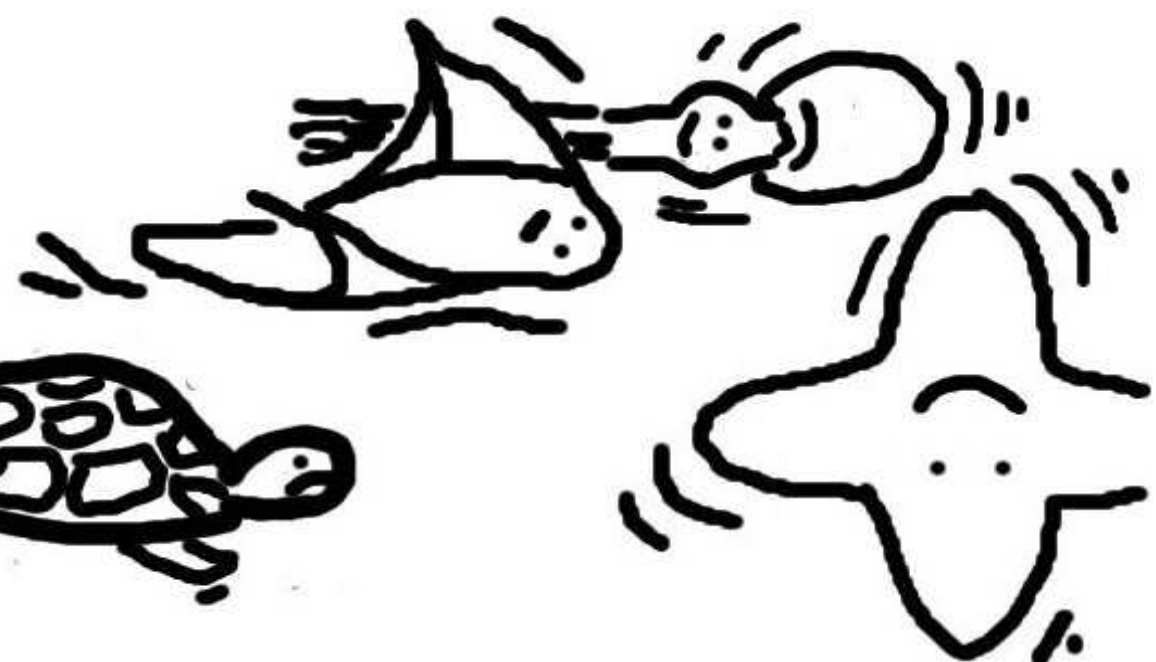
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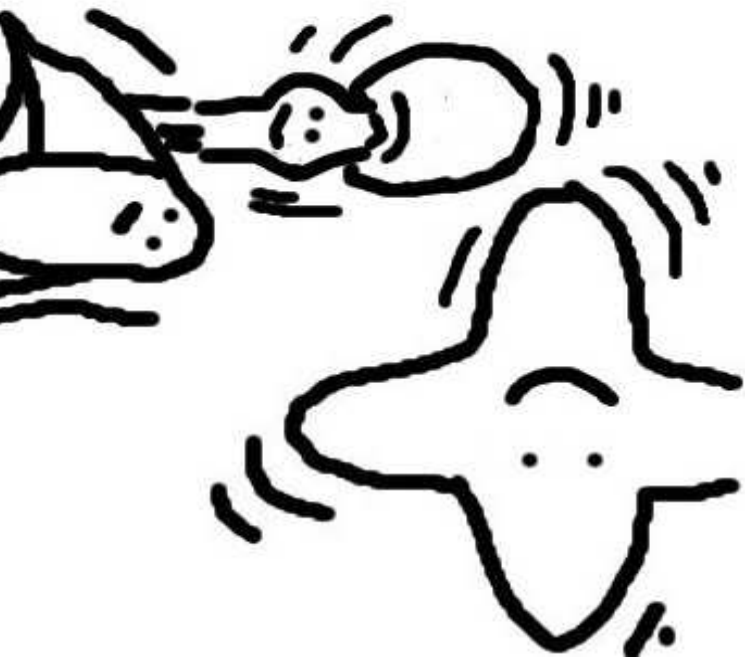
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